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Manipulation of a Bose-Einstein condensate by a time-averaged orbiting potential using phase jumps of the rotating field

P. W. Cleary, T. W. Hijmans, and J. T. M. Walraven
Van der Waals–Zeeman Institute of the University of Amsterdam, Valckenierstraat 65, 1018 XE Amsterdam, The Netherlands
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We report on the manipulation of the center-of-mass motion (“sloshing”) of a Bose-Einstein condensate in a time-averaged orbiting potential (TOP) trap. We start with a condensate at rest in the center of a static trapping potential. When suddenly replacing the static trap with a TOP trap centered about the same position, the condensate starts to slosh with an amplitude much larger than the TOP micromotion. We show, both theoretically and experimentally, that the direction of sloshing is related to the initial phase of the rotating magnetic field of the TOP. We show further that the sloshing can be quenched by applying a carefully timed and sized jump in the phase of the rotating field.

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I. INTRODUCTION

Time-averaged potentials (TAP) offer a versatile tool for trapping both charged and neutral particles. For neutral atoms the most common example in this class of traps is the time-averaged orbiting potential (TOP), which was used in the experiments in which the first Bose-Einstein condensate (BEC) was created [1,2]. The TOP trap consists of a magnetic quadrupole trap [3,4] shifted by a uniform magnetic modulation field rotating at a high (audio) frequency. As this rotation is slow as compared with the Larmor precession of the atomic magnetic moments, the atoms remain polarized with respect to the instantaneous effective magnetic field [5] as follows from the adiabatic theorem. On the other hand, the rotation is fast as compared with the orbital motion of the atoms. As a consequence, the atomic motion consists of a fast rotating part (micromotion), superimposed on a slow oscillating part (macromotion). In the simplest theoretical description, the static approximation, the micromotion is eliminated by time averaging the instantaneous potential over a full cycle of the modulation field.

Suppose we load a particle with given momentum \( p_0 \) at position \( r_0 \) in a TOP trap using a sudden switch-on procedure. One might naively guess that the ensuing motion is given by the dynamics in the TAP, subject to the initial conditions \( r = r_0 \) and \( p = p_0 \), but this guess turns out to be wrong. In fact, one can show that the initial conditions for the slow motion depend on the phase of the TOP at the time of switch-on. This phenomenon was analyzed by Ridinger and coworkers [6,7] for the special case of a one-dimensional rapidly oscillating potential (ROP) with zero average. Ridinger et al. also showed, first for a classical particle [6] and subsequently for the quantum case [7], that the amplitude and energy associated with the slow motion can be altered by applying a suitable phase jump in the rapidly oscillating field.

In this paper we show, both theoretically and experimentally, that the dependence on the initial phase and the possibility of influencing the motion by phase jumps are also present for a two-dimensional rotating TOP field. In particular we show that a cloud of atoms that is initially at rest with zero momentum acquires a sloshing motion as soon as the TOP is suddenly switched on. This is true even if the cloud is initially at the minimum of the effective potential. The amplitude of this slow macromotion is much larger than that of the fast micromotion, while the direction of sloshing depends on the TOP phase at switch-on. We also demonstrate that this macromotion can be almost entirely quenched by applying a carefully timed and sized phase jump in the TOP field.

The motion of atoms and ultracold atomic clouds in TOP traps has been extensively described in the literature. Following the achievement of the first BEC [2], the use of the axially symmetric TOP was described theoretically in Refs. [8–13] and explored experimentally by other groups [14–19] to study properties of the BEC. The idea of the TOP was extended to an asymmetric triaxial TOP trap developed by Ref. [15] and used by other groups [17,18]. A number of other variations were introduced: In many cases, it turns out to be convenient to switch on the TOP after a preparative stage of cooling in a conventional static trap such as a magnetic quadrupole trap (see, e.g., Ref. [15]), an optically plugged magnetic quadrupole [20], and Ioffe-configurations [21–23]. Often the transfer of the cloud from the static to the TOP trap cannot be performed adiabatically for topological reasons. Bearing this in mind, it becomes relevant to carefully analyze the dynamics that may be induced by a sudden switch-on of the TOP. In addition, applications that require manipulation of a BEC are heavily dependent on precise control of the location of the atomic cloud and can thus benefit from the techniques described.

In our experiments the condensate is prepared in a Ioffe-Pritchard (IP) trap before transferring to a TOP. This procedure induces the “sloshing motion.” Although our method is very specific, it is typical for any sudden change of a TOP geometry in amplitude and/or phase. In our case the transfer was chosen because the use of radio-frequency-induced evaporative cooling is more efficient in a static magnetic trap than in a TOP. Once transferred to the TOP we can create trapping geometries that are difficult to realize using a static magnetic potential without introducing Majorana losses associated with the presence of zero-field points. An example is the double-well potential used in Ref. [21].

The remainder of this paper is organized as follows. In Sec. II we calculate the motion of a cloud of atoms in a TOP that at switch-on is at rest at the center of the trap. We discuss the motion that results and derive the conditions under which
a phase jump can lead to a substantial reduction of the energy associated with the slow motion of the cloud. In Sec. III we discuss the experimental details and the preparation of the BEC and its transfer to the TOP. In Sec. IV we present the experimental results and compare them with the theory of Sec. II. Finally in Sec. V we give a summary and conclusion.

II. THEORY

A. Time-averaged Ioffe-Pritchard potential

In the literature the term TOP is most often used for a spherical-quadrupole trap combined with a rotating uniform magnetic modulation field. In this paper we will use TOP in a broader context, to include the magnetic trapping potential created by combining a IP trap with rotating modulation field. Challis et al. [13] have shown that the dynamical eigenstates of a degenerate Bose gas in a TOP are given by solutions of the usual Gross-Pitaevskii equation but taken in a circularly translating reference frame, that is, a reference frame the origin of which performs a rapid circular motion but retains a constant orientation. In particular this implies that the center of mass of a condensate in its ground state performs the same micromotion in a TOP as a point particle with the magnetic moment of an atom. In this spirit we use as a ^87 Rb condensate to study the micromotion and macromotion in a TOP.

We consider a cigar-shaped IP potential [4,24,25]

\[ U(\rho, z) = \mu \sqrt{\alpha^2 \gamma^2 + \left( B_0 + \frac{1}{2} \beta \rho^2 \right)^2}, \]

where \( \gamma(t) \) is the radial position of a test atom with respect to the IP symmetry axis, \( \mu \) the magnetic moment of the atom, and \( \alpha, \beta, \) and \( B_0 \) the parameters for the radial gradient, axial curvature, and offset value of the IP magnetic field, respectively. Equation (1) is a good approximation for the IP trap that is valid for \( \alpha^2 \gg \beta B_0 \) and in the limit \( \gamma \ll \alpha/\beta \) [4,24,25].

In the presence of the TOP field we transform to the circularly translating frame [13] and have

\[ \gamma(t) = (x - \rho_m \cos(\omega t + \phi_m)), \quad y - \rho_m \sin(\omega t + \phi_m)), \]

where \( (x, y, z) \equiv (\rho, z) \equiv \mathbf{r} \) is the position of the atom in the laboratory frame and the IP symmetry axis is displaced over a distance \( \rho_m = \frac{B_m}{\alpha} \) in the direction

\[ \mathbf{\hat{\rho}}_m = (\cos(\omega t + \phi_m)), \sin(\omega t + \phi_m)) \]

by the uniform modulation field

\[ \mathbf{B}_m = \mathbf{B}_0 \cos(\omega t + \phi_m), -\sin(\omega t + \phi_m)) \]

applied perpendicular to the \( z \) axis. The \( y \) axis is taken along the vertical direction, the \( xz \) plane being horizontal. The modulation field \( \mathbf{B}_m \) rotates at angular frequency \(-\omega\) (phase \(-\phi_m)) around the horizontal \( z \) axis as illustrated in Fig. 1. Notice that the sense of rotation of the IP-field minimum is opposite to that of the \( \mathbf{B}_m \) field, in contrast with the original TOP configuration [1], where the field zero rotates in the same direction as the bias field. This reflects the difference between the 2D-quadrupole symmetry of the IP trap and the axial symmetry of the spherical-quadrupole trap. The rotation of the modulation field \( \mathbf{B}_m \) also gives rise to a fictitious field \( \mathbf{B}_0 \), that has to be added or subtracted from the offset field \( \mathbf{B}_0 \), depending on the sense of rotation,

\[ \mathbf{B}_0 \rightarrow \mathbf{B}_0(1 \pm \mathbf{B}_0/\mathbf{B}_0) = \mathbf{B}_0(1 \pm \omega/\omega_L), \]

where \( \omega_L = g_F \mu_B B_0/\hbar \) is the Larmor frequency of magnetic moment of the atoms, with \( g_F \) the hyperfine factor and \( \mu_B \) the Bohr magneton. In a standard TOP, the fictitious field in combination with a gradient of the quadrupole field gives rise to a shift of the equilibrium position of the cloud in the direction of the axis around which the field rotates [5,17]. In our IP TOP the axial field is homogeneous near the origin and the shift is absent; the change in \( \mathbf{B}_0 \) turns out to be small and will be neglected in this paper.

For \( \beta = 0 \) and \( B_0 = 0 \) the potential \( U(\rho, z) \) corresponds to that of a two-dimensional quadrupole field with a zero-field line that rotates at distance \( \rho_m \) around the \( z \) axis as a result of the modulation. For \( B_0 = 0 \) the distance \( \rho_m \) is known as the radius of the “circle of death.” For \( \Delta z = 2(2|B_0|/\beta)^{1/2} \) [21]. In this paper we will consider only the case \( B_0 > 0 \).

In the common description of the TOP one analyzes the motion in an effective potential, obtained by time averaging the static trap over a full rotation period of the \( \mathbf{B}_m \) field. For Eq. (1) this procedure yields the effective potential

\[ U(\mathbf{r}) = \frac{1}{2\pi} \int_0^{2\pi} U(x - \rho_m \cos \zeta, y - \rho_m \sin \zeta, z) \, d\zeta, \]

where \( \zeta = \omega t + \phi_m \). For the cigar-shaped IP potential we consider the condition

\[ \omega \gg \Omega_\rho \gg \Omega_z. \]
where, for an atom of mass \( m \), the quantity \( \Omega_0 = (\mu / m)^{1/2} \) is the axial harmonic oscillation frequency in the effective potential \( \mathcal{U}(0,0,z) \). Analogously, harmonic oscillation frequency in the radial plane is given by

\[
\Omega_r = \sqrt{\frac{\mu \alpha^2}{m B_0} \left( 1 - \frac{1}{2} \frac{B_m^2}{B_0^2} \right)} \equiv \Omega,
\]

where \( B_0 = (B_0^2 + B_m^2)^{1/2} \) is offset value of the effective potential at the origin [21].

The first inequality in Eq. (7) ensures that the fast and slow radial motions of the atoms can be separated, which is the well-known operating regime for a TOP trap [1]. The second inequality implies that the axial motion in the effective trap is slowest and that the motion can be treated as quasi two-dimensional in the radial plane.

To account for the acceleration due to gravity \( (g) \), the gravitational potential \( mg \) has to be added to Eqs. (1) and (6). The main effect is to shift the minimum of the potentials in the negative \( y \) direction by the amount

\[
\Delta y = g / \Omega^2.
\]

This expression holds as long as the gravitational sag \( \Delta y \) is much smaller than the harmonic radius \( \rho_0 \equiv B_0 / \alpha \).

Since \( \rho_0 \gg \rho_m \), the effective potential (6) may be treated as harmonic as long as the motion is confined to a region around the \( z \) axis that is small compared with \( \rho_m \). For our experiment the harmonic approximation holds rather well and is sufficient for gaining qualitative insight into the micro- and macromotion, as will be shown in Sec. II B. Refinements associated with switch-on transients and gravity are discussed and macromotion, as will be shown in Sec. II B.

B. Micromotion and macromotion

To analyze the effect of switching on the \( B_m \) field at \( t = 0 \) we first consider an atom "at rest" in the center of the effective trapping potential \( \mathcal{U}(\rho,z) \). Such an atom exhibits no period-averaged dynamics (no macromotion) but only circular micromotion at a frequency \( \omega \) about the origin as illustrated in Fig. 1. The radius of this stationary micromotion,

\[
\rho_0 = \frac{\mu \alpha}{m \omega^2} (1 + B_0^2 / B_m^2)^{-1/2},
\]

follows from the condition \( F_c = m \omega^2 \rho_0 \) for the centripetal force \( F_c = -\nabla \mathcal{U} \big|_{\rho=0} = \mu \alpha (1 + B_0^2 / B_m^2)^{-1/2} \rho_0 \). The speed of this stationary micromotion,

\[
v_0 = \omega \rho_0 = \frac{\mu \alpha}{m \omega} (1 + B_0^2 / B_m^2)^{-1/2},
\]

directed orthogonally to the direction \( \hat{\rho}_m \). Such pure micromotion results only if at \( t = 0 \) the atom is already moving at speed \( v_0 \) along a circle of radius \( \rho_0 \) around the origin and is located at position \( \rho = -\rho_0 \hat{\rho}_m \) (see Fig. 1). Obviously an atom at \( t = 0 \) at rest at the origin \( \rho = (0,0) \) does not satisfy these initial conditions, and as a consequence its macromotion will start with a finite launch speed. We will see that the result is elliptical motion at frequency \( \Omega \), with the long axis approximately perpendicular to the initial direction of \( \hat{\rho}_m \) and with a substantial amplitude of order \( \omega / \Omega \). Usually this motion is undesired, and our aim is to quantify it and subsequently quench it by imparting a phase jump to the TOP field.

It is worth mentioning that in the conditions relevant for the experiments described in this paper the amplitude and energy of the macromotion are not negligible compared with other relevant length and energy scales. The characteristic size of the condensate is given by the Thomas-Fermi radius, which turns out to be slightly smaller than the macromotion amplitude. Likewise, the energy associated with the macromotion is at least as large as the chemical potential.

To gain insight into the way in which the sudden switch-on of the TOP influences the macromotion of an atom initially at rest at the origin, we first consider a simple model in which it is assumed that the motion in the radial plane can be decomposed into two harmonic components, oscillating at the micromotion and macromotion frequencies \( \omega \) and \( \Omega \), respectively. The position \( \rho(t) \) and velocity \( \dot{\rho}(t) \) are given by

\[
\rho(t) = \left\{ \begin{array}{ll}
\rho_0 \cos(\omega t + \phi), & \rho_0 \sin(\omega t + \phi) \\
+ \{X_0 \cos(\Omega t + \varphi_x), Y_0 \sin(\Omega t + \varphi_y)\},
\end{array} \right.
\]

\[
\dot{\rho}(t) = \left\{ \begin{array}{ll}
-v_0 \sin(\omega t + \phi), & v_0 \cos(\omega t + \phi) \\
+ \{-V_{0,x} \sin(\Omega t + \varphi_x), V_{0,y} \cos(\Omega t + \varphi_y)\},
\end{array} \right.
\]

where \( X_0 \) (\( Y_0 \)) is the amplitude, \( V_{0,x} = \Omega X_0 \) (\( V_{0,y} = \Omega Y_0 \)) the velocity amplitude, and \( \varphi_x \) (\( \varphi_y \)) the initial phase of the macromotion in the \( x \) (\( y \)) direction; \( \phi \) is the initial phase of the micromotion. The atom starts at rest at the origin; hence the initial conditions are \( \rho, \dot{\rho} = 0 \) at \( t = 0 \). If the condition

\[
\omega \gg \Omega
\]

is satisfied, the acceleration due to the micromotion dominates over that of the macromotion. The total acceleration may be approximated by \( \ddot{\rho} \simeq F_c / m \). In other words, \( \ddot{\rho} \) points in the direction \( \hat{\rho}_m \), which is opposite to the direction of \( \rho \) (see Fig. 1). Hence, the initial phase of the micromotion is \( \phi \approx \phi_m + \pi \), where \( \phi_m \) is fixed by the phase of the rotating \( B_m \) field [26]. Without loss of generality we can set \( \phi_m = 0 \), which means that \( \rho_0 \) is oriented along the positive \( x \) direction at \( t = 0 \). With this choice and setting \( \phi = \phi_m + \pi \), we find from the initial conditions \( \varphi_x, \varphi_y = 0 \), \( X_0 = \rho_0 \), and \( Y_0 = (\omega / \Omega) \rho_0 \). Substituting these values in Eq. (12) we obtain an equation for the macromotion representing an elliptical orbit with its major axis oriented perpendicular to the instantaneous direction \( \hat{\rho}_m \) of the \( B_m \) field at \( t = 0 \). Since the amplitude of the macromotion along its major axis is larger than the macromotion by the factor \( \omega / \Omega \), a substantial sloshing motion results from the sudden switch-on. Note that with increasing \( \omega \), the micromotion amplitude \( \rho_0 \) decreases like \( 1 / \omega^2 \), whereas the amplitude of the sloshing motion \( Y_0 \) decreases only like \( 1 / \omega \). For this reason the sloshing cannot be neglected in most practical cases involving audio-frequency modulation.

C. Numerical analysis

To validate the analytical model introduced in Sec. II B, we numerically integrate the classical equations of motion in the
The initial gravitational sag in the IP trap is 1.2 µm. When switching on the TOP, the sag Δy jumps in ~3 µs to 1.7 µm and settles in ~0.5 ms to its final value 1.6 µm due to the decrease of B₀. Thus the gravitational sag increases jumpwise and settles at δy = 0.4 µm. During the same transient the radius of the stationary micromotion grows from ρ₀ = 0.21 µm to ρ₀ = 0.33 µm, and δ increases by about 5%.

The dotted red traces in Fig. 2 correspond to the numerical calculation, including all the already mentioned refinements relevant to the experiments. We have also investigated the effects of gravity, Bₘ switching, and B₀ switching separately. We find that the main effect of the settling time of B₀ is to reduce the amplitude along the major axis by ~35%. The combined effect of changing gravitational sag and Bₘ transient is to slightly increase the x amplitude as well as to produce a slight tilt angle of the trajectory (see rightmost panel of Fig. 2).

The tilt angle θ of the macromotion also follows from a fit of Eq. (12) to the numerical results. For known values of X₀, Y₀, φₓ, and φᵧ, the angle of rotation θ to align the coordinate system along the major and minor axis is given by

$$\theta = \frac{1}{2} \tan^{-1} \left[ 2 \sin(\phi_x - \phi_y) X_0 Y_0 \left( \frac{Y_0^2}{Y_0^2 - X_0^2} \right) \right].$$  

For φₘ₀ = 0 the tilt angle equals the rotation angle (θ = 0).

The results of a fit of Eq. (12) to the numerical results including only the refinements (a) and (b), as well as a fit including all three refinements (a), (b), and (c) are also given in Table I. Extending the analytical model to include the refinements (a) and (b) is straightforward and given in detail in the Appendix. The expressions for the amplitudes and phases depend on the model parameter τ₀ and are given by Eqs. (A6)–(A9) in the Appendix. The model parameter τ₀ is chosen by ensuring that the value of the tilt angle θ of the model reproduces that of a fit to the numerical solution for zero settling time, θ = 0.024π. This results in τ₀ = 3.5 ms. Excellent agreement is obtained with the numerical model as is shown in Table I. Insight in the cause of the reduction of the major-axis amplitude associated with the settling behavior of B₀ can also be gained using the analytical model. As discussed in the Appendix the major refinement is to change the launch speed corresponding to the initially smaller value of ρ₀. Although this refinement captures the origin of the 35% reduction of the major-axis amplitude, Table I shows that the overall agreement with the numerical model is less favorable.

### D. Phase jumps

Let us now analyze how the macromotion can be quenched. For a one-dimensional ROP it was demonstrated in Ref. [6] that the amplitude of the macromotion can be quenched by an appropriate phase jump of the modulation field. For the 2D motion in a TOP, the success of such an approach is not a priori obvious because the phase jumps for the x and y motion cannot be selected independently. Yet, as will be shown, for the TOP as well it is possible to quench both the X₀ and Y₀ amplitudes more or less completely by imposing a single phase jump Δφₘ₀ to the Bₘ field.

For clarity we first restrict ourselves to the case φₘ₀ = 0 and neglect the effects of gravity and switching transients. This means that the cloud is launched at t = 0 in the vertical y direction with a speed that is equal to v₀, the micromotion
phase jump is achieved when the jump is applied at a time \( t_a \) when \( \dot{\rho}_m(t_a) \) has a magnitude equal to \( v_0 \). The value of \( \Delta \phi_m \) is again selected such as to set \( \dot{\rho}_m \) perpendicular to \( \dot{\rho}(t_a) \). By reasoning similar to the case already described, we find that the condition of an equilateral triangle of the three velocity vectors is now replaced by one that is an isosceles-triangle condition with the micromotion velocity and \( \dot{\rho}(t_a) \) both having a magnitude \( v_0 \). This in turn means that the magnitude of the phase jump will deviate slightly from the values \( \pm \pi/3 \) already found. Also, the nearest distance to the \( x \) axis at which the isosceles-triangle condition can be met is in general not equal to zero. This means that some residual macromotion will be present after the phase jump, with an amplitude given by the distance to the origin of the center of the circular orbit into which the cloud is transferred by the phase jump. One can show that there is always a choice possible where the isosceles-triangle condition is satisfied such that this distance is approximately \( 2v_0 \) or less. As a consequence, even in the worst case, the macromotion amplitude is reduced from \( (\omega/\Omega) v_0 \) to an amplitude of order \( v_0 \).

The criterion that the acceleration be set perpendicular to the total velocity at the time that the macromotion speed is equal to \( v_0 \) can be expressed by the following equation:

\[
\Delta \phi_m = \arctan \left( \frac{\dot{\rho}_y(t_a)}{\dot{\rho}_x(t_a)} \right) - \phi(t_a) + (-1)^k \frac{\pi}{2},
\]

where \( \dot{\rho}_x(t_a) = -v_0 \sin(\phi(t_a)) - V_{0y} \sin(\Omega t_a + \psi_y) \) and \( \dot{\rho}_y(t_a) = v_0 \cos(\phi(t_a)) + V_{0y} \cos(\Omega t_a + \psi_y) \) are \( x \) and \( y \) components of \( \dot{\rho} \) at time \( t_a \) and \( k = 1 \) for \( \dot{\rho}_x(t_a) > 0 \) and \( k = 0 \) for \( \dot{\rho}_x(t_a) < 0 \). We return to selection of the jump time and the use of Eq. (16) when discussing the measurement procedure in Sec. III B.

Examples of the numerical calculations of the quenching procedure are shown in Fig. 4. The near complete quenching of the macromotion shown in Fig. 4(a) is obtained for \( \delta_1 = 0 \) and \( \tau = 0 \) with phase jump \( \Delta \phi_m = -\pi/3 \) at time \( t_a = 3.834 \text{ ms} \) in the time interval around \( t_1 = 3\Delta t/\Omega \). In Fig. 4(b) the refinements (a), (b), and (c) are included in the simulation of the experiment. In this case the phase jump had to be adjusted to \( \Delta \phi_m = -0.22\pi \) for maximum quenching. Note that the quenching is less complete. By adjusting, at constant \( \Omega \), the micromotion frequency to \( \omega = 4.068 \text{ kHz} \) and the jump time to \( t_a = 3.769 \text{ ms} \), complete quenching similar to that shown in Fig. 4(a) was also obtained when including all refinements in the numerical model.

III. EXPERIMENTAL

A. Apparatus

The experiments are done with the apparatus described in detail in Refs. [27] and [28]. We produce a BEC of \( 2.5 \times 10^{12} \) atoms of \( ^{87}\text{Rb} \) in the \( |F = 2, m_F = 2 \rangle \) state in an IP trap using radio-frequency evaporative cooling. The symmetry axis \( (z \text{ axis}) \) of the trap lies horizontal with trap frequencies \( (\Omega_x/2\pi = 455(5) \text{ Hz} \), \( \Omega_y/2\pi = 21 \text{ Hz} \)) and the magnetic-field offset \( B_0 = 9.5(3) \times 10^{-5} \text{ T} \), \( \alpha = 3.53 \text{ T/m} \), and \( \beta = 266 \text{ T/m}^2 \). The Thomas-Fermi radius of the BEC is 2.2 \( \mu \text{m} \). The TOP field is produced by two pairs of coils, one in the \( x \) direction, the other in the \( y \) direction, as described.
The current used is (TGH 1244), amplified by a standard audio amplifier (Yamaha) generated by a TTI 4 channel arbitrary waveform generator to keep the inductance low. The current for the TOP is with an equilibrium BEC in the IP trap already described. The coils consist of only two windings (three macromotion half periods). 

\[ \frac{\Delta \phi_m}{\Omega_1} \]

Gravity:

\[ \frac{1}{\delta t} \]

The micromotion is recognized as the rapid modulation on the position of the condensate in the trap we image the cloud at \( t = t_0 \). A cloud released at rest at time \( t_0 \) is imaged at position \( R_0 = \rho(t_{rel}) + \frac{1}{2} \hat{\rho}_g \Delta t_{TOF}^2 \), where \( \hat{\rho}_g \) is the gravitational acceleration. For a finite release velocity \( \rho(t_{rel}) \) the cloud will be imaged at \( R = \rho(t_{rel}) \Delta t_{TOF} + R_0 \).

In practice we may neglect the small variation in the release position due to the macromotion, approximating \( \rho(t_{rel}) \approx \rho(0) \), because this variation is smaller than the shot-to-shot reproducibility of the cloud position. From the model analysis of Sec. II B the variation in release position due to the macromotion is estimated to be \( \delta \rho(t_{rel}) \lesssim (\omega/\Omega) \rho_0 \approx 4 \mu m \).

The centroid of the image of the expanded cloud is determined using a simple Gaussian fitting procedure and has a shot-to-shot reproducibility of \( \sim 8 \mu m \), small as compared with the 140 \( \mu m \) radius of the expanded cloud. No improvement in shot-to-shot reproducibility was found by changing to a higher magnification. Since our measurements depend only on the position of the cloud center, they are insensitive to fluctuations in atom number or density. To reconstruct the motion of the condensate in the trap we image the cloud at \( t = t_i \), where \( t_i \) is the holding time in the TOP. We obtain the release velocity by measuring the \( x \) and \( y \) components of the cloud centroid \( (R_x, R_y) \). A typical set of data is shown in Fig. 5.

The micromotion is recognized as the rapid modulation on the slow macromotion. As the frequency of the micromotion is accurately known, we avoid aliasing by sampling the motion in steps of 0.025 ms, much shorter than the micromotion period. If we wish to look only at the macromotion in a stroboscopic manner, we can sample precisely at the micromotion period of 0.25 ms, with the best results obtained when sampling on the

FIG. 4. (Color online) Numerically calculated radial trajectories in the \( x \) and \( y \) directions for the same trap parameters as used for Fig. 2, with a quenching phase jump \( \Delta \phi_m \) applied at optimized \( t = t_x \approx t_e \) (three macromotion half periods). (a) Instant switching, no gravity: \( \Delta \phi_m = -\pi/3, t_x = 3.834 \text{ ms} \); (b) including switching transients and gravity: \( \Delta \phi_m = -0.22 \pi, t_x = 3.834 \text{ ms} \).

FIG. 5. (Color online) The centroid position after 23 ms TOF plotted in camera pixel units against holding time in the TOP trap. Upper dataset: \( R_x \); lower dataset: \( R_y \). The solid lines represent the fit of Eqs. (17) and (18) to the data. Note that by a stroboscopic measurement at 0.25 ms intervals the micromotion is eliminated. Each point represents a single measurement.

B. Measurement procedure

Our experiments on phase-jump-controlled motion in a TOP trap are done with the \( B_m \) field operated at \( \omega/2\pi = 4 \text{ kHz} \). This frequency is sufficiently high \( (\omega/\Omega \gtrsim 10) \) to satisfy the “TOP condition” [Eq. (14)]. The frequency is chosen lower than in a typical TOP to ensure that the speed of the stationary micromotion, 9 mm/s as estimated with Eq. (11), is accurately measurable. In the experiments we start with an equilibrium BEC in the IP trap already described. At \( t = 0 \) we switch on the \( B_m \) field, using \( B_0 \) to tune the measured trap frequency to \( \Omega/2\pi = 394 \text{ Hz} \). As the trap minimum shifts down by \( \delta y = 0.40 \mu m \), the initial position of the cloud is slightly above the trap center. The 1/e-switching time of the \( B_m \) field was measured to be \( \tau \approx 3 \text{ ms} \), which corresponds to \( \omega \tau \approx 0.08 \). When changed, the \( B_0 \) field settles to a new value after a damped oscillation with a frequency of 650 Hz and a damping time \( \tau' \approx 0.56 \text{ ms} \). This corresponds to \( \Omega/\tau' \approx 0.2 \). The cloud is imaged at position \( R_0 = \hat{\rho}(t_{rel}) + \frac{1}{2} \hat{\rho}_g \Delta t_{TOF}^2 \), where \( R_0 \) is the gravitational acceleration. For a finite release velocity \( \hat{\rho}(t_{rel}) \) the cloud will be imaged at \( R = \hat{\rho}(t_{rel}) \Delta t_{TOF} + R_0 \).

In practice we may neglect the small variation in the release position due to the macromotion, approximating \( \rho(t_{rel}) \approx \rho(0) \), because this variation is smaller than the shot-to-shot reproducibility of the cloud position. From the model analysis of Sec. II B the variation in release position due to the macromotion is estimated to be \( \delta \rho(t_{rel}) \lesssim (\omega/\Omega) \rho_0 \approx 4 \mu m \).

The centroid of the image of the expanded cloud is determined using a simple Gaussian fitting procedure and has a shot-to-shot reproducibility of \( \sim 8 \mu m \), small as compared with the 140 \( \mu m \) radius of the expanded cloud. No improvement in shot-to-shot reproducibility was found by changing to a higher magnification. Since our measurements depend only on the position of the cloud center, they are insensitive to fluctuations in atom number or density. To reconstruct the motion of the condensate in the trap we image the cloud at \( t = t_i \), where \( t_i \) is the holding time in the TOP. We obtain the release velocity by measuring the \( x \) and \( y \) components of the cloud centroid \( (R_x, R_y) \). A typical set of data is shown in Fig. 5.

The micromotion is recognized as the rapid modulation on the slow macromotion. As the frequency of the micromotion is accurately known, we avoid aliasing by sampling the motion in steps of 0.025 ms, much shorter than the micromotion period. If we wish to look only at the macromotion in a stroboscopic manner, we can sample precisely at the micromotion period of 0.25 ms, with the best results obtained when sampling on the

FIG. 4. (Color online) Numerically calculated radial trajectories in the \( x \) and \( y \) directions for the same trap parameters as used for Fig. 2, with a quenching phase jump \( \Delta \phi_m \) applied at optimized \( t = t_x \approx t_e \) (three macromotion half periods). (a) Instant switching, no gravity: \( \Delta \phi_m = -\pi/3, t_x = 3.834 \text{ ms} \); (b) including switching transients and gravity: \( \Delta \phi_m = -0.22 \pi, t_x = 3.834 \text{ ms} \).

FIG. 5. (Color online) The centroid position after 23 ms TOF plotted in camera pixel units against holding time in the TOP trap. Upper dataset: \( R_x \); lower dataset: \( R_y \). The solid lines represent the fit of Eqs. (17) and (18) to the data. Note that by a stroboscopic measurement at 0.25 ms intervals the micromotion is eliminated. Each point represents a single measurement.
crests of the micromotion. Fitting the expressions

\[ R_x = -v_0 \Delta_{\text{TOF}} \sin(\omega t + \phi) - V_{0,x} \Delta_{\text{TOF}} \sin(\Omega t + \varphi_x) + R_{0,x}, \]  
\[ R_y = v_0 \Delta_{\text{TOF}} \cos(\omega t + \phi) + V_{0,y} \Delta_{\text{TOF}} \cos(\Omega t + \varphi_y) + R_{0,y}, \]  

(17)
(18)
to the data and using the TOP frequency \( \omega \) and \( \Delta_{\text{TOF}} \) as known parameters, we obtain the amplitudes \( v_0, V_{0,x}, V_{0,y} \) as well as the macromotion frequency \( \Omega \) and the phases \( \phi, \varphi_x, \varphi_y \). Note that the fit also yields the reference position \( R_0 = \{R_{0,x}, R_{0,y}\} \), but this information is superfluous for the reconstruction of the intrapulse motion. Once these quantities are determined, the motion of the condensate in the TOP trap is readily reconstructed with Eq. (12).

To investigate the effect of phase jumps, we implement the approach described in Sec. II D. First we determine for given \( \omega \) and \( \Delta_{\text{TOF}} \) all parameters to reconstruct the motion with the method just described. This enables us to determine the time intervals \( t_n - \Delta t < t < t_n + \Delta t \), where the cloud returns close to the origin, and choose within this interval the time \( t_n \), where the total velocity \( \dot{\rho}(t_n) \) has magnitude \( v_0 \) as shown in Fig. 6(a). The red dashed lines correspond to the analytical model of Sec. II D for the case of instant switching: no gravity [the case of Fig. 4(a)]. The black solid lines correspond to the calculation including all relevant experimental constraints.

The phase jump \( \Delta \phi_m \), that sets \( \hat{\rho}_m \) perpendicular to \( \dot{\rho}(t_n) \) is given by Eq. (16). This optimal phase jump \( \Delta \phi_m \) is plotted versus \( t_n \) in a time interval around \( t_3 = 3\Delta t / 2 \) in Fig. 6(b). For the case of instant switching, no gravity, the optimum phase jump is seen to be \( \Delta \phi_m = -\pi / 3 \). At the chosen time \( t_n \) we vary the phase jump \( \Delta \phi_m \) around the value suggested by Eq. (16) in search for optimal quenching. To reconstruct the residual macromotion, we hold the cloud for a variable additional time \( t_b \), before TOF imaging at time \( t = t_a + t_b \).

IV. RESULTS AND DISCUSSION

In this section we show the results obtained with the experimental procedure described in Sec. III. We measured the macromotion induced by switching on the \( B_m \) field for three values of the initial TOP phase, \( \phi_m = 0, \pi/4, \pi/2 \). For \( \phi_m = 0 \) part of the raw data are shown in Fig. 5. In Fig. 7 we show the measured velocity of the macromotion obtained with the stroboscopic method. The upper and lower panels correspond to \( \phi_m = 0 \) and \( \pi/4 \), respectively. The data for \( \phi_m = \pi/2 \) are not shown but are similar to those for \( \phi = 0 \) and with the roles of \( x \) and \( y \) interchanged.

The solid lines in the left panels of Fig. 7 are obtained by fitting Eqs. (17) and (18) to the full data including micromotion and provide the input for calculating the amplitudes. Using the known TOP frequency \( \omega/2\pi = 4 \) kHz and flight time \( \Delta_{\text{TOF}} = 23 \) ms, the fit yields for the velocity amplitudes, phases, and frequency \( v_0 = 7.6(2) \) mm/s, \( V_0,x = 0.7(2) \) mm/s, \( V_0,y = 5.6(2) \) mm/s, \( \phi = 1.00(1)\pi \), \( \varphi_x = 0.5(2)\pi \), \( \varphi_y = 0.05(2)\pi \), and \( \Omega/2\pi = 394(4) \) Hz. The corresponding in-trap amplitudes are \( \rho_0 \equiv v_0/\omega = 0.30(1) \) \( \mu \)m, \( X_0 \equiv V_0,x / \Omega = 0.28(7) \) \( \mu \)m, and \( Y_0 \equiv V_0,y / \Omega = 2.3(1) \) \( \mu \)m.

The right panels in Fig. 7 are parametric plots of the trajectories obtained by reconstructing the motion in the trap from the velocity fits already described. The trajectories provide a useful way to see the effect of the initial phase of the applied \( B_m \) field, and in addition the upper panel can be directly compared with the theoretical prediction shown in Fig. 2. As expected, the orientation of the major axis of the macromotion is dependent on the initial phase \( \phi_m \) of the \( B_m \) field. The small tilt \( \theta \) away from the direction perpendicular to \( \hat{\rho}_m \) is clearly visible and consistent with the calculations for a finite switch-on time and the presence of gravity. The value

FIG. 6. (Color online) Illustration of how to choose the optimal phase jump and its timing. Both panels: solid black curve: experimental conditions; dashed red curve: analytical model of Sec. II D for the case of instant switching: no gravity. (a) Total speed of the cloud in units of the micromotion speed \( v_0 \) [optimal phase jump time \( t_n \) corresponds to \( \dot{\rho}(t_n) = v_0 \); the dashed blue line (scale on right) shows the \( y \) component of the macromotion position crossing zero at \( t = t_3 \) (stationary micromotion can be achieved by adjusting \( \omega \) such that \( t_3 = t_n \)]. (b) Optimal phase jump as a function of jump time as calculated by Eq. (16).

FIG. 7. (Color online) Left panels show the macromotion velocities (taken with the stroboscopic method) of the cloud centroid \( x \) (black) and \( y \) (red) versus time for \( \phi_m = 0 \) and \( \pi/4 \). Solid curves are fits of Eqs. (17) and (18) to the data. Right panels represent the reconstructed trajectories in parametric form (in units of the TOP radius \( \rho_m = 19.5 \mu \)m). The difference in aspect ratio is caused by the gravity shift.
TABLE II. Experimental results (expt.) for macromotion induced by the switch-on of the TOP field for $\phi_m = 0, \pi/4$. The data are compared with the results of the numerical calculation of Sec. II C (num). In all cases the tilt angle has been calculated with the aid of Eq. (15).

<table>
<thead>
<tr>
<th>$\phi_m$</th>
<th>$\theta/\pi$</th>
<th>$\varphi_x/\pi$</th>
<th>$\varphi_y/\pi$</th>
<th>$X_0/\rho_0$</th>
<th>$Y_0/\rho_0$</th>
</tr>
</thead>
<tbody>
<tr>
<td>expt.</td>
<td>0</td>
<td>0.04(2)</td>
<td>0.5(2)</td>
<td>0.05(2)</td>
<td>0.9(2)</td>
</tr>
<tr>
<td>num 0</td>
<td>0</td>
<td>0.016</td>
<td>0.20</td>
<td>0.06</td>
<td>0.82</td>
</tr>
<tr>
<td>expt. $\pi/4$</td>
<td>0.04(2)</td>
<td>0.49(2)</td>
<td>0.12(2)</td>
<td>6.6(4)</td>
<td>5.2(3)</td>
</tr>
<tr>
<td>num $\pi/4$</td>
<td>0.013</td>
<td>0.47</td>
<td>0.04</td>
<td>4.95</td>
<td>4.55</td>
</tr>
</tbody>
</table>

obtained for $\rho_0$ is slightly smaller than the value calculated with Eq. (10), but in view of experimental uncertainties certainly consistent with the value of $\alpha$. The results for $\varphi_x/\pi, \varphi_y/\pi, X_0/\rho_0, Y_0/\rho_0$, and the tilt angle $\theta$ obtained for $\phi_m = 0$ and $\pi/4$ are given in Table II. For comparison, the numerical results are also included.

We now turn to the results of a quenching experiment. The time $t_a \approx 3.83$ ms and magnitude $\Delta \phi_m = -0.22\pi$ of the phase jump have been chosen to meet the conditions necessary to quench the macromotion as introduced in Sec. III B and illustrated in Fig. 6. In Fig. 8 we show velocity data taken with the stroboscopic method. For $t < 3.83$ ms the data coincide with those shown in the upper panel of Fig. 7, but the solid lines are not a fit, representing the macromotion velocity predicted by the numerical calculation on the basis of the experimental parameters. These velocity curves correspond to the macromotion part of the position plot [Fig. 4(b)] and have no adjustable parameters. Both experiment and theory show pronounced reduction in the amplitude of the macromotion. Although the phases of the quenched motion cannot be determined convincingly with our signal-to-noise ratio, the agreement between theory and experiment is satisfactory.

In general a jump in the micromotion phase produces an abrupt change in macromotion phase and amplitude. For the case illustrated in Fig. 8 we obtain a reduction of more than a factor of 5 in the amplitude of oscillation in the $y$ direction at the expense of only a slight increase of the amplitude in the $x$ direction. As a result the macromotion is reduced to the size of the micromotion. The energy associated with the macromotion is consequently reduced by a factor of about 15, reducing it to a small fraction of the micromotion energy. This demonstrates that the initial sloshing motion of the cloud can be efficiently quenched by applying an appropriate phase-jump angle. As pointed out at the end of Sec. II D, we expect that it should be possible to suppress the macromotion almost completely by adjusting the micromotion frequency such that $t_1 = t_a$.

Even a small variation in the phase-jump magnitude or its timing can result in a substantial difference in quenching efficiency. This is illustrated in Fig. 9, where we plot the ratio of macro- to micromotion energy,

$$\frac{E_{\text{macro}}}{E_{\text{micro}}} = \frac{V_{0,x}^2 + V_{0,y}^2}{v_0^2},$$

(19)

as the phase jump is varied in steps of 10 degrees, for $t_a = 1.32$ and 1.33 ms, where the position and velocity criteria are well satisfied. For most phase jumps $\Delta \phi_m$, the result is an increase in energy. The drawn lines are the predictions from the numerical model for the same conditions at $t_a = 1.31$ and 1.32 ms. The data are consistent with the numerical model at these times.

V. SUMMARY AND CONCLUSION

We have shown that a cold atomic cloud initially at rest at the minimum of the effective potential of a TOP trap acquires a macroscopic sloshing motion, in addition to near-circular micromotion, when the TOP is suddenly switched on. The energy associated with this macromotion is of the same order as the energy of the micromotion, and the amplitude of the former is larger than that of the latter by a factor $\sim \omega / \Omega$. The micromotion is consequently reduced by a factor of about 15, reducing it to a small fraction of the micromotion energy. This demonstrates that the initial sloshing motion of the cloud can be efficiently quenched by applying an appropriate phase-jump angle. As pointed out at the end of Sec. II D, we expect that it should be possible to suppress the macromotion almost completely by adjusting the micromotion frequency such that $t_1 = t_a$.

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(19)

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As the micromotion is shared in common mode by all trapped atoms, the associated energy does not affect the thermodynamics of the cloud in any way. In contrast, the macromotion energy is generally unwanted and potentially harmful. Fortunately, as we have shown, it is possible to quench this macromotion almost completely and instantly by applying a suitable and properly timed phase jump to the rotating magnetic field that defines the TOP. We have shown theoretically that this procedure works, even for the 2D case of the TOP, which is an extension of previous theory describing similar phenomena in 1D [6,7]. We have presented a framework that allows a deterministic procedure for choosing the optimal parameters for the phase jump. Our experiments corroborate the theoretical model for the TOP in a quantitative manner.

The macromotion induced by the switch-on and the subsequent possibility of altering this motion by phase jumps have several consequences, some of which we now briefly mention. For example, the sloshing motion may affect the time of flight imaging once the fields have been switched off. When comparing TOF images for different holding times it is in general not sufficient to synchronize the release time to the micromotion period. The position after TOF can be easily polluted by the nonzero macromotion, which evolves asynchronously with the micromotion. The time scales in this experiment are on the order of a few macromotion periods. The physics of interest of the cloud is usually seen on much longer time scales of hundreds of such periods. On these longer time scales, the presence of even small anharmonicities can lead to the conversion of macromotion energy into heat. The macromotion can be of an order of the chemical potential, which can have consequences for the stability of the condensate.

The possibility to excite or quench macromotion by phase jumps of the rotating field is a valuable feature of the TOP. This shows that the switch-on profile mainly affects the acceleration in the ‘primed’ coordinate system.

\[
x'(t) = -\rho_0 \cos \omega t + X'_0 \cos (\Omega t + \phi'_x),
\]

\[
y'(t) = -\rho_0 \sin \omega t + Y'_0 \sin (\Omega t + \phi'_y),
\]

where \(X'_0, Y'_0\) are the amplitudes and \(\phi'_x, \phi'_y\) the phases with respect to the rotated axes. Taking the time derivative and using the initial conditions \(\phi'_0, \phi'_0 = 0\), \(X'_0 = \rho_0, Y'_0 = (\omega/\Omega)\rho_0\). This corresponds to an ellipse with its major axis oriented perpendicular to the instantaneous direction \(\vec{b}_m = \hat{b}_m\) of the \(B_m\) field at \(t = 0\).

For exponential switch-on of the \(B_m\) field with \(1/e\) time \(\tau\), we have for the acceleration in the ‘primed’ coordinate system

\[
x'(t) = \omega^2 [1 - \exp(-t/\tau)] \rho_0 \cos \omega t - \Omega^2 X'_0 \cos (\Omega t + \phi'_x),
\]

\[
y'(t) = \omega^2 [1 - \exp(-t/\tau)] \rho_0 \sin \omega t - \Omega^2 Y'_0 \sin (\Omega t + \phi'_y),
\]

where, during switch-on, \(X'_0, Y'_0, \phi'_x, \phi'_y\), and \(\Omega\) are functions of time. Since \(\Omega \ll \omega\), we may approximate, for \(\omega t \ll 1\),

\[
x'(t) \simeq \omega^2 [1 - \exp(-t/\tau)] \rho_0 \cos \omega t \gg y'(t).
\]

This shows that the switch-on profile mainly affects the acceleration in the \(x'\) direction because this is the initial direction of acceleration. By the time \(\omega t \ll 1\) is sufficiently large to make \(y'\) negligible, the switch-on transient is already finished. For \(\omega t \ll 1\), the velocity in the \(x'\) direction is given by

\[
x'(t) \simeq \omega^2 [t - \tau + \tau \exp(-t/\tau)] \rho_0.
\]

This expression suggests approximating the switch-on profile by a step function at \(t = \tau_0 \simeq \tau\) and treating \(X'_0, Y'_0, \phi'_x, \phi'_y\) as constants for \(t \geq \tau_0\). This “delayed sudden-step approximation” is equivalent to imposing the boundary conditions \(\phi'_x = 0\) at \(t = \tau_0\). In this approximation we obtain for the phases and amplitudes

\[
\phi'_x = \tan^{-1}[\omega^2 \tau_0 / \Omega], \quad \phi'_y = 0,
\]

\(X'_0 = \rho_0 (1 + \omega^2 \tau_0^2 / \Omega^2)^{1/2}\), and

\(Y'_0 = (\omega/\Omega)\rho_0\) for \(t \geq \tau_0\). The phase development \(\omega \tau_0\) due to the rotation of the \(B_m\) field during switch-on will appear as a rotation of the major and minor axes of the macromotion with respect to the primed coordinate system defined by \(t = 0\). The optimal value for \(\tau_0\) can be determined by comparing the predictions of the analytical model with the results of a numerical calculation (see Sec. II C).

In the presence of gravity, this analysis remains valid as long as the radial frequency \(\Omega\) does not change substantially during switch-on of the \(B_m\) field; in principle \(\Omega\) can be kept constant by simultaneously switching \(B_0\) and \(B_m\) in such a way that the quantity \(B_0/(1 + 4 B_m^2 / B_0^2)\) equals the value of \(B_0\) before the \(B_m\) field was switched on. In case of a small and fast change in \(\Omega\) our model can be adapted by changing the initial conditions to \(\phi = \phi/\Omega\), \(\rho = 0\) at \(t = \tau_0\), where \(\delta \gamma = \Delta y_{\text{TOP}} - \Delta y_{\text{sp}}\) is the difference in gravitational sag. Using the adapted boundary conditions we obtain in the limits \((g\omega/B_0^2)^{1/2} \ll \Omega \ll \omega\) and \(\omega \tau_0 \ll 1\) for the amplitudes and phases of the macromotion

\[
X_0 = \rho_0 [1 + (\omega^2 / \Omega^2 - 1) \sin^2 (\omega \tau_0 + \phi_m)]^{1/2},
\]

\[
Y_0 = \rho_0 [1 + (\omega^2 / \Omega^2 - 1) \cos^2 (\omega \tau_0 + \phi_m)]^{1/2} + \delta y^2 / \rho_0^2 + 2 (\delta y / \rho_0) \sin (\omega \tau_0 + \phi_m)]^{1/2}.
\]

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\[\varphi_x = -\Omega \tau_0 + \tan^{-1}\left[\frac{\omega}{\Omega} \tan(\omega \tau_0 + \phi_m)\right] + n\pi, \quad (A8)\]
\[\varphi_y = -\Omega \tau_0 + \tan^{-1}\left[\frac{\Omega}{\omega} \tan(\omega \tau_0 + \phi_m) + (\delta y/\rho_0 \cos(\omega \tau_0 + \phi_m))\right] + n\pi, \quad (A9)\]

where \(n = 0\) for \(|\omega \tau_0 + \phi_m| \leq \pi/2, n = 1\) for \(|\omega \tau_0 + \phi_m| > \pi/2\). For \(\phi_m = 0\), these equations coincide with the equations for \(X_0, Y_0, \varphi_x,\) and \(\varphi_y\) in the primed coordinate system. Analyzing the limit \(\omega \tau_0 \to 0\) for the case \(\delta y \simeq \rho_0\) (typical for our experimental conditions), we find \(X_0 \simeq \rho_0\) and \(Y_0 \simeq (\omega/\Omega)\rho_0\) for \(\phi_m = 0\) and \(X_0 \simeq (\omega/\Omega)\rho_0\) and \(Y_0 \simeq 2\rho_0\) for \(\phi_m = \pi/2\). Thus, we deduce that gravity can have a substantial influence on the amplitude of the macromotion along its minor axis but not on the amplitude along the major axis. For known values of \(X_0, Y_0, \varphi_x,\) and \(\varphi_y\) the angle of rotation \(\vartheta\) to align the coordinate system along the major and minor axis is given by Eq. (15).

For \(\Omega \tau_0 \ll \omega \tau_0 \ll 1\) and in the absence of gravity (\(\delta y = 0\)) the delayed sudden step gives rise to a small rotation \(\Delta \varphi \simeq \omega \tau_0\), independent of \(\phi_m\). For \(\delta y \simeq \rho_0\) gravity gives rise to an additional contribution to this rotation, which is minimal for \(\phi_m = \pi/2\), where the macromotion is launched perpendicular to the gravity direction and Eq. (15) can be approximated by \(\varphi \simeq \omega \tau_0 \left[1 + (1 + \delta y/\rho_0) (\Omega/\omega)^2\right]\). The contribution is maximal for \(\phi_m = 0\), where Eq. (15) can be approximated by \(\varphi \simeq \omega \tau_0 - (\Omega/\omega)^2 (\delta y/\rho_0)^2 (1 + \omega \tau_0)\).

Insight into the dependence of \(X_0\) and \(Y_0\) on the settling behavior of \(B_0\) can be obtained from Eq. (A5), which shows that the initial acceleration and, hence, the launch speed scales with the initial value of \(\rho_0\). Therefore, most of the settling behavior is captured by using the initial value of \(\rho_0\) in Eqs. (A6) and (A7). The 5% change in \(\Omega\) requires a further refinement of the model. This cannot be implemented without sacrificing the simplicity of the model and is not pursued here.

[26] We verified that the approximation \(\phi = \phi_m + \pi\) holds to within one degree for conditions relevant for our analysis.