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Published in:
Astrophysical Journal

DOI:
10.1088/0004-637X/750/2/161

Link to publication

Citation for published version (APA):

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Download date: 04 Aug 2019
THE MISSING CAVITIES IN THE SEEDS POLARIZED SCATTERED LIGHT IMAGES OF TRANSITIONAL PROTOPLANETARY DISKS: A GENERIC DISK MODEL


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28 Received 2012 February 7; accepted 2012 March 7; published 2012 April 26

ABSTRACT

Transitional circumstellar disks around young stellar objects have a distinctive infrared deficit around 10 μm in their spectral energy distributions, recently measured by the Spitzer Infrared Spectrograph (IRS), suggesting dust depletion in the inner regions. These disks have been confirmed to have giant central cavities by imaging of the submillimeter continuum emission using the Submillimeter Array (SMA). However, the polarized near-infrared scattered light images for most objects in a systematic IRS/SMA cross sample, obtained by HiCIAO on the Subaru telescope, show no evidence for the cavity, in clear contrast with SMA and Spitzer observations. Radiative transfer modeling indicates that many of these scattered light images are consistent with a smooth spatial distribution for μm-sized grains, with little discontinuity in the surface density of the μm-sized grains at the cavity edge. Here we present a generic disk model that can simultaneously account for the general features in IRS, SMA, and Subaru observations. Particularly, the scattered light images for this model are computed, which agree with the general trend seen in Subaru data. Decoupling between the spatial distributions of the μm-sized dust and mm-sized dust inside the cavity is suggested by the model, which, if confirmed, necessitates a mechanism, such as dust filtration, for differentiating the small and big dust in the cavity clearing process. Our model also suggests an inwardly increasing gas-to-dust ratio in the inner disk, and different spatial distributions for the small dust inside and outside the cavity, echoing the predictions in grain coagulation and growth models.

Key words: circumstellar matter – protoplanetary disks – radiative transfer – stars: pre-main sequence

1. INTRODUCTION

Transitional disks have a small or no excess from ~1 μm to ~10 μm relative to their full disk cousins, but a significant excess at longer wavelengths (Williams & Cieza 2011), suggesting a cleared out inner disk. This interpretation dates back to the era of the Infrared Astronomical Satellite (Strom et al. 1989; Skrutskie et al. 1990), and was later developed with the help of detailed near-infrared (NIR) to mid-infrared (MIR) spectra provided by the Infrared Spectrograph (IRS) on board the Spitzer Space Telescope. Detailed radiative transfer modeling suggests that this kind of spectral energy distribution (SED) is consistent...
with disk models that harbor a central (partially) depleted region (i.e., a cavity or a gap), while a “wall-like” structure at the outer edge of this region can be responsible for the abrupt rise of the SED at MIR (Calvet et al. 2005; Espaillat et al. 2007).29

The disk+cavity model based on SED-only fitting usually contains large uncertainties because the SED samples the emission from the whole disk: by tuning the ingredients in the fitting, one could fit the IRS SED with different models (see the example of UX Tau A; Espaillat et al. 2010, 2011; Andrews et al. 2011, hereafter A11). Better constraints on the disk structure can be obtained from resolved images of the transitional disks. Using the Submillimeter Array (SMA) interferometer (Ho et al. 2004), resolved images of transitional disks at submillimeter (sub-mm) wavelength have provided direct detections of these cavities (Andrews & Williams 2007; Andrews et al. 2009), and measurements of their properties. Recently, A11 observed a sample of 12 nearby transitional disks (at a typical distance of ∼140 pc). Combining both the SMA results and the SED, they fit detailed disk+cavity model for each object, and the cavity size (∼15–70 AU) is determined with ∼10% uncertainty. They concluded that large grains (up to ∼mm-sized) inside the cavity are depleted by at least a factor of 10–100 (the “depletion” in this work is relative to a “background” value extrapolated from the outer disk). Under the assumption that the surface density of the disk is described by their model, the infrared spectral fitting demands that the small grains (μm-sized and smaller) inside the cavity be heavily depleted by a factor of ∼105.

Recently, most objects in this sample have been observed by the Subaru High-Contrast Coronographic Imager for Adaptive Optics (HiCIAO) at NIR bands, as part of the Strategic ExploRations of Exoplanets and Disks with Subaru (SEEDS) project (Tamura 2009). SEEDS is capable of producing polarized intensity (PI) images of disks, which greatly enhances our ability to probe disk structure (especially at the inner part) by utilizing the fact that the central source is usually not polarized, so that the stellar residual in PI images is much smaller than in full intensity (FI) images (Perrin et al. 2004; Hinkley et al. 2009; Quanz et al. 2011). The SEEDS results turned out to be a big surprise—in many cases the polarized NIR images do not show an inner cavity, despite the fact that the inner working angle of the images (the saturation radius or the coronagraph mask size, ψin ∼ 0′′1–0′′15, or ∼15–25 AU at the distance to Taurus ∼140 pc, see Section 2.3) is significantly smaller than the cavity sizes inferred from sub-mm observations. High contrast features such as surface brightness excesses or deficits exist in some systems, but they are localized and do not appear to be central cavities. Instead, the image is smooth on large scales, and the azimuthally averaged surface brightness radial profile (or the profile along the major axis) increases inward smoothly until ψin, without any abrupt break or jump at the cavity edge (the slope may change with radius in some systems). Examples include ROX 44 (M. Kuzuhara et al. 2012, in preparation), SR 21 (K. Follette et al. 2012, in preparation), GM Aur (J. Hashimoto et al. 2012a, in preparation), and SAO 206462 (Muto et al. 2012; see also the sample statistics (J. Hashimoto et al. 2012b, in preparation). Some objects such as UX Tau A also do not show a cavity (R. Tanii et al. 2012, in preparation), however the inner working angle of their SEEDS images is too close to the cavity size, so the status of the cavity is less certain. We note that LkCa 15 also does not exhibit a clear cavity in its PI imagery (J. Wisniewski et al. 2012, in preparation), but does exhibit evidence of the wall of a cavity in its FI imagery (Thalmann et al. 2010).

This apparent inconsistency between observations at different wavelengths reveals something fundamental in the transitional disk structure, as these data sets probe different components of protoplanetary disks. At short wavelengths (i.e., NIR) where the disk is optically thick, the flux is dominated by the small dust (μm-sized or so) at the surface of the disk (where the stellar photons get absorbed or scattered), and is sensitive to the shape of the surface; at long wavelength (i.e., sub-mm), disks are generally optically thin, so the flux essentially probes the disk surface density in big grains (millimeter (mm) sized or so), due to their large opacity at these wavelengths (Williams & Cieza 2011).

