Epistemic modelling and protocol dynamics

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Chapter 9

Epistemic Approaches to Security Protocol Verification

9.1 Knowledge in Security Protocols

Security protocols are rules (often based on cryptography) that govern communications in hostile environments in order to guarantee certain security goals. Many such goals are naturally expressed in terms of knowledge: only the right agents should get to know the right things. This has to do with the fact that many security properties are about hiding information from the bad guys or making sure the good guys get their information. For example, here are some intuitive epistemic readings of the security properties mentioned in [RS01]:

- **Sender authentication**: the receiver knows the sender of a message;
- **Mutual authentication**: both parties (commonly) know they are talking to each other;
- **Anonymity**: the sender is unknown (to an eavesdropper);
- **Secrecy**: an intruder does not know certain information.

More specifically, in the area of voting protocols, which recently drew much attention, more involved properties are considered, for example (cf. [DKR07]):

- **Vote-privacy**: nobody other than the voter herself knows that a particular voter voted in a particular way;
- **Receipt-freeness**: a voter does not gain any information (a receipt) which can be used to let another know for sure that she voted in a certain way.
- **Coercion-resistance**: a voter cannot cooperate with a coercer to let him know that she voted in a certain way.
The above list is only indicative, and by no means exhaustive to cover the security properties that have epistemic readings. Although the precise formal meaning of the security properties as above is debatable, the relevance of epistemics in such settings is undeniable (cf. also [Kra07] (Slogan 8): “The purpose of a cryptographic protocol is to interactively compute, via message passing, knowledge of the truth of desired and, dually, knowledge of the falsehood of undesired cryptographic states of affairs”).

However, security protocols are deceptively simple-looking objects with very subtle behaviours, which require extremely precise formal analysis. Designing a correct protocol can be thought of as programming Satan’s computer as [AN95] put it. Consider the 3-line Needham-Schroeder authentication protocol [NS78]:

1. \( A \rightarrow B : \{n_A, A\}_{PK_A} \)
2. \( B \rightarrow A : \{n_A, n_B\}_{PK_A} \)
3. \( A \rightarrow B : \{n_B\}_{PK_A} \)

which prescribes a set of action patterns with roles of agents to authenticate two agents with each other. BAN logic provided a correctness proof of the above protocol, which was later proven flawed due to a man-in-the-middle attack [Low96]:

1. \( A \rightarrow I : \{n_A, A\}_{PK_i} \)
1’ \( I(A) \rightarrow B : \{n_A, A\}_{PK_b} \)
2. \( B \rightarrow I(A) : \{n_A, n_B\}_{PK_A} \)
2’ \( I\rightarrow A : \{n_A, n_B\}_{PK_A} \)
3. \( A \rightarrow I : \{n_B\}_{PK_i} \)
3’ \( I(A) \rightarrow B : \{n_B\}_{PK_b} \)

where \( A, B, I \) are concrete agents playing different roles according to the specification of the protocol. After \( A \) contacts \( I \), the intruder \( I \) can pretend to be \( A \) towards \( B \) by forwarding \( A \)’s special number to \( B \). After \( B \)’s reply, \( I \) can use \( A \) to obtain \( B \)’s number and confirm \( B \) according to the protocol. Thus \( B \) may believe he is talking to \( A \) while in fact he is talking to \( I \).

The lack of a proper semantics for its epistemic language and its high level reasoning limit the value of correctness proofs in BAN-logic. This proves the need for a closer look at the meaning of knowledge and the cryptographic operations used in security protocols.

### 9.1.1 Different Aspects of Knowledge

As an appetizer, consider the property of Secrecy:

> “an intruder does not know certain information”.

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1 A generates a random number (a nonce), and then sends it to \( B \) in a “locked box” that only \( B \) can open with his private key. \( B \) then sends \( A \)’s number back with a random number of his own, in a box that only \( A \) can open. \( A \) then confirms by sending \( B \) his number back. The intended goal is that both \( A \) and \( B \) know that they are talking to each other.
If the information concerned is a bit string \( s \) (a piece of information), then to know it amounts to possessing this piece of bit string, while \( s \) itself does not have any truth value. On the other hand, if the information concerned has the form “it was B who sent the message” (call it \( \phi \)), then to know \( \phi \) means knowing the fact that it was B who sent the message, or in other words knowing that the proposition \( \phi \) is true. Clearly, the same word knowledge can be used for different aspects of what there is to learn. We will, following [RS05b], refer to the first type of knowledge (in the sense of possession of bit strings) as knowledge of explicit data \(^2\) and to the second type of knowledge as propositional knowledge.

More subtleties regarding knowledge in a security context, are related to the cryptographic operations used in the security protocols. First of all, based on the bit strings that agents possess and the cryptographic operations available, they can know more bit strings by constructing complex message terms from what they possess, or decomposing a composed one into simpler ones. Such knowledge, in terms of possession of bit strings obtained by cryptographic operations, can be classified as algorithmic knowledge \([HP03]\). More intricately, if an agent \( A \) does not possess the symmetric key \( k \), then the encrypted message of \( m \) by \( k \) (denoted by \( \{m\}_k \)) should mean no more than a random bit string to \( A \), even though she possesses it. Thus we need a notion of knowledge to denote that an agent can see the inherent structure of bit strings. We call the last type “certain knowledge” following [BRS07].

These different ways of using the term “knowledge” (and the verb ‘to know’) suggest different structures and treatments in the formal models, which we will discuss in Section 9.2.2.

9.1.2 Tension Between Epistemic and Temporal Structure

Despite the epistemic flavour in expressing security goals, the interchange of messages, which constitutes protocols, occurs over time. Thus a rigorous epistemic approach to security protocol verification needs to harmonise the epistemic and temporal aspects. However, the intuition about the expressivity of epistemic logics does not quite coincide with the practice of security protocol verification so far: most of the successful approaches usually model the protocols formally with purely temporal structures, and try to capture the properties in a temporal formalism (cf. e.g., [RS01, AF01, FGM04]. The tension between the natural temporal essence of the formal model of protocols, and the natural epistemic formalisation of the security requirements has proven to be a challenge. This raises two natural questions:

1. Does introducing epistemics into the language indeed boost the expressive power in formalising security properties?

2. What is the computational cost of combining epistemic and temporal aspects in security protocol verifications?

\(^2\) [Kra07] uses the term “individual knowledge” for this.
Fortunately, recent years have seen a growing interest in epistemic approaches connected to the study of certain security properties that are not easily expressed in terms of events which did or did not happen along a single run of the protocol. A list of such properties includes, for example, anonymity [SS99, HO05], receipt-freeness [JdV06, JP06, BRS07], and coercion-resistance [DKR06, DKR07]. The verification of such properties depends on whether agents are able to distinguish between different courses of events, which is exactly the idea behind the standard Kripke semantics of knowledge. Formally, this involves the addition of equivalence relations to the temporal model, where it is useful, natural or even necessary as we will argue in Section 9.4.

Moreover, despite the apparent disguises of the formalisations, the epistemic logical approaches proposed by different research communities do have some important common features, where careful comparisons are needed to pinpoint the differences. Our goal of this chapter is two-fold. First, we give a brief overview of several epistemic proposals in Section 9.2 and compare the essential techniques they employ in Section 9.3. The survey in these sections is intended to be an introduction to this developing field of epistemic verification. Second, in Section 9.4, we try to give partial answers to the questions we proposed above. The survey will be presented mostly in a high level fashion and will only get to some technical details in Sections 9.3 and 9.4 when truly necessary.

While we intend this chapter to give a brief overview of approaches to modelling knowledge in the analysis of security protocols, we cannot cover all different aspects. The focus in this chapter will be on model checking approaches to verification, based on modal logics of knowledge rather than belief, that are possibilistic rather than probabilistic. For those interested in the other aspects, our introductory text in Subsection 9.2.1 contains pointers to some work in the areas outside of our focus.

### 9.2 Epistemic Approaches: A Brief Survey

#### 9.2.1 BAN logic

The starting point of formal verification of security protocols is often attributed to the development of BAN-logic [BAN89], named after its inventors Burrows, Abadi, and Needham. The syntax of this logic includes predicates of belief and actions, thus it is able to express message passing actions and security goals. In fact, BAN-logic presents a calculus (proof system) by giving a number of inference rules to derive statements. For example, here is a rule for “if A believes he shares a secret key $k$ with $B$, and $A$ has received a message $X$ encrypted with $k$, then $A$ believes that it was $B$ who sent the message”:

$$
\frac{A \text{ believes } (A \leftrightarrow B), \ A \text{ sees } [X]_k}{A \text{ believes } (B \text{ said } X)}
$$

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3However, it is essentially knowledge, following the intuition given by the authors.
To handle protocols in this framework, the protocol first needs to be idealised, then the initial assumptions are spelled out in the BAN-language, after which each step in the protocol is annotated with a BAN-formula asserting the state of affairs after that step. The statement after the final step describes the outcome of the protocol. The goal of the analysis is to derive a final assertion that implies the protocol is correct.

However, the soundness of the inference rules in the BAN-approach was questionable due to the lack of a formal semantics and clear underlying assumptions of the “idealisation” which led BAN-logic to an abstraction level too high to capture the consequences of all the possible intruder behaviours. These drawbacks made the BAN-logic analysis of the Needham-Schroeder authentication protocol overlook the possibility of the man-in-the-middle attack exposed by Lowe [Low96], who used a process theoretic analysis in the process algebra CSP [BHR84]. At the same time, model checking approaches [CGP99] began to flourish and later became prominent. To do model checking on security protocols with epistemic logic, it is necessary to have a suitable formal semantics for knowledge in the security setting.

Despite the efforts made in the literature [GNY90, Bie90, Syv92], the main hurdle to a reasonable semantics of BAN-like logics was the so-called logical omniscience problem, an inherent issue of the standard possible-world semantics of epistemic logics [VW51, Hin62]: agents know all the valid propositions and all logical consequences of what they know. According to the Kripke semantics, if a message \( m \) is indeed of the form \( \{m'\}_k \) (thus \( m = \{m'\}_k \) is true everywhere in the model), then an agent knows it, even when she does not possess the key \( k \). This sounds contradictory to our intuition in security analysis.

Many approaches have been suggested to avoid the logical omniscience problem (see [FHMV95] Ch.9 and [HP10a] for surveys). In the context of security analysis, the most relevant one is the approach of algorithmic knowledge [HMV94], which is prominent in our later introduction of various epistemic approaches. The idea is that an agent knows a message term only if it is derivable by some algorithm with respect to a deductive system capturing idealised cryptographic operations [HP03, Puc06]. For propositional knowledge, a more sophisticated way of avoiding the logical omniscience problem can be obtained by deviating from the standard Kripke semantics in the definition of reachable possible worlds, as demonstrated in [CD05b, CD07]. Essentially, such an approach introduces extra possible worlds which may not be in the model when evaluating epistemic formulas. Awareness can also be used to deal with logical omniscience in the security setting (for instance, see [ABV03]), but we will not elaborate on this here.

Before moving on from BAN to the modern model checking epistemic approaches, we should mention that several authors have proposed analyses for security protocols involving belief rather than knowledge, e.g. [HD07, vdMW07, BS08a]. Also, the epistemic approaches that we survey are possibilistic in the sense that an agent knows a fact if he does not consider it possible to be false, while in certain security contexts this may be inappropriate. For example, can we rightfully say that A anonymously

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4See [Tee06] for a more elaborate discussion on the soundness of BAN-logic.
sent a message, if \( A \) is the sender of the message in 99 out of 100 runs considered possible? This suggests a *probabilistic* approach to knowledge or belief to analyse certain security properties, as in \[RR98\] [SS99] [HO02] [HO05] [Shm04] [BP05]. These *doxastic* and *probabilistic* approaches are not covered in our survey.

### 9.2.2 Basics of Epistemic Approaches

In this section, we will list the commonly used components of most epistemic approaches in the post-BAN era. We first need a logical language \( \mathcal{L} \) to specify properties of models, where \( I \) is a (finite) set of agents. Due to the fact that we are talking about message passing in a protocol setting, we need to mention messages in our language. This is often done by introducing the message terms as follows:

\[
m ::= c \mid k \mid \{m\}_k \mid (m, m')
\]

where \( c \) stands for some basic plain terms which may in general have many sorts (e.g., names, integers, etc.), \( \{m\}_k \) is the encryption of \( m \) with key \( k \), and \( (m, m') \) intuitively represents pairing of \( m \) and \( m' \). In general, arbitrary cryptographic operations \( f \) can be introduced in this way.

Associated with the message terms there is a derivation system to capture the cryptographic functions in the message terms \[Pau97\] [Pau98] [CJM98]. For example, the following derivation rules capture the symmetric encryption and pairing of the messages:

\[
synth: m, m' \quad \frac{m, m'}{(m, m')} \quad \frac{m}{\{m\}_k} \quad \frac{k}{\{m\}_k} \\
synth: \frac{m, m'}{m} \quad \frac{m}{m'} \quad \frac{\{m\}_k}{k}
\]

where \( \text{synth} \) rules govern the application of cryptographic operations to form new terms from the old, while \( \text{analz} \) rules intuitively extract information from complex terms. We can alternatively represent \( \text{analz} \) rules by an equational theory \( E \), e.g., \( \text{dec} (\text{enc} (x, y), y) = x \) for the last rule above, if \( \text{dec}, \text{enc} \) are introduced as cryptographic operations with the obvious meaning in the language of message terms. Given a set of messages \( M \), we say \( M \vdash m \) if either \( m \in M \) or \( m \) is derivable from \( M \) by applying the rules. We write \( m =_E m' \), if \( m = m' \) is an instantiation of an equation induced by \( E \). \[HP03\] argues that a derivation system may not be convenient to model certain powerful adversary operations, and proposes to use arbitrary algorithms instead of derivation systems. For simplicity, we will not cover this more general case here.

We build formulas based on message terms which are not formulas themselves. Following the observations in Section 9.1.1, we need different knowledge operators in the language to cope with various types of knowledge:

1. **Knowledge of explicit data** (possession of bit strings): We build basic propositions in the shape of \( \text{has}_i m \), where \( m \) is a message term, meaning that agent \( i \) possesses \( m \). For such knowledge we have the \( \text{de dicto} \) reading: \( \text{has}_i \{m\}_k \) means that the bit
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string of \(\{m\}_i\) is possessed by \(i\). However, \(i\) may be unsure about the structure of the message.

2. **Algorithmic knowledge** (possession of derivable bit strings): In the literature, the knowledge of explicit data can be viewed as a special case of algorithmic knowledge. We can use \(\text{has}_m\) to express that \(m\) as a bit string can be derived from the information agent \(i\) possesses, by applying corresponding cryptographic operations modelled by \(\text{synth}\) and \(\text{analz}\) rules (see \([HP03]\) and \([RS05b]\) for the detailed rationale).

3. **Propositional knowledge** (what facts are known to the agents): As in the standard epistemic logic, we use \(K_i\phi\) to express that “agent \(i\) knows that \(\phi\) is true.” Thus the logical language \(L_I\) may look like:

\[
\text{has}_m \mid \overline{\text{has}_m} \mid \phi \land \psi \mid \neg \phi \mid K_i\phi \mid O\phi
\]

where \(m \in M\), and \(O\) can be any modal operator other than \(K_i\), depending on what properties we want to specify. On the other hand, given an existing modal logic language, we can turn it into a language about message passing by adding epistemic operators and taking \(\text{has}_m\) as the basic propositions.

4. **Certain knowledge** (the understanding of the bit strings). This kind of knowledge sits in between algorithmic knowledge and propositional knowledge, since it is not only about message terms itself but also about the observational power of agents \([BRS07]\). We may use \(K_i\text{has}_m\) to express that agent \(i\) knows that \(m\) is of certain structure, e.g., \(K_i\text{has}_S[c]\) means \(i\) knows that he has a bit string which stands for \(\{c\}_k\). Thus knowledge operator \(K_i\) induces somehow a de re reading of \(\text{has}_m\).

To evaluate the basic formulae in the shape of \(\text{has}_m\) on Kripke models, we need to associate a set of message terms for each \(i\) at each state. Then \(\text{has}_m\) is true at a state \(s\) if \(m\) is in the set of messages associated with \(i\) on \(s\). The semantics of \(\overline{\text{has}_m}\) is also straightforward by considering the derivable messages at a state.

According to the standard Kripke semantics, \(K_i\phi\) is true at a state if \(\phi\) is true anywhere reachable from the current state. The equivalence relations naturally model the epistemic uncertainties of agents. Thus the actual formal meaning of propositional knowledge and certain knowledge depends on the definition of the equivalence relation in the model and the message terms possessed by agents at various states. We will compare different equivalence relations in Section 9.3.1.

Given an epistemic language in the above style, an epistemic verification framework should give a general way to build up models from a protocol description in

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3Here the “overline” in \(\overline{\text{has}_m}\) shows that \(m\) is in the closure of derivation.

4In addition to \(\text{has}_m\), it is also common to introduce special propositions to denote the actions happened in the past, e.g., \(\text{send}_i(m)\) (see, for instance \([HP03]\)).

5Different semantics for \(K_i\) operator may cause subtly different readings for such statements. We will see different semantics in Section 9.3.1.
order to do model checking. Two approaches are discussed in the next subsections following the traditions of Epistemic Temporal Logic and Dynamic Epistemic Logic.

9.2.3 Epistemic Temporal Approaches

To ease the exposition we now equip the interpreted systems defined in Definition 2.3.1 with explicit events. As usual, given a set of agents \( I \) with \( \epsilon \) for the environment and the sets of local states \( L_1, \ldots, L_n, L_\epsilon \), a set \( S \) of global states is a subset of \( L_\epsilon \times L_1 \times \cdots \times L_n \). Given a set of events \( E \) and a set of global states \( S \), we associate with each \( e \in E \) a transition relation \( e \to \subseteq S \times S \). An infinite run \( r \) on \( S \) is a function \( r : \mathbb{N} \to S \times E \). Let \( r_S(u) \) and \( r_E(u) \) be the corresponding global state and event (to happen) at the \( u \)th point of the run \( r \) respectively. We say a run \( r \) is admissible if \( \forall u \geq 0 : r_S(u) \to r_S(u + 1) \). An interpreted system \( I \) is then defined as a pair \( (R, V) \) where \( R \) is a set of admissible runs, and \( V : S \to 2^P \) is a valuation function assigning to each proposition atom in \( P \) a truth value. We denote by \( (I, r, u) \) the point \( r(u) \) in interpreted system \( I \).

To verify a protocol in the presence of an adversary, we need to formalise the protocols and the adversary model, describing the possible actions of an adversary. Here we show an example of a formalisation of the Needham-Schroeder authentication protocol mentioned in Section 9.1, with the Dolev-Yao adversary model \([DY83]\) where all the messages are delivered via the intruder role \( (E) \) acting as a buffer (see, e.g., \([Cre06]\) for rationale):

\[
\begin{align*}
\text{for } A : & \\
1. & A \text{ send } E : [n_A, A]_{|\epsilon|} & 1. & B \text{ rec } E : [n_A, A]_{|\epsilon|} \\
2. & A \text{ rec } E : [n_A, n_B]_{|\epsilon|} & 2. & B \text{ send } E : [n_A, n_B]_{|\epsilon|} \\
3. & A \text{ send } E : [n_B]_{|\epsilon|} & 3. & B \text{ rec } E : [n_B]_{|\epsilon|}
\end{align*}
\]

Here the action patterns in a protocol are broken down and grouped into local protocols by roles. Note that, in the above formalisation, the intruder implicitly eavesdrops on all the messages and the agents will accept any message that the intruder may possess, as long as it is in the forms specified (thus modelling the intruder’s ability to manipulate messages).

Despite differences in details in each specific framework, e.g. \([HP03]\), \([vdMS04]\), \([RS05b]\), \([BCL09]\), we can summarise the merit of the general ETL approach for modelling protocols under an adversary model, as the following steps.

1) Suppose the set of agents is \( I = \{1, 2, \ldots, n, \epsilon\} \), where \( \epsilon \) indicates the intruder. We start from a set \( S_0 \) (usually a singleton) of initial states which are tuples of local states \( \langle l_1, \ldots, l_n, l_\epsilon \rangle \). An initial local state for agent \( i \) should, among other things, encode a set of message terms representing the messages that agent \( i \) initially

\(\text{\footnote{Sometimes one intruder is enough, and we can give a small finite bound on the number of other agents, see, for instance. [LC03].}}\)

\(\text{\footnote{For simplicity, we do not go into the details of the various specification languages and adversary models proposed in the literature. For example, [HP03] provide the possibility of modelling different adversaries in the IS-framework.}}\)
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possesses (i.e. the information states of agents [RS05b]). In such a setting, we can retrieve the information state of \( i \) at global state \( s \) by \( \text{info}_i(s) \). We can then define the semantics of \( \text{has}_j m \) and \( \text{has}_j m \) at \((I,r,u)\) by \( \text{info}_j(r_{s}(u)) \) in a straightforward way.

**Step 2.** We can generate a temporal structure, based on the initial states, by collecting all the admissible sequences of global states according to the protocol under the adversary model. The protocol specification and the adversary model define a set of events (instantiated action patterns). To give the transition relation \( \xrightarrow{\sim} \) for the events on the global states, we can give each event \( e \) a precondition and a postcondition. The first specifies when the event can happen and the latter one describes for which pairs of agents the message is delivered (under the Dolev-Yao model). The order of the actions according to the protocol can be encoded also by preconditions requiring that a certain action happened in the earlier stage of the run. We call the resulting set of runs the generated temporal structure \( T(S_0) \).

We choose to let each \( e \) be observable to an agent \( i \) iff \( i \) herself is involved, e.g., \((j \text{ send } e : m)\) is only observable by \( e \) and \( j \). Similarly, the \( i \)-observable subsequence of \((j \text{ send } e : m)\) is \((i \text{ rec } e : m')\). In the Dolev-Yao setting we presented above, the intruder can observe all the events. In a more sophisticated analysis, the events are composed by synchronising local events with respect to each agent according to their local protocols, cf. e.g., [BCL09].

**Step 3.** From \( T(S_0) \), we build up the epistemic temporal model \( E(T(S_0)) \) by defining epistemic relations \( \sim_i \) between points \((T(S_0), r, k)\). The standard way of defining \( \sim_i \) in IS is by matching local states of \( i \), or local views of \( i \) of the histories of events. However, the information sets and local histories in the protocol setting do not capture how the messages are understood by the agents (recall what we called certain knowledge, Section 9.2.2). It is possible that two message terms are different, but still regarded as the same by an agent e.g., events \( \text{rec} : [m]_k \) and \( \text{rec} : [m']_k \) are not distinguishable to an agent who does not have the key \( k \). Moreover, if an agent later obtains the key \( k \), then she can tell \([m]_k \) and \([m']_k \) apart by "looking back with a fresh eye". Thus we need to build \( \sim_i \) on some sophisticated equivalence relation on messages (\( \approx \)). In Section 9.3.1 we will discuss different existing definitions for \( \approx \) on lists of message terms, since we usually assume that the agents can remember the order of the messages passing actions that she can observe.

It is not hard to see that we can lift \( \approx \) to equivalence between points in an IS. Suppose each information set is represented by a list of messages. Let \( M_i(e_0, \ldots, e_u) \) be the list of messages occurring in \( i \)'s observable subsequence of events in \( e_0, \ldots, e_u \).

Two obvious possibilities are:

- **Asynchronous:** \((s_0 \xrightarrow{e_0} s_1 \ldots s_{u-1} \xrightarrow{e_u} s_u) \sim_i (s'_0 \xrightarrow{e'_0} s'_1 \ldots s'_{u-1} \xrightarrow{e'_u} s'_u) \) iff \( \text{info}_i(s_u) \approx \text{info}_i(s'_u) \)
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- **Synchronous:** $(s_0 \xrightarrow{e_0} s_1 \ldots s_{u-1} \xrightarrow{e_u} s_u) \sim_i (s'_0 \xrightarrow{e'_0} s'_1 \ldots s'_{u'-1} \xrightarrow{e'_{u'-1}} s'_{u'})$ iff $u' = u$ and $(info(s_0), M_i(e_0, \ldots, e_{u-1})) \approx (info(s'_0), M_i(e'_0, \ldots, e'_{u'-1})).$

The above procedure can be summarised with the slogan:

*First temporal then epistemic.*

Notably, [BCL09] presents a fully automated method to generate interpreted systems from formal specification of protocols taking many small details into consideration. Other methods to generate IS-like models include process algebra with epistemic annotations, e.g., [DMO07], which makes use of an operational semantics to generate the model from the protocol specified in process algebra terms.

### 9.2.4 Dynamic Epistemic Logic Approaches

As we have demonstrated in the previous chapters, DEL can be applied in modelling what agents learn through different communication acts according to epistemic reasoning, for example in the Russian Cards scenario discussed in Chapter 3. Thus it looks promising to analyse security protocols by modelling protocols in terms of action models. In [HMV05], [VO07], and [DW07] the first attempts were made towards the security protocol verification by DEL. Note that, security protocols are much more complicated than the epistemic protocols discussed in Chapter 3 and Chapter 4, thus to model such protocols, more general event models of DEL are needed rather than atomic actions or public announcements only. We summarize the modelling steps as follows based on the above attempts:

**Step 1.** We start with a finite initial static model $M$ with epistemic relations $\sim_i$ ready. Similar as in the interpreted system approach, a state is associated with a tuple of information sets modelling the messages that agents possess. The epistemic relations can be given similarly according to the equivalence $\approx$ on lists of messages.

**Step 2.** We need to build an event model $\mathcal{A}$ which captures all the protocol actions with suitable pre- and postconditions similar to what we described at step 2 for ETL approaches. For example, to model the Needham-Schroeder authentication protocol mentioned above, we can build action model $\mathcal{A} = (E, \{\approx_i\}_{i \in I}, Pre, Pos)$ such that $E$ includes all instantiated actions of the protocol, for example: event $e = (j \text{ send } e : [n_j, j]_{PK})$ with $Pre(e) = has((n_j, j)_{PK})$ and $Pos(e)(has((n_j, j)_{PK})) = \top.$ The epistemic relations $\approx_i$ between events can be generated by lifting $\approx$ on lists of messages to events, under the constraint that an agent can always distinguish the events that she is involved in from other actions.

**Step 3.** The update execution computes the result of performing $\mathcal{A}$ on $M$ iteratively, thereby it essentially builds up all the possible runs of the protocol.

10This is an example of asynchronous and forgetful agents [SG02], other memory conditions can be applied here.

11In [DW07], we introduced the iteration operation on event models in a DEL language which is similar to the one we presented in Chapter 3 but with public announcements replaced by event models.
9.3. Comparisons

The above procedure can be summarised as the slogan:

*First epistemic then temporal.*

Although it seems that DEL modelling is very similar to ETL modelling, we will pinpoint the tricky differences between the two approaches in details in Section 9.3.2.

9.2.5 Tools

In the last decade, many tools have been developed to handle formal verification in the setting of ETL or DEL, with potential application in security analysis. For ETL model checking, we have MCK: Model Checking Knowledge [GvdM04, vdMS04] and MCMAS: Model Checker for Multi-Agents Systems [LR06a, LQR09]. [BCL09] recently presented a fully automatic translation from protocol descriptions given in CAPSL (Common Authentication Protocol Specification Language) into the input language for MCMAS, enabling the automated checking of the security protocols from the Clark-Jacobs security protocol library by means of epistemic temporal logic. For DEL model checking, we have DEMO: Dynamic Epistemic MOdelling [vE07] and LYS: a knowledge anaLYsis toolset [Orz05]. Other relevant tool sets include the ETL-model checker MCTK [Su04], the ATL-model checker [AHM+98], and the real-time system model checker [KNN+08].

In the literature, various tools are presented with some case studies demonstrating how the framework can be applied. For these demonstrations, often well-known situations or protocols are chosen which require relatively small models. The classic examples in the epistemic verification demonstrations are the Dining Cryptographers protocol for anonymous broadcast [Cha88], the Muddy Children (see, e.g., [FHMV95]) for demonstrating the effect of (repetition of) public announcements, and Russian Cards Problem (see [vD03]) for secure public announcements. Such common examples facilitate comparisons of the modelling and efficiency among different tools based on different frameworks, see, for example [vDvdHvdMR06], which takes the Russian Cards problem as a test case for MCK, MCMAS and DEMO.

9.3 Comparisons

In this section we will compare more technical aspects of the approaches mentioned in the previous section. In the first part, we discuss the different versions of equivalence. In the second part, we compare the epistemic temporal approach with the dynamic epistemic one in the security setting.

9.3.1 On Equivalences

Some well known formal methods have been adapted or designed to include (trace) equivalences to deal with multi-trace security properties (e.g., applied pi-calculus

---

12This is definitely not a complete list, see [LP07] for a survey of symbolic model checking for ETL.
In this part, we focus on how the equivalence relations of agents are defined, based on the lists $\langle m_1, \cdots, m_n \rangle$ that record the messages that an agent received in order. The rest of this subsection will be devoted to the comparison of the following equivalence relations:

- **simple deduction equivalence** $\approx_d$
- **pattern matching equivalence** $\approx_{\text{pat}}$ (in [AT91, AR02] and [BRS07]);
- **static equivalence** $\approx_s$ (defined in [AF01, AC04], and later used in [CDK09b, CDK09a]);
- **permutation equivalence** $\approx_{\text{per}}$ (in [CD05a, GHPvR05], and later used in [CD07, JP06]).

We assume there is a fixed equational theory $E$ corresponding to the derivation system on terms of messages. Let $M = \langle m_1, \ldots, m_n \rangle$ and $M' = \langle m'_1, \ldots, m'_n \rangle$ then:

- $M \approx_d M'$ iff for all message terms $m$: $M \vdash m \iff M' \vdash m$.

- $M \approx_{\text{pat}} M'$ iff $M$ and $M'$ induce the same recognisable message patterns, i.e. for all $j$: $\text{pat}(m_j, M) = \text{pat}(m'_j, M')$, where $\text{pat}(m_j, M)$ is roughly the message term in which the unconstructable parts are replaced by an uninterpreted symbol $\Box$. For example:

  $\text{pat}(|m|_k, M) = \begin{cases} 
  \{\text{pat}(m, M)|_k \} & \text{if } M \vdash k \\
  \Box & \text{otherwise}
  \end{cases}$

  For formal details on various cryptographic operations we refer to [AR02, BRS07].

- $M \approx_s M'$ iff $M$ and $M'$ satisfy the same equality tests. Formally, defining $\sigma_M, \sigma_{M'}$ to be the substitutions replacing $x_j$ with $m_j$ and $m'_j$ respectively, then $M \approx_s M'$ iff for any message terms with variables $t(x_1, \ldots, x_n)$ and $t'(x_1, \ldots, x_n)$:

  $\sigma_M(t) \models_E \sigma_{M'}(t) \iff \sigma_M(t') \models_E \sigma_{M'}(t')$ \[14\]

- $M \approx_{\text{per}} M'$ iff there is a permutation $\pi: M \rightarrow M'$ such that for all $j$: $\pi(m_j) = m'_j$ and $\pi(t(m)) = t(\pi(m))$ for any message term with variables $t$ and any suitable list $\overline{m}$ from $\{m \mid M \vdash m\}$. [CD05a] shows that $\approx_{\text{per}}$ is indeed an equivalence relation.

The relation $\approx_d$ is very fine (despite the fact it does not require a one-one correspondence of messages) and thereby assigns strong observational power to the agents:

\[13\]Note that the equivalences we consider here all respect the number of messages.

\[14\]Here we leave out the details about protected names in the original frame (our $\sigma$) in applied-pi calculus.
e.g. $M_1 = \langle c \rangle \not\approx_d M_2 = \langle c' \rangle$. It may only make sense to employ such an equivalence relation for the intruder if we need to guarantee extreme security. On the other hand $\approx_{pat}$ is rather coarse as it treats all the unreadable parts as the same: e.g. $M_3 = \langle c \rangle, \langle c' \rangle \not\approx_{pat} M_4 = \langle c \rangle, \langle c \rangle$ since $pat([c], M_3) = pat([c'], M_3) = pat([c], M_4) = 0$.

Static equivalence is somewhere in between e.g., $M_1 \approx_s M_2$ but $M_3 \not\approx_s M_4$ since $\not\in \approx\langle c \rangle, \langle c' \rangle$. To relate $\approx_s$ and $\approx_{per}$, Cohen and Dam show that:

**9.3.1. Theorem ([CD07]).** For any lists of messages $M$ and $M'$ satisfying $|\{m \mid M \not\approx m\}| = |\{m \mid M' \not\approx m\}| = \omega$:

$$M \approx_s M' \iff M \approx_{per} M'$$

where the cardinality condition allows us to permute all the non-derivable messages in $M$ to the non-derivable messages in $M'$.

[CD07] pleads for a principled approach to model indistinguishability relations that is worth elaborating upon. They define two states to be indistinguishable for a test $\theta$ if the agent can compute the same observations from both states. There observations can be considered as tests in the spirit of static equivalence. They generate relations on the basis of the computational power of the agents: taking $\Theta$ to be a set of observations $\theta$ (tests), and $A$ an algorithm returning for each $\theta \in \Theta$ and $M$ the answer “yes”, “no” or “unknown” to the question whether $\theta$ holds at $M$, they let $M \approx_{\Theta,A} M'$ iff for all $\theta \in \Theta$ $A(\theta, M) = A(\theta, M')$. For example $\approx_{pat}$ can be reformulated as $\approx_{\Theta,A}$ where $\Theta$ is built as follows:

$$t ::= x \mid c \mid k \mid \langle t \rangle \mid \langle t, f \rangle$$
$$\theta ::= \text{has}(t) \mid \exists x. \theta$$

where the only free variable in $\theta$ is $x$.

It is easy to see that $\theta$ expresses the pattern of a message. The corresponding algorithm $A$ then takes a pattern and then try to match it in $M$. On the other hand, to have $\Theta$ define $\approx_{\Theta}$, we at least need to introduce equality into the language of $\Theta$. In fact, if we take $\Theta$ as a logical language then this proposal is actually asking for logical characterisations of different equivalence relations with corresponding “model checking” algorithms for $\Theta$ on $M$. As another example, a logical characterisation of $\approx_{per}$ is given in [CD07] Theorem 3.

Regarding the complexity of checking such equivalence, we should first note that the decidability of $M \vdash m$ can be encoded by the decidability of $\approx_s$ or $\approx_{pat}$. However, checking $\vdash$ can be undecidable [AC04] depending on the underlying derivation system. [BRS07] shows that when $M$ is finite, a derivation system containing encryption and blind signature can be decided in PTIME. This implies the decidability of $\approx_{pat}$ according to the definition of $\approx_{pat}$ in [BRS07]. More general results in [AC04] show that when $E$ is a convergent subterm theory that can cover many important cryptographic operations, both $\approx_s$ and $\vdash$ are decidable in PTIME.

### 9.3.2 ETL vs. DEL in Modelling

We now compare the epistemic temporal approach with the dynamic epistemic approach in modelling.
Limitations of DEL

As epistemic temporal logic and dynamic epistemic logic are two important methods of describing epistemic interaction over time, technical comparisons have been done to pinpoint the differences between the two. From an abstract point of view, ignoring the structure of the local states, an ETL-model is a tree-like Kripke structure with relations labelled by events and agent names. We get a similar structure, if we start from a static initial Kripke model, performing sequences of DEL-updates, and link each state and its update by the corresponding event (s → (s, e)).

Van Benthem et al. ([vBGHP09]) characterise the class of ETL tree-like structures that are DEL constructable by a uniform protocol in the above sense, by the notions of Synchronicity (agents are always aware if something has happened), Perfect Recall (the local history is remembered), No Miracles, and Epistemic Bisimulation Invariance (see below). This means that standard DEL can only deal with idealised agents who satisfy those properties. If we model intruders with enough observation power for better security, then Synchronicity and Perfect Recall can be intuitively assumed. However, No Miracles and Epistemic Bisimulation Invariance may lead to some drawbacks of DEL approaches in security verification:

**No Miracles**: An ETL-model $M$, considered as a Kripke model with temporal action transitions $\rightarrow_{\text{act}}$ and epistemic relations $\sim_i$, has the property No Miracles if the following holds: for all states $s, s'$ and events $e, e'$ such that $s \rightarrow_{\text{act}} t$ and $s' \rightarrow_{\text{act}} t'$, for some $t, t'$: if $s \sim_i s'$ and there are $s'', s'''$ with $s'' \rightarrow_{\text{act}} t''$, $s''' \rightarrow_{\text{act}} t'''$ for some $t'' \sim_i t'''$, then $t \sim_i t'$. (If two actions lead to indistinguishable states somewhere in the model, then it cannot be the case that performing these actions on indistinguishable states will lead to distinguishable states.)

However consider the following (partial) model where $\sim_i$ denotes an equivalence relation based on $\equiv_{\text{pat}}$:

\[
\begin{align*}
&i : [\{c\}] \quad i : [\{c\}] \\
&\quad \downarrow \quad \quad \downarrow \\
&i : [\{c\}] \quad i : [\{c\}] \\
&\quad \downarrow \quad \quad \downarrow \\
&i : [\{c\}, k] \quad i : [\{c\}, k] \\
&\quad \downarrow \quad \quad \downarrow \\
&i : [\{c\}, k] \quad i : [\{c\}, k] \\
&\quad \downarrow \quad \quad \downarrow \\
&i : [\{c\}, k] \quad i : [\{c\}, k] \\
\end{align*}
\]

where $k' \neq k$ and $c' \neq c$. Clearly, this model violates No Miracle, so it is impossible for it to be generated by the standard DEL approach. The problem is rooted in the definition of epistemic relations in the action models. Recall that the epistemic relations in the updated model are defined by the synchronisation of the epistemic relations in the static model and those in the action model. However, in the security protocol setting, the same receive action on indistinguishable states may cause the resulting states to be distinguishable, as the example shows. One way to go around this is to “split” each action into multiple copies with different preconditions such that different copies of the same action may be distinguished under different preconditions. For example, in the action model, the action $(i \text{ rec } e : k)$ with the
precondition \( \text{has}_i[c]k \) should be \( i \)-distinguishable from the same action with the precondition \( \text{has}_i[c']k \), if \( c \neq c' \). However, this ad-hoc method may introduce infinitely many copies of actions in the action model, which is not allowed by the standard DEL.

**Epistemic Bisimulation Invariance** requires the same event to happen at the states that are epistemically bisimilar (i.e. bisimulation disregarding the temporal relations). This is because the pre-conditions in the action model are formalised in the dynamic epistemic language. This may cause problems if we want to model protocol actions with temporal preconditions in terms of the past (for example, if \( i \) sends \( k \) only if \( j \) sent \( k' \)). The usual solution is to encode the history of actions by new basic propositions.

**Limitations of ETL**

According to the modelling procedure we described in Section 9.2.3, the epistemic relations are built after the temporal structures. This may prevent us from handling knowledge-based protocols, which have preconditions in terms of knowledge, e.g., \( i \) sends \( m \) only if \( i \) knows that \( j \) has \( k \). As shown in [HF89, FHMV97], it is possible to construct the unique temporal structure and epistemic relations simultaneously according to a knowledge-based protocol, if the system is synchronous and the epistemic preconditions are not about the future. On the other hand, DEL by definition can handle conditions about what may happen in the future, since in action models we can have preconditions like \( K_i(\langle A, e \rangle \phi) \) (\( i \) knows that \( e \) may happen and in that case \( \phi \) will be true).

In the ETL modelling of security protocols, the initial (global) states represent the initial distribution of names, keys, and other messages. If we focus on a particular distribution, then we can start with a unique initial state. By doing so, we implicitly assume that the distribution of the information, e.g., who has what key, is commonly known [BRS07]. However, what if one agent is uncertain about whether another agent knows that she has a public key? Such higher order uncertainties are not well-handled if we generate epistemic relations between initial states based on matching local states. For example, suppose the only message term is a public key \( k \) and agent \( i \) has it while agent \( j \) does not. To make the formula \( \phi = K_i(\text{has}_i k \land \neg \text{has}_j k) \land \hat{K}_iK_i \text{has}_i k \land \hat{K}_j \neg K_j \text{has}_j k \) true in an initial model, we need at least two states which represent the same initial distribution of messages, as the following model shows:

\[
\begin{align*}
&i : \{k\}; j : \{} \quad \longleftrightarrow \quad i : \{k\}; j : \{}
\end{align*}
\]

\[
\begin{align*}
i : \{}; j : \{} \quad \longleftrightarrow \quad i : \{}; j : \{}
\end{align*}
\]

15 As argued in [HF89], if a protocol has “forward-looking” conditions (like \( K_i F \phi \) “\( i \) knows that \( \phi \) will hold eventually”), it is circular to define the admissible runs uniquely. Therefore there may be none or several solutions to the fix-point-like definition of the admissible runs.
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It is clear that $\phi$ holds at the upper two states. However, if the epistemic relations are generated by matching local states or other local information, then there should be a $j$ relation linking all the states. But then formula $K_i \neg K_j \text{has}_k$ will be true at the upper worlds, contradictory to our initial intention. In fact, if we want to handle higher order uncertainties by the generated epistemic relations, we need to introduce some extra tokens in the local states of $j$ to distinguish the two upper states. Intuitively, a local state of one agent, though called local, should also contain information about one’s opinion of others, in order to handle higher order uncertainties. However, it is rather ad-hoc to introduce those auxiliary tokens. On the other hand, DEL is more flexible in modelling how agents reason about each other, because the equivalences can be defined by choice. More flexibility is also offered by the possibility of modelling higher order uncertainties in the action models.

To summarize, the distinct features in either the DEL or ETL approaches are usually double-edged swords:

<table>
<thead>
<tr>
<th>Features</th>
<th>ETL</th>
<th>DEL</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Equivalence relations</strong></td>
<td>generated by matching local information</td>
<td>generated by product update or by hand (for initial models)</td>
</tr>
<tr>
<td>Pros</td>
<td>flexible and automatic; generated in a distributed fashion</td>
<td>easy to handle higher order uncertainties; update mechanism is formally defined</td>
</tr>
<tr>
<td>Cons</td>
<td>inconvenient for higher order uncertainties at initial states</td>
<td>inconvenient in a cryptographic setting</td>
</tr>
<tr>
<td><strong>Events</strong></td>
<td>represented by transitions on global states</td>
<td>modelled in action models</td>
</tr>
<tr>
<td>Pros</td>
<td>flexible</td>
<td>pre- and postconditions are encoded in the DEL language thus easy to handle epistemic conditions in protocols</td>
</tr>
<tr>
<td>Cons</td>
<td>detailed modelling (e.g. pre- and postconditions) is outside the framework</td>
<td>equivalence relations between events are designed by hand</td>
</tr>
</tbody>
</table>

Based on the above observation, we may want to combine the two frameworks, as already attempted in [HY09, VBGP09, Hos10, WSvE10]. Chapter 5 of this thesis also presents an effort to bring the distributed features of ETL to DEL modelling.

Compared to the ETL approach, the standard DEL approach has limitations in generating suitable equivalence relations in the security setting. On the other hand, as we demonstrated in Part I, DEL seems convenient for epistemic protocols where:

- preconditions are in terms of the knowledge of the agents;
- higher order uncertainties are crucial (e.g., higher order uncertainty about initial distribution of information or observation of actions);
• protocol goals are in terms of the nested knowledge form.

Epistemic protocols use epistemic reasoning rather than cryptography to obtain security. Examples of such protocols include e.g., Dining Cryptographers [CCD88] and Card Cryptography [FW96, vD03, vD08]. As we have shown in Chapter 3, to verify such protocols, meta-knowledge of the protocols themselves matters and creates some complications. It is not yet clear whether intruder’s knowledge about the goal of a security protocol will also affect the verification result.

9.4 To Know or Not, Towards a Technical Answer

As emphasised in the previous sections, many epistemic approaches are motivated by a common conviction that epistemic logic can express security properties “more naturally”. However, in practice, in most of the formal frameworks, security properties are formalised as temporal formulae rather than in terms of knowledge. To really justify the use of epistemics, it is crucial to understand better whether adding epistemics can indeed help to express more security properties, and if so, what the cost is for the improved expressivity.

9.4.1 On Expressivity of ETL

Aiming at a technical basis to answer the above questions, we formally compare the expressivity of epistemic temporal logic (ETL) versus pure temporal logic (TL) in the rest of this section. Here we regard ETL and TL as classes of logics: we do not fix the exact logic unless necessary. The comparison will always be between a temporal logic L and an epistemic temporal logic that extends L with epistemic operators.

A logic L₁ is strictly more expressive than L₂, if (1) for every formula in L₂ there is a formula in L₁ defining the same class of models (i.e. they have exactly the same models); but (2) there is a formula in L₁ which does not have a corresponding formula in L₂. Note that the comparison of the expressivity of different logics is usually studied given the condition that the logics concerned are defined on the same type of models. However, in the case of ETL and TL, this condition does not hold: the models of ETL involve epistemic relations, while these are absent in the TL-models. This complicates formal comparisons of the two logics in terms of expressivity. To make the comparison of ETL and TL possible, we need to provide the common playground for these two logics.

A rather straightforward observation is that if we consider the epistemic relations of agent i to be just another kind of transitions, labelled ‘i’, then ETL can be “reduced” to TL. Let CTL’ and μL be CTL’ and modal μ-calculus with extra actions labelled by the names of agents in I respectively. Let C^{ETL} and C^{TL} be the classes of all ETL- and TL-models respectively. Then:

9.4.1. Theorem. There exists a language translation t_L : L_{ETL} → L_{TL} and a model transform-
mation \( t_M : \mathcal{C}_{ETL} \rightarrow \mathcal{C}_{TL} \) where \( TL \in \{ CTL^*, PDL, \mu I \} \) such that:

\[
\forall \phi \in \mathcal{ETL} \forall M \in \mathcal{C}_{ETL} (M \models \mathcal{ETL} \phi \iff t_M(M) \models \mathcal{TL} t_L(\psi)).
\]

**Proof**  We only discuss the CTL* case. Let \( t_L \) be the translation that, for each formula, 1) replaces each occurrence of \( K_i \) by \( AX_i \), 2) recursively replaces each common knowledge operator \( CI' \) (with \( I' \subseteq I \)) by \( A(\neg(\bigvee_{i \in I'} X_i \top) U L(t_L(\neg \phi))) \). Let \( t_M \) be the transformation which unravels the epistemic relations into labelled temporal relations.

This observation suggests a way to reduce \( \mathcal{ETL} \) model checking to \( \mathcal{TL} \) model checking, with the help of some small model property. However, the unravelling of epistemic relations may introduce an exponential blow-up of the models, see, for instance [AvC07].

On the other hand, the above result is somehow misleading in understanding the expressivity of \( \mathcal{ETL} \) and \( \mathcal{TL} \), since we reinterpret epistemic relations as temporal operators by introducing new operators in the temporal language. To address the comparison of expressivity without manipulating the language we can consider the following case:

**Suppose that the epistemic relations of the \( \mathcal{ETL} \)-models are generated by the temporal structures as explained in Section 9.2.3.** We can turn the \( \mathcal{ETL} \)-models into \( \mathcal{TL} \)-models by ignoring the generated epistemic relations. A straightforward question is to ask whether explicit epistemics helps to define more classes of such temporal models, or if the epistemic information can be retrieved from the temporal structure. Formally we need to prove or disprove the following:

\[
\exists \phi \in L_{ETL}, \forall \psi \in L_{TL} : t_M(C_\phi) \neq C_\psi.
\]

where \( C_\phi (C_\psi) \) is the class of \( \mathcal{ETL} (\mathcal{TL}) \) models which satisfy \( \phi (\psi) \); \( t_M \) transforms the \( \mathcal{ETL} \) models in \( C_\phi \) into corresponding \( \mathcal{TL} \) models by ignoring the generated epistemic relations.

In case that the epistemic relations are generated respecting synchronicity (i.e. epistemic relations only appear in the same level of the tree unravelling of the temporal model), then we have a clear answer to the above question. We can reformulate Theorem 1 of [AvZ06] in spirit as follows:

**9.4.2. Theorem.** If we only consider the \( \mathcal{ETL} \) models satisfying synchronicity, then the secrecy flavoured \( \mathcal{ETL} \) formula \( AXAG(\neg Kp \land \neg Kp \land \neg Kp) \) (never be sure about \( p \) in the future) is not \( t_M^{-} \)-translatable into \( L_{\mu} \).

The proof is essentially hidden in [Eme87], which shows that the class of the trees that have a level where \( p \) is true everywhere, is not recognisable by non-deterministic Muller tree automata. We can employ the pumping-lemma-like argument of [Eme87] to obtain this result.

More generally, it is known that Monadic Second Order Logic (MSO) cannot express “\( x \) and \( y \) are at the same level” on trees [LS87]. Thus, the merit of the above untranslatability result may actually be rooted in the property of synchronicity. Hence, although synchronicity is a commonly accepted idealisation of the agents, we still
9.4. To Know or Not, Towards a Technical Answer

want to know whether we can ignore it or replace it by other properties but get a similar untranslatability result. This is still open.

9.4.2 Model Checking ETL

The previous sections gave both the intuitive and technical arguments on the usability and expressivity of the epistemic approaches in protocol verification. However, do we pay any cost in the complexity of model checking? In this section we summarize the important model checking results of the literature. For complexity results regarding the satisfiability problems of the corresponding logics, we refer to [HV86, SG02].

[SG02] shows that on explicit Kripke models the model checking problem of CTL with common knowledge operators (CTL + C) can be done in PTIME and [vdHW02] proved that for Alternating Time Logic (ATL) with knowledge, it is PTIME-complete. This looks similar to the logics without knowledge operators. However, due to the construction of epistemic models in the protocol verification setting, we are more interested in the model checking problem on finitely generated infinite epistemic temporal models. Results in [SG02] indicate that on asynchronous generated models with forgetful agents, the complexity of model checking complies to the general case on Kripke structures. However, we are more interested in the finitely generated synchronous system with perfect recall agents as intruders. Here are some results for this situation:

<table>
<thead>
<tr>
<th>Reference</th>
<th>Logic</th>
<th>Fragment</th>
<th>Complexity</th>
</tr>
</thead>
<tbody>
<tr>
<td>[vdMS99]</td>
<td>LTL + K</td>
<td>full</td>
<td>non-elementary</td>
</tr>
<tr>
<td>[vdMS99]</td>
<td>LTL + C</td>
<td>full</td>
<td>undecidable</td>
</tr>
<tr>
<td>[vdMS99]</td>
<td>LTL + C</td>
<td>UNTIL-free</td>
<td>PSPACE-complete</td>
</tr>
<tr>
<td>[EGvdM07]</td>
<td>LTL + C</td>
<td>single agent</td>
<td>PSPACE-complete</td>
</tr>
<tr>
<td>[SG02]</td>
<td>CTL + K</td>
<td>full</td>
<td>non-elementary</td>
</tr>
<tr>
<td>[SG02]</td>
<td>CTL + C</td>
<td>full</td>
<td>undecidable</td>
</tr>
<tr>
<td>[AvC07]</td>
<td>CTL + K</td>
<td>nesting-free</td>
<td>PSPACE-complete</td>
</tr>
<tr>
<td>[SG02]</td>
<td>PDL + C</td>
<td>full</td>
<td>PSPACE-complete</td>
</tr>
<tr>
<td>[SG02]</td>
<td>MU + K</td>
<td>full</td>
<td>undecidable</td>
</tr>
<tr>
<td>[AvC07]</td>
<td>MU + K</td>
<td>nesting-free</td>
<td>EXPTIME-complete</td>
</tr>
</tbody>
</table>

Putting together the decidability of $\approx$ on messages terms (cf. Section 9.3.1) and the model checking results above, we can obtain decidability results for security verification (e.g. [BRS07])\[16\]

The above results suggest that we may need to restrict ourselves to single agent cases or nesting-free ETL formulas due to the computational complexity. This somehow coincides with the disadvantages of ETL modelling we mentioned in Section 9.3. ETL modelling is not very suitable for multi-agent cases with higher order uncertainty.

---

\[16\] Important security properties are generally undecidable if there are no restrictions on the number of messages and nonces, for example, cf. [DLMS99] for the undecidability for secrecy. A solution is to focus on decidable subclasses as in e.g. [RS05a].
On the other hand, although multi-agent cases are often undecidable in general, we can still have some hope by restricting ourselves to certain classes where equivalence relations of agents have certain patterns (e.g. \[EVDMS02\]). Moreover, some model checking techniques such as abstraction and symmetry reduction that are specific to ETL or DEL can be found in \[DOW08, CDLR09, CLDQ09\].

As a final note, in practice, the performance of an ETL model checking tool kit relies on the particular class of models to be checked and their representations, for example, model checking CTL+K against “compact models” is in PSPACE \[LR06a\].

9.5 Conclusion

In this chapter, we surveyed the epistemic approaches to security protocol verification with the questions: are security protocols essentially about knowledge (what is there to know?), how to model the different kinds of knowledge involved (how to know?), and does an epistemic approach bring benefits (why to know?). We first made the distinctions between different types of knowledge relevant in the security setting and then gave an overview of commonly used techniques in the epistemic approaches. In particular, we compared various equivalence relations defined in the literature that correspond to the semantics of propositional knowledge. We also compared two major epistemic logical approaches proposed to model interaction in multi-agent systems. It turns out that, in a setting of security protocol verification, ETL approaches are more suitable to model message passing over time, based on which appropriate equivalence relations can be generated. On the other hand, the DEL approach offers more freedom to model higher order information and uncertainties in terms of agents’ knowledge about each other as we demonstrated in Part I of this thesis. The model checking results of ETL also confirm that it is better to focus on a single agent case: in the security setting, this would be the intruder. Finally, we collected clues for the comparison of the expressivity of ETL and TL, in order to see when an epistemic approach is inevitable. We showed under the assumption of synchronicity, that ETL can define more (security) properties of the temporal structures.