Combining all the three pieces of the puzzle together (SED, sub-mm observation, and NIR imaging), we propose a disk model that explains the signatures in all three observations simultaneously: The key point is that the spatial distributions of small and big dust are decoupled inside the cavity. In this model, a well-defined cavity (several tens of AU in radius) with a sharp edge exists only in spatial distribution of the big dust and reproduces the central void in the sub-mm images, while no discontinuity is found for the spatial distribution of the small dust at the cavity edge. Inside the cavity, the surface density of the small dust does not increase inwardly as steeply as it does in the outer disk; instead it is roughly constant or declines closer to the star (while maintaining an overall smooth profile). In this way, the inner region (sub-AU to a few AU) is heavily depleted in small dust, so that the model reproduces the NIR flux deficit in the SED (but still enough small dust surface density to efficiently scatter near-IR radiation). Modeling results show that the scattered light images for this continuous spatial distribution of the small dust appear smooth as well, with surface brightness steadily increasing inwardly, as seen in many of the SEEDS observations.

The structure of this paper is as follows. In Section 2 we introduce the method that we use for the radiative transfer modeling. In Section 3 we give the main results on the scattered light images: First a general interpretation of the big picture through a theoretical perspective, followed by the modeling results of various disk+cavity models. We investigate the sub-mm properties of these models in Section 4, and explore the degeneracy in the disk parameter space on their model SED in Section 5. We summarize the direct constraints put by the three observations on this transitional disk sample in Section 6, as well as the implications of our disk models. Our generic solution, which qualitatively explains the signatures in all the three observations, is summarized in Section 7.

2. RADIATIVE TRANSFER MODELING

In this section, we introduce the model setup in our radiative transfer calculations, and the post processing of the raw NIR polarized scattered light images that we perform in order to mimic the observations. The purpose of this modeling exercise is to “translate” various physical disk models to their corresponding NIR polarized scattered light images, sub-mm emission images, and SED, for comparison with observations.

2.1. Model Setup

We use a modified version of the Monte Carlo radiative transfer code developed by Whitney et al. (2003a, 2003b), Robitaille
not detectable in SEEDS

cretion under the accretion rate assumed in our models below

populations are taken to be Gaussian (i.e., $\alpha$

and B. Whitney et al. 2012, in preparation; for the

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the dust sublimation radius $R_{\text{sub}}$ in this work). The big grains contain 85% of the dust mass outside the cavity, and are completely absent inside. The thick curves at $R < R_{\text{cav}}$ in the left panel indicate three different $\Sigma_i$ (rising, flat, and declining, as Equations (2)-(4), with names indicating their behavior when moving inward inside the cavity) for the small dust, all continuous at the cavity edge ($\delta_{\text{sub}} = 1$). The bottom thin dashed curve illustrates the surface density profile in typical A11 models, which have a uniformly heavily depleted cavity with $\delta_i \approx 10^{-5}$, and the thin solid curve represents a slight small-grain depletion at the cavity edge ($\delta_{\text{sub}} = 0.3$) with a flat $\Sigma_i$. The vertical dotted curves indicate the cavity edge and typical SEEDS inner working angle ($\sim 0.1$–0.15 AU or $\sim 15$–20 AU at Taurus). The labels on the axes are for Sections 3 and 4.

et al. (2006), and B. Whitney et al. 2012, in preparation; for the disk structure, we use A11 and Whitney et al. (2003a) for references. The NIR images (this section) and SED (Section 5) are produced from simulations with $4 \times 10^{10}$ photon packets, and for the sub-mm images (Section 4) we use $5 \times 10^{10}$ photon packets. By varying the random seeds in the Monte Carlo simulations, we find the noise levels in both the radial profile of the convolved images (Section 2.3) and the SED to be $\lesssim 0.5\%$ in the range of interest. In our models, we construct an axiymmetric disk (assumed to be at $\sim 140$ pc) 200 AU in radius on a $600 \times 200$ grid in spherical coordinates ($R, \theta$), where $R$ is in the radial direction and $\theta$ is in the poloidal direction ($\theta = 0^\circ$ is the disk mid-plane). We include accretion energy in the disk using the Shakura & Sunyaev $\alpha$ disk prescription (Whitney et al. 2003b). Disk accretion under the accretion rate assumed in our models below (several $\times 10^{-9} M_\odot$ yr$^{-1}$) does not have a significant effect on the SED or the images (for simplicity, accretion energy from the inner gas disk is assumed to be emitted with the stellar spectrum, but see also the treatment in Akeson et al. 2005). We model the entire disk with two components: a thick disk with small grains ($\sim \mu\text{m-sized}$ and smaller, more of less pristine), and a thin disk with large (grown and settled) grains (up to $\sim$mm-sized). Figure 1 shows the schematic surface density profile for both dust populations.

The parameterized vertical density profiles for both dust populations are taken to be Gaussian (i.e., $\rho(z) = \rho_0 e^{-z^2/2h^2}$, isothermal in the vertical direction $z$), with scale heights $h_s$ and $h_b$ being simple power laws $h \propto R^\beta$ (we use subscripts “s” and “b” to indicate the small and big dust throughout the paper, while quantities without subscripts “s” and “b” are for both dust populations). Following A11, to qualitatively account for the possibility of settling of big grains, we fix $h_b = 0.2 \times h_s$ in most cases to simplify the models, unless indicated otherwise. Radially the disk is divided into two regions: an outer full disk from a cavity edge $R_{\text{cav}}$ to 200 AU, and an inner cavity from the dust sublimation radius $R_{\text{sub}}$ to $R_{\text{cav}}$ ($R_{\text{sub}}$ is determined self-consistently as the radius at which the temperature reaches the sublimation temperature $T_{\text{sub}} \sim 1600\text{ K}$; Dullemond et al. 2001; usually around 0.1–0.2 AU). At places in the disk where a large surface area of material is directly exposed to starlight, a thin layer of material is superheated, and the local disk “puffs” up vertically (Dullemond & Dominik 2004a). To study this effect at the inner rim ($R_{\text{sub}}$) or at the cavity wall, we adopt a treatment similar to A11. In some models below we manually raise the scale height $h$ at $R_{\text{sub}}$ or $R_{\text{cav}}$ by a certain factor from its “original” value, and let the puffed up $h$ fall back to the underlying power-law profile of $h$ within $\sim 0.1$ AU as $e^{-3h/0.1\text{AU}}^2$. We note that these puffed up walls are vertical, which may not be realistic (Isella & Natta 2005).

For the surface density profile in the outer disk, we assume

$$\Sigma_s(R) = \Sigma_{\text{cav}} \frac{R_{\text{cav}}}{R} e^{(R_{\text{cav}} - R)/R_{\text{cav}}},$$

where $\Sigma_{\text{cav}}$ is the surface density at the cavity edge (normalized by the total disk mass), $R_{\text{cav}}$ is a characteristic scaling length, and the gas-to-dust ratio is fixed at 100. Following A11, we take 85% of the dust mass to be in large grains at $R > R_{\text{cav}}$. For the inner disk (i.e., $R < R_{\text{cav}}$) three surface density profiles have been explored:

$$\Sigma_s(R) = (\delta_{\text{cav}} \Sigma_{\text{cav}}) \frac{R_{\text{cav}}}{R} e^{(R_{\text{cav}} - R)/R_{\text{cav}}} \quad \text{(rising $\Sigma_s(R)$),}$$

$$\Sigma_s(R) = \delta_{\text{cav}} \Sigma_{\text{cav}} \quad \text{(flat $\Sigma_s(R)$), and}$$

$$\Sigma_s(R) = (\delta_{\text{cav}} \Sigma_{\text{cav}}) \frac{R_{\text{cav}}}{R} \quad \text{(declining $\Sigma_s(R)$),}$$

and their names are based on their behavior when moving inward inside the cavity. We note that Equations (2) and (1) together form a single $\Sigma(R)$ scaling relation for the entire disk (with different normalization for the inner and outer parts), as in A11. We define the depletion factor of the total dust inside the cavity as

$$\delta(R) = \frac{\Sigma(R)}{\Sigma_{\text{full}}(R)},$$

where $\Sigma_{\text{full}}(R)$ is found by extrapolating $\Sigma_s(R)$ from the outer disk, i.e., evaluating Equation (1) at $R < R_{\text{cav}}$ (or Equation (2) with $\delta_{\text{cav}} = 1$). In addition, we define $\delta_s(R)$ and $\delta_b(R)$ as the
cavity depletion factors for the small and big dust, respectively, as
\[
\delta_s(R) = \frac{\Sigma_{i,s}(R)}{0.15 \times \Sigma_{\text{full}}(R)}, \quad \delta_b(R) = \frac{\Sigma_{i,b}(R)}{0.85 \times \Sigma_{\text{full}}(R)},
\]
where 0.15 and 0.85 are the mass fractions of the small and big dust in the outer disk. We note that unlike previous models such as A11, our cavity depletion factors are radius dependent (a constant \(\delta_s(R)\) or \(\delta_b(R)\) means a uniform depletion at all radii inside the cavity). Specifically, we define the depletion factor right inside the cavity edge as
\[
\delta_{\text{cav},s} = \delta_s(R = R_{\text{cav}} - \epsilon), \quad \delta_{\text{cav},s} = \delta_b(R = R_{\text{cav}} - \epsilon),
\]
\[
\delta_{\text{cav},b} = \delta_b(R = R_{\text{cav}} - \epsilon).
\]
With the same \(\delta_{\text{cav}}\), different models with different \(\Sigma_i(R)\) profiles (Equations (2)–(4)) have similar \(\Sigma_i(R)\) (and \(\delta(R)\)) in the outer part of the cavity, but very different \(\Sigma_i(R)\) (and \(\delta(R)\)) at the innermost part. Lastly, the mass-averaged cavity depletion factor \(\langle \delta \rangle\) is defined as
\[
\langle \delta \rangle = \frac{\int_{0}^{R_{\text{cav}}} \Sigma_i(R) 2\pi R dR}{\int_{0}^{R_{\text{cav}}} \Sigma_{\text{full}}(R) 2\pi R dR}.
\]

SMA observations have placed strong constraints on the spatial distribution of the big dust, while the constraints on the small grains from the SED are less certain, especially beyond \(R \sim 10\) AU. Based on this, we adopt the spatial distribution of big grains in A11 (i.e., Equation (1), and no big grains inside the cavity), and focus on the effect of the distribution of small grains inside the cavity. Therefore, the sub-mm properties of our models are similar to those of the models in A11 (Section 4), since large grains dominate the sub-mm emission. We tested models with non-zero depletion for the big grains, and found that they make no significant difference as long as their surface density is below the SMA upper limit. Here on we drop the explicit radius dependence indicator \(R\) from various quantities in most cases for simplicity.

2.2 Dust Properties

For the small grains we try two models: the standard interstellar medium (ISM) grains (Kim et al. 1994; \(\sim\mu m\)-sized and smaller), and the model that Cotera et al. (2001) employed to reproduce the HH 30 NIR scattered light images, which are somewhat larger than the ISM grains (maxim size \(\sim 20\mu m\)). These grains contain silicate, graphite, and amorphous carbon, and their properties are plotted in Figure 2. The two grain models are similar to each other, and both are similar to the small grains model that A11 used in the outer disk and the cavity grains that A11 used inside the cavity and on the cavity wall. We note that for detailed modeling which aims at fitting specific objects, the model for the small grains needs to be turned for each individual object. For example, the strength and shape of the silicate features indicate different conditions for the small grains in the

\begin{figure}
\centering
\includegraphics[width=\textwidth]{figure2}
\caption{Dust properties of the grain models we use, showing opacity \(\kappa\) (a), albedo \(\omega\) (b), average cosine scattering angle \(g\) (c), and maximum polarization \(P_l\) (d) (which typically occurs at a 90° scattering angle). The opacity is the dust+gas opacity assuming a gas-to-dust ratio of 100. Thick curves are for the small dust models, which dominate the scattered light due to their large-scale height and NIR opacity. Thin curves are for the big dust models, which dominate the sub-mm emission due to their high opacity at these wavelengths. The solid curves are the fiducial choices in this work.}
\end{figure}
inner disk (Adame et al. 2011 and Furlan et al. 2011, who also pointed out that the silicate features in transitional disks typically show that the grains in the inner disk are dominated by small amorphous silicate grains similar to ISM grains). However, since we do not aim at fitting specific objects, we avoid tuning the small dust properties and assume ISM grains (Kim et al. 1994) for the models shown below, to keep our models generalized and simple.

For the large grains we try three different models, namely, Models 1, 2, and 3 from Wood et al. (2002). The properties of these models are plotted in Figure 2. They adopt a power-law size distribution (i.e., as in Kim et al. 1994) with an exponential cutoff at large size, and the max size is \( \psi 1 \) mm. These grains are made of amorphous carbon and astronomical silicates, with solar abundances of carbon and silicon. These models cover a large parameter space, however we find that they hardly make any difference in the scattered light image and the IRS SED, due to their small-scale height and their absence inside the cavity. For this reason we fix our big grains as described by Model 2 in Wood et al. (2002, which is similar to the model of the big grains in A11). We note that small grains have much larger opacity than big grains at NIR, and it is the other way around at sub-mm (Figure 2).

2.3. Post Processing of the Scattered Light Images

To obtain realistic images that can be directly compared to SEEDS observations, the raw NIR images of the entire disk+star system from the radiative transfer simulations need to be convolved with the point-spread function (PSF) of the instrument. SEEDS can obtain both the FI and the PI images for any object, either with or without a coronagraph mask. The observation could be conducted in several different observational modes, including angular differential imaging (ADI; Marois et al. 2006), polarization differential imaging (PDI; Hinkley et al. 2009), and spectral differential imaging (SDI; Marois et al. 2000). For a description of the instrument, see Tamura (2009) and Suzuki et al. (2010).

In this work, we produce both the narrowband 880 µm images and H-band NIR images. While at 880 µm, we produce the FI images, for the NIR scattered light images we focus on the PI images (produced in the PDI mode, both with and without a coronagraph mask). This is because (1) PDI is the dominate mode for this sample in SEEDS and (2) it is more difficult to interpret FI (ADI) images since its reduction process partially or completely subtracts azimuthally symmetric structure. Other authors had to synthesize and reduce model data in order to test for the existence of features like cavities (Thalmann et al. 2011). For examples of PDI data reduction and analysis, see Hashimoto et al. (2011). When observing with a mask, \( \psi_m \) in the PI images is the mask size (typically 0.15 in radius), and when observing without a mask, \( \psi_m \) is determined by the saturation radius, which typically is \( \sim 0.1 \).

To produce an image corresponding to observations made without a mask, we convolve the raw PI image of the entire system with an observed unsaturated HiCIAO H-band PSF. The resolution of the PSF is \( \sim 0.05 (\sim 1.2\arcsec / D \text{ for an 8 m telescope}) \) and the Strehl ratio is \( \sim 40\% \) (Suzuki et al. 2010). The integrated flux within a circle of radius 0.25 is \( \sim 80\% \) of the total flux (\( \sim 90\% \) for a circle of radius 0.5). We then carve out a circle at the center with 0.1 in radius to mimic the effect of saturation. We call this product the convolved unmasked PI image. To produce an image corresponding to observations with a mask, we first convolve the part of the raw PI image that is not blocked by the mask with the above PSF. We then convolve the central source by an observed PI coronagraph stellar residual map (the stellar PSF under the coronagraph), and add this stellar residual to the disk images (the flux from the inner part of the disk that is blocked by the mask, \( \sim 20 \text{AU at } \sim 140 \text{ pc, is added to the star} \)). Lastly, we carve out a circle 0.15 in radius from the center from the combined image to indicate the mask. We call this product the convolved masked PI image. We note that the stellar residual is needed to fully reproduce the observations, but in our sample the surface brightness of the stellar residual is generally well below the surface brightness of the disk at the radius of interest, so it does not affect the properties of the images much.

In this study, the disk is assumed to be face-on in order to minimize the effect of the phase function in the scattering, so that we can focus on the effect of the disk structure. This is a good approximation since most objects in this IRS SMA/Subaru sample have inclinations around \( \sim 25^\circ \) (i.e., minor to major axis ratio \( \sim 0.9 \); an observational bias toward face-on objects may exist, since they are better at revealing the cavity). Additional information about the scattering properties of the dust could be gained from analyzing the detailed azimuthal profile of the scattered light in each individual system, which we defer to the future studies. To calculate the azimuthally averaged surface brightness profiles, we bin the convolved images into a series of annuli 0.05 in width (the typical spatial resolution), and measure the mean flux within each annulus.

3. THE NIR POLARIZED SCATTERED LIGHT IMAGES

With the tools described above, we investigate what kinds of disk structure could simultaneously reproduce the gross properties of all three kinds of observations described in Section 1. In this section, we first investigate the properties of the scattered light images from a semi-analytical theoretical point of view (Section 3.1), then we present the model results from the Monte Carlo simulations (Section 3.2).

3.1. Theoretical Considerations

In a single NIR band, when the (inner) disk is optically thick (i.e., not heavily depleted of the small grains), the scattering of the starlight can be approximated as happening on a scattering surface \( z_s \) where the optical depth between the star and surface is unity (the single scattering approximation). This surface is determined by both the disk scale height (particularly \( \beta \) in the simple vertically isothermal models), and the radial profile of the surface density of the grains. The surface brightness of the scattered light \( I_{\text{scat}}(R) \) scales with radius as (Jang-Condell & Sasselov 2003; Inoue et al. 2008)

\[
I_{\text{scat}}(R) \sim \zeta \rho \frac{L_*}{4\pi R^2} \sin \gamma, 
\]

where \( L_* \) is the stellar luminosity at this wavelength, \( \zeta \) is a geometrical scattering factor, \( \rho \) is the polarization coefficient for PI (\( p = 1 \) for FI), and \( \gamma \) is the grazing angle (the angle between the impinging stellar radiation and the tangent of the scattering surface). We note that both \( \zeta \) and \( p \) depend on azimuthal angle, inclination of the disk, and the scattering properties of the specific dust population responsible for scattering at the particular wavelength. However, if the disk is relatively face-on and not too flared, they are nearly position independent, because the scattering angle is nearly a constant throughout the disk and
the dust properties of the specific dust population do not change much with radius. The grazing angle is determined by the curvature of the scattering surface. In axisymmetric disks, assuming the surface density and scale height of the small dust to be smooth functions of radius, the grazing angle is also smooth with radius, and two extreme conditions can be constrained as follows.

1. For disks whose scattering surface is defined by a constant poloidal angle $\theta$ (such as a constant opening angle disk), $\gamma \sim R_s/R$ (Chiang & Goldreich 1997; where $R_s$ is the radius of the star), so the brightness of the scattered light scales with $R$ as

$$I_{\text{scat}}(R) \propto R^{-3}. \quad (10)$$

2. For flared disks (but not too flared, $h \lesssim R$), the grazing angle can be well approximated as

$$\sin \gamma \sim \gamma \sim \frac{dz_s}{dR} \sim \frac{z_s}{R}. \quad (11)$$

In this case, Muto (2011) explicitly calculated the position of the scattering surface $z_s$ at various radii (see also Chiang & Goldreich 1997), and found $z_s = \eta h_s$, where the coefficient $\eta$ is a few and is nearly a constant. Combined with the fact that $h_s/R \propto R^{\beta-1}$ ($\beta \sim 1.25$–1.3 as typical values in irradiated disks; Chiang & Goldreich 1997; Hartmann et al. 1998), we have the intensity of the scattered light scales with radius as

$$I_{\text{scat}}(R) \propto R^{\beta-3}. \quad (12)$$

Although the above calculations are under two extreme conditions (for complete flat or flared disks), and they are based on certain assumptions and the observed images have been smeared out by the instrument PSF, the radial profiles (azimuthally averaged, or along the major axis in inclined systems) of SEEDS scattered light images for many objects in this sample lie between Equations (10) and (12) in the radius range of interest. In order to guide the eye and ease the comparison between modeling results and observations, we use the scaling relation

$$I_{\text{scat}}(R) \propto R^{-2.5} \quad (13)$$

to represent typical observational results, and plot it on top of the radiative transfer results, which will be presented in Section 3.2 (with arbitrary normalization).

On the other hand, an abrupt jump in the surface density or scale height profile of the small dust in the disk produces a jump in $\gamma$ at the corresponding position. The effect of this jump will be explored in Section 3.2.

### 3.2. Modeling Results

First, we present the simulated $H$-band PI images for a face-on transitional disk with a uniformly heavily depleted cavity with $\Sigma_c$ as Equation (2) (Figure 3), and the associated surface brightness radial profiles (the thick solid curves in Figure 4). In each figure, the three panels show the raw image, the convolved masked image, and the convolved masked image, respectively. This model is motivated by the disk+cavity models in A11; we therefore use parameters typical of those models. Experiments show that the peculiarities in each individual A11 disk model hardly affect the qualitative properties of the images and their radial profiles, as long as the cavity is large enough ($\gtrsim 0\arcsec 2$) and the disk is relatively face-on.

This disk harbors a giant cavity at its center with $R_{\text{cav}} = 42$ AU ($\sim 0\arcsec 3$ at 140 pc). The disk has the same inwardly rising $\Sigma$ scaling both inside and outside the cavity as Equations (1) and (2). Outside the cavity both dust populations exist, with the big/small ratio as 0.85/0.15. Inside the cavity there is no big dust ($\delta_b = 0$), and the small dust is uniformly heavily depleted to $\delta_s = \delta_{\text{cav},s} \sim 10^{-5}$ ($\delta \sim 10^{-6}$). The surface density profiles for both dust populations can be found in Figure 1. The disk has total mass of $0.01 M_\odot$ (gas-to-dust mass ratio 100), $h/R = 0.075$ at 100 AU with $\beta = 1.15$, $R_c = 40$ AU, and accretion rate $M = 5 \times 10^{-9} M_\odot \text{yr}^{-1}$. The central source is a 3 $R_\odot$, 2 $M_\odot$, 5750 K G3 pre-main-sequence star. We puff up the inner rim and the cavity wall by 100% and 200%, respectively.

The most prominent features of this model in both the un-masked and masked PI images are the bright ring at $R_{\text{cav}}$, and the surface brightness deficit inside the ring (i.e., the cavity). Correspondingly, the surface brightness profile increases inwardly in the outer disk, peaks around $R_{\text{cav}}$, and then decreases sharply. This is very different from many SEEDS results (such as the examples mentioned in Section 1), in which both the bright ring and the inner deficit are absent, and the surface brightness radial profile keeps increasing smoothly all the way from the outer disk to the inner working angle, as illustrated by the scaling relation (Equation (13)) in Figure 4.

This striking difference between models and observations suggests that the small dust cannot have such a large depletion at the cavity edge. Figure 4 shows the effect of uniformly filling the cavity with small dust on the radial profile for unmasked...
images (left) and masked images (right), leaving the other model parameters fixed. As \( \delta_i \) gradually increases from \( \sim 10^{-5} \) to 1, the deviation in the general shape between models and observations decreases. The \( \delta_i = 1 \) model corresponds to no depletion for small grains inside the cavity (i.e., a full small dust disk); this model agrees much better with the scattered light observations, despite a bump around the cavity edge produced by its puffed up wall (Section 3.2.3), although this model fails to reproduce the superimposed seeing halo from the bright innermost disk (especially for the unmasked images).

In the rest of Section 3 we focus on the small grains inside the cavity while keeping the big grains absent, and study the effect of the parameters \( \Sigma_i \), \( \delta_{\text{cav,s}} \), and the puffing up of the inner rim and cavity wall on the scattered light images. The convolved images for three representative models are shown in Figure 5, and the radial profiles for all models are shown in Figure 6. Each model below is varied from one standard model, which is shown as the top panel in Figure 5 and represented by the thick solid curves in all panels in Figure 6. This fiducial model has a flat \( \Sigma \) with no discontinuity at the cavity edge for the small dust (i.e., \( \delta_{\text{cav,s}} = 1 \)), and no puffed up rim or wall, but otherwise identical parameters to the models above.

### 3.2.1. The Effect of \( \Sigma_i \)

First we study the effect of three surface density profiles inside the cavity, namely, rising (Equation (2)), flat (Equation (3)), and declining \( \Sigma \) (Equation (4)). The surface densities for these models are illustrated in Figure 1. Panel (a) in Figure 6 shows the effect of varying the surface density on the image radial profiles. Except for shifting the entire curve up and down, different \( \Sigma \) produce qualitatively very similar images and radial profiles, and all contain the gross features in many SEEDS observations (illustrated by the scaling relation (13)). This is due to both the fact that smooth surface density and scale height profiles yield a smooth scattering surface, and the effect of the PSF. We note...
that there is some coronagraph edge effect at the inner working angle in the masked images, which is caused by that the part of the disk just outside (but not inside) the mask is convolved with the PSF. This results in a narrow ring of flux deficit just outside the mask. In general, the flux is trustable beyond about one FWHM of the PSF from $\psi_{\text{in}}$ ($\sim 0.05 + 0.15 = 0.2$) (Muto et al. 2012; some instrumental effects in observations may also affect the image quality within one FWHM from the mask edge as well).

### 3.2.2. The Effect of $\delta_{\text{cav},s}$

We investigate the effect of different $\delta_{\text{cav},s}$ with flat $\Sigma_i$ (Equation (3)). Panel (b) in Figures 6 shows the effect on the radial profile of the convolved images. When deviating from the fiducial model with $\delta_{\text{cav},s} = 1$ (i.e., a continuous small dust disk at $R_{\text{cav}}$), a bump around the cavity edge and a surface brightness deficit inside the cavity gradually emerge. We quantify this effect by measuring the relative flux deficit at $0.2'' ((2/3) R_{\text{cav}})$ as a function of $\delta_{\text{cav},s}$, the small dust discontinuity at the cavity edge (subpanel in each plot). For each model we calculate the ratio of the flux at $0.2'', f_{0.2}$, to $f_{0.6}$, the flux at $0.6'' (= 2 R_{\text{cav}})$, normalized by $f_{0.2}/f_{0.6}$ in the fiducial, undepleted model. For the model with a $50\%$ discontinuity in $\Sigma_i$ at $R_{\text{cav}}$ ($\delta_{\text{cav},s} = 0.5$), $f_{0.2}/f_{0.6}$ is $\sim 15\%$ lower than in the fiducial model in the convolved unmasked images, and $\sim 20\%$ lower in the convolved masked images. The latter is larger because the mask suppresses the halo of the innermost disk, thus the relative flux deficit in the masked image is closer to its intrinsic value, i.e., the deficit in the raw images. In this sense the masked images are better at constraining the discontinuity of the small dust than the unmasked images. The middle row in Figure 5 shows the model images for $\delta_{\text{cav},s} = 0.3$ (illustrated by the thin solid curve in Figure 1). The edge of the cavity is quite prominent in the raw image, while it is somewhat smeared out but still visible in the convolved images. For many objects in this IRS/SMA/Subaru cross sample, the SEEDS images are grossly consistent with a continuous small dust disk at the $R_{\text{cav}}$, while in some cases a small discontinuity may be tolerated.

For the purpose of comparison with the observations, we now discuss the detectability of a finite surface density discontinuity at the cavity edge, given the sensitivity and noise level of the SEEDS data (the numerical noise level in our simulations is well below the noise level in the observations, see Section 2.1). In typical SEEDS observations with an integration time of several hundred seconds, the intrinsic Poisson noise of the surface brightness radial profile due to finite photon counts is usually a few tenths of $1\%$ at radius of interests, smaller than the error introduced by the instrument and the data reduction process. Muto et al. (2012) estimated the local noise level of the surface brightness to be $\sim 10\%$ at $R = 0.5$ for the SEEDS SAO 206462 PI images, which should be an upper limit for the noise level in the azimuthally averaged surface brightness (more pixels) and in the inner region of the images (brighter). If this is the typical value for the instrument, then our modeling results indicate that...
Figure 6. Surface brightness radial profiles of the convolved unmasked (left) and masked (right) PI images for the models in Section 3.2, showing the effect of $\Sigma_i$ (a), $\delta_{\text{cav},s}$ (b), and the puffed up inner rim and cavity wall (c). The subpanel in panel (b) shows the relative flux deficit at 0.2" ($i/3 R_{\text{cav}}$) as a function of $\delta_{\text{cav},s}$ (Section 3.2.2). All models have no big dust inside the cavity. The curves labeled “fiducial” are the same in all panels, which is from a model with flat $\Sigma_i$, a continuous small dust surface density profile ($\delta_{\text{cav},s} = 1$), and no puffed up cavity wall (the top row in Figure 5). Results show that both a modest depletion in the small grains at $R_{\text{cav}}$ and a puffed up cavity wall can add a bump to the originally smooth radial profile, while various forms of $\Sigma_i$ with no discontinuity at $R_{\text{cav}}$ produce similar surface brightness radial profile. Typical SEEDS results, as summarized in Section 1 and illustrated by the scaling relation (13) (with arbitrary normalization), are consistent with smooth small dust disks continuous in both surface density and scale height. The apparent inward surface brightness decrease near $\psi_{\text{in}}$ in the masked images is a coronagraph edge effect (Section 3.2.1).
SEEDS surface brightness measurements should be able to put relatively tight constraints on the surface density discontinuity for the small dust at $R_{\text{cav}}$. For example, SEEDS should be able to distinguish a disk of small dust continuous at $R_{\text{cav}}$ from a disk of small dust with a 50% density drop at $R_{\text{cav}}$.

Thus, a lower limit on the small dust depletion factor at the cavity edge can be deduced from detailed modeling for each individual object. This lower limit is likely to be higher than the upper limit from SMA on the depletion factor of the big dust ($\lesssim 0.1$–0.01), for objects with relatively smooth radial profiles. If this is confirmed for some objects in which the two limits are both well determined, it means that the density distribution of the small dust needs to somehow decouple from the big dust at the cavity edge. We will come back to this point in Section 6.

3.2.3. The Effect of the Puffed Up Inner Rim and Cavity Wall

Lastly, we explore the effects of the puffed up inner rim and the cavity wall on the images, by comparing the fiducial model (no puffing up anywhere) to a model with the inner rim puffed up by 100%, and another model with the cavity wall puffed up by 200%. Panel (c) in Figure 6 shows the effects. Puffing up the inner rim has little effect on the image, while the puffed up wall produces a bump at the cavity edge, similar to the effect of a gap edge. Images for the model with the puffed up wall are shown in Figure 5 (bottom row), where the wall is prominent in the raw image while it been somewhat smeared out but still visible in the convolved images. Scattered light images should be able to constrain the wall for individual objects. Without digging deeply into this issue, we simply note here that the SEEDS images for many objects in this sample are consistent with no or only a small puffed up wall.

4. THE SUB-MM PROPERTIES AND IMAGES

4.1. The Sub-mm Intensity Profile

For all models shown in Section 3, the disk is optically thin in the vertical direction at 880 $\mu$m ($\tau \sim \Sigma_{\nu} \lesssim 1$, where $\kappa_{\nu}$ is the opacity per gram at $\nu$). In this case, the intensity $I_{\nu}(R)$ at the surface of the disk at a given radius may be expressed as

$$I_{\nu}(R) \approx \int_{\infty}^{\tilde{z}} \left( B_{\nu,T(z)} \kappa_{\nu,b} \rho(z) + B_{\nu,T(z)} \kappa_{\nu,s} \rho_{s}(z) \right) dz,$$

(14)

where $\nu = 341$ GHz at 880 $\mu$m, $B_{\nu,T(z)}$ is the Planck function at $T(z)$ (the temperature at $z$), and $\rho(z)$ is the vertical density distribution ($T$ and $\rho$ depend on $R$ as well). Outside the cavity, the big dust dominates the 880 $\mu$m emission, since the big dust is much more efficient at emitting at $\sim 880$ $\mu$m than the small dust ($\kappa_{\nu,b}/\kappa_{\nu,s} \gtrsim 30$ at these wavelengths). Inside the cavity there is no big dust by our assumption, so the sub-mm emission comes only from the small dust. The thick curves in Figure 7 show the 880 $\mu$m intensity as a function of radius for the models in Section 3.2.2.1 (i.e., continuous small dust disks with rising, flat, or declining $\Sigma_i$). In other words, this is an 880 $\mu$m version of the surface brightness radial profile for the “raw” image, without being processed by a synthesized beam dimension (the SMA version of the “PSF”). The bottom thin dashed curve is for the uniformly heavily depleted cavity model as in Figure 3 ($\delta_b = \delta_{\text{cav,b}} \sim 10^{-5}$, rising $\Sigma_i$) and no big dust inside the cavity, which represents the sub-mm behavior of the models for most systems in A11.

Since the disk is roughly isothermal in the vertical direction near the mid-plane where most dust lies (Chiang & Goldreich 1997), $T(z)$ may be approximated by the mid-plane temperature $T_{\text{mid}}$. The Planck function can be approximated as $B_{\nu,T} \approx 2\nu^2kT/e^2$ at this wavelength due to $h\nu \ll kT$ (880 $\mu$m $\sim 16$ K, marginally true in the very outer part of the disk). In addition, since the two dust populations have roughly the same mid-plane temperature, but very different opacities ($\kappa_{\nu,b} \gg \kappa_{\nu,s}$), Equation (14) can be simplified to $I_{\nu}(R) \propto T_{\text{mid}}^{b} \Sigma_{b}^{b}$ for $R > R_{\text{cav}}$ and $I_{\nu}(R) \propto T_{\text{mid}}^{s} \Sigma_{i}^{s}$ for $R < R_{\text{cav}}$. For our continuous small disk models with a complete cavity for the big dust, the intensity at 880 $\mu$m drops by $\sim 2.5$ orders of magnitude when moving from outside (inside $(R_{\text{cav}} + \epsilon)$) to inside $(R_{\text{cav}} - \epsilon)$ the cavity edge, due to both the higher opacity of the big dust and the fact that big dust dominates the mass at $R > R_{\text{cav}}$. Inside the cavity, the intensity (now exclusively from the small dust) is determined by the factor $T_{\text{mid}}^{s} \Sigma_{i}$. For an irradiated disk $T_{\text{mid}}$ increases inwardly, typically as $T_{\text{mid}} \propto R^{-1/2}$ (Chiang & Goldreich 1997), while $\Sigma_i$ in our models could have various radial dependencies (Eqs. (2)–(4)). In the flat $\Sigma_i$ models (Equation (3)), the intensity inside the cavity roughly scales with $R$ as $I_{\nu}(R) \propto R^{-1/2}$–the same as $(T_{\text{mid}}(R))$–and is 1.5 orders of magnitude lower than $I_{\nu}(R_{\text{cav}}+\epsilon)$ in the innermost disk (around the sublimation radius). On the other hand, if there is no depletion of the small dust anywhere inside the cavity (i.e., the rising $\Sigma_i$ with $\delta_b = 1$ case), the intensity at the center (thick dashed curve) can exceed $I_{\nu}(R_{\text{cav}}+\epsilon)$ by two orders of magnitude.

In A11, for 880 $\mu$m images of models with no big dust inside the cavity, the residual emission near the disk center roughly traces the quantity $T_{\text{mid}}^{s} \Sigma_i^{s}$. In most cases, A11 found those residuals to be below the noise floor. Due to the sensitivity limit, the constraint on $T_{\text{mid}}^{s} \Sigma_i^{s}$ inside the cavity is relatively weak; nevertheless, A11 were able to put an upper limit equivalent to $\delta_b \lesssim 0.01$–0.1 for the mm-sized dust (with exceptions such...
as LkCa 15). Here we use a mock disk model to mimic this constraint. The top thin dashed curve in Figure 7 is from a model with uniform depletion factors $\delta_i = \delta_s = 0.01$ for \textit{both} dust populations inside the cavity (so the entire disk has the same dust composition everywhere). The result shows that, qualitatively, various models with a continuous small dust disk and a complete cavity for the big dust are all formally below this mock SMA limit, though a quantitative fitting of the visibility curve is needed to constrain $\delta_i$ and $\delta_{\text{cav,s}}$ in terms of upper limits, on an object by object basis. This may line up with another SED-based constraint on the amount of small dust in the innermost disk, as we will discuss in Section 5.

4.2. The 880 $\mu$m Images

While the intensity discussion qualitatively demonstrates the sub-mm properties of the disks, Figure 8 shows the narrowband images at 880 $\mu$m for two disk models. The top row is from the model which produces Figure 3 (also the bottom thin dashed curve in Figure 7 and the left panel in Figure 1), which is an A11 style model with a uniformly heavily depleted cavity with rising $\Sigma_i$, $\delta_i = \delta_{\text{cav,s}} \approx 10^{-5}$, and no big dust inside the cavity. The bottom row is from the fiducial model in Section 3.2 (which produces the top row in Figure 5, and the thick solid curve in Figure 7 and the left panel in Figure 1), which has a continuous distribution for the small dust with flat $\Sigma_i$ and $\delta_{\text{cav,s}} = 1$, and no big dust at $R < R_{\text{cav}}$, as well. The panels are the raw images from the radiative transfer simulations (left), images convolved by a Gaussian profile with resolution $\sim0.3$ (middle, to mimic the SMA observations; A11) and $\sim0.1$ (right, to mimic future Atacama Large Millimeter Array, ALMA, observations; Section 6.3).

Both models reproduce the characteristic features in the SMA images of this transitional disk sample: a bright ring at the cavity edge and a flux deficit inside agree with the semi-analytical analysis in Section 4.1, but they have \textit{very different} NIR scattered light images. The intrinsic reason for this apparent inconsistency is, as we discussed above, that big and small dust dominate the sub-mm and NIR signals in our models, respectively. Thus two disks can have similar images at one of the two wavelengths but very different images at the other, if they share similar spatial distributions for one of the dust populations but not the other.

Lastly, we comment on the effect of big-to-small dust ratio, which is fixed in this work as 0.85/0.15 to simplify the model (see the discussion of depletion of the small dust in the surface layer of protoplanetary disks; D’Alessio et al. 2006). The scattering comes from the disk surface and is determined by the grazing angle, which only weakly depends on the small dust surface density, if it is continuous and smooth (Section 3.2.1). Changing the mass fraction of the big dust in the outer disk from 0.85 to 0.95 in our $\delta_{\text{cav,s}} = 1$ models (effectively a factor of three drop in surface density of the small dust everywhere) introduces a $\sim20\%$ drop in the surface brightness of the scattered light images, but a factor of three drop in the cavity 880 $\mu$m intensity ($I_\nu(R) \propto \Sigma_i$ at $R < R_{\text{cav}}$). Lastly, we note that since the big-to-small dust sub-mm emission ratio is $\propto \kappa_{\nu,b} \Sigma_b / \kappa_{\nu,s} \Sigma_s$, the small grains must contain more than 90\% of the total dust mass to dominate the sub-mm emission.

5. THE TRANSITIONAL-DISK-LIKE SED

In this section, we explore the parameter degeneracy in reproducing the transitional-disk-like SED with their distinctive NIR–MIR dips. SED fitting (particularly of the IRS spectrum) can only provide constraints on the spatial distribution of the small dust within a few or a few tens AU from the center, and it contains strong degeneracy in the parameter space (A11). Below, we show that disk models with different cavity structures can produce roughly the same SED, containing the transitional disk signature, as long as their innermost parts are modestly...
depleted (by a factor of \(\sim 1000\) or so). Except for the specifically mentioned parameters, the other parameters of these models are the same as for the fiducial model in Section 3.2; in particular there is no big dust inside the cavity.

5.1. The Degeneracy in SED Fitting

Figure 9 shows the SED for four disk+cavity models. The uniformly heavily depleted model is motivated by A11, which has an inner cavity with \(\delta_i \sim 10^{-5}\), rising \(\Sigma_i\), and puffed up inner rim and cavity wall. The full small dust disk model (the thin dashed curve) has otherwise identical properties but with the small dust cavity being uniformly filled (\(\delta_i = 1\)). The other two smooth small dust disk models have \(\delta_{cav,s} = 1\) (no discontinuity at the cavity edge) and no puffed up inner rim or wall. See Section 5.1 for detailed parameters in these models. The three thick curves show the parameter degeneracy in producing the SED—diving to roughly the same depth at NIR and coming back to the same level at MIR, as the signature of transitional disks. The full small dust disk model shows that increasing surface density at small radii would eventually wipe out the distinctive deficit in the NIR, and the resulting SED gradually evolves to a full-disk-like SED.

The surface density (or the depletion factor) at the innermost part (from \(R_{\text{sub}}\) to \(\sim 1\) AU or so). While the two smooth small dust disk models differ by \(\sim 5\) orders of magnitude on the depletion factor (or the surface density) at the cavity edge from the uniformly heavily depleted model, the difference is much smaller at the innermost disk, where most of the NIR–MIR flux is produced. At the innermost disk, the small dust is depleted by \(\sim 3\) orders of magnitude in the flat \(\Sigma_i\) model, \(\sim 5\) orders of magnitude for the declining \(\Sigma_i\) model, and \(\sim 10^{-5}\) for the uniformly heavily depleted model (with rising \(\Sigma_i\)). On the other hand, the integrated depletion factor (\(\delta_i\)) for the small dust is \(\sim 0.3\) for the flat \(\Sigma_i\) model, \(\sim 0.2\) for the declining \(\Sigma_i\), and \(\sim 10^{-5}\) for the uniformly heavily depleted model, more in line with \(\delta_{cav,s}\), because most of the dust is at the outer part of the cavity. We note that the total amount of small dust is not as important as its spatial distribution inside the cavity, and the amount of dust in the innermost part, in determining the NIR–MIR SED.

1. The depletion factor (or the surface density) at the innermost part (from \(R_{\text{sub}}\) to \(\sim 1\) AU or so). While the two smooth small dust disk models differ by \(\sim 5\) orders of magnitude on the depletion factor (or the surface density) at the cavity edge from the uniformly heavily depleted model, the difference is much smaller at the innermost disk, where most of the NIR–MIR flux is produced. At the innermost disk, the small dust is depleted by \(\sim 3\) orders of magnitude in the flat \(\Sigma_i\) model, \(\sim 5\) orders of magnitude for the declining \(\Sigma_i\) model, and \(\sim 10^{-5}\) for the uniformly heavily depleted model, more in line with \(\delta_{cav,s}\), because most of the dust is at the outer part of the cavity. We note that the total amount of small dust is not as important as its spatial distribution inside the cavity, and the amount of dust in the innermost part, in determining the NIR–MIR SED.

2. The scale height of small grains \(h_s\) at the innermost part. The two smooth small dust disk models are more flared than the uniformly heavily depleted model. While the three have roughly the same scale height outside the cavity, the difference increases inward. At 1 AU, \(h_s\) for the uniformly heavily depleted model is \(1.7 \times \) that of the flat \(\Sigma_i\) model and \(2.4 \times\) that of the declining \(\Sigma_i\) model.

3. The puffed up inner rim. The inner rim scale height is doubled in the heavily depleted model, which increases the NIR flux and reduces the MIR flux since the puffed up rim receives more stellar radiation and shadows the disk behind it. The puffed up inner rim is removed in the flat or declining \(\Sigma_i\) models.

Figure 9. SED for four disk+cavity models. The uniformly heavily depleted model is motivated by A11, which has an inner cavity with \(\delta_i \sim 10^{-5}\), rising \(\Sigma_i\), and puffed up inner rim and cavity wall. The full small dust disk model (the thin dashed curve) has otherwise identical properties but with the small dust cavity being uniformly filled (\(\delta_i = 1\)). The other two smooth small dust disk models have \(\delta_{cav,s} = 1\) (no discontinuity at the cavity edge) and no puffed up inner rim or wall. See Section 5.1 for detailed parameters in these models. The three thick curves show the parameter degeneracy in producing the SED—diving to roughly the same depth at NIR and coming back to the same level at MIR, as the signature of transitional disks. The full small dust disk model shows that increasing surface density at small radii would eventually wipe out the distinctive deficit in the NIR, and the resulting SED gradually evolves to a full-disk-like SED.
5.2. Discussion of the Disk Model in Producing the SED

The inner rim is puffed up in A11 to intercept the starlight and to shadow material at larger radii. At a given radius, the scale height $h$ of the gas disk scales as

$$h \approx c_s / \Omega,$$  \hspace{1cm} (15)

where $\Omega$ is the orbital frequency and $c_s$ is the isothermal sound speed in the disk

$$c_s \approx \sqrt{kT/\mu},$$  \hspace{1cm} (16)

where $T$ is the (mid-plane) temperature and $\mu$ is the average weight of the particles. If the scale heights of the dust and the gas are well coupled (e.g., for well-mixed-gas-dust models or a constant level of dust settling), tripling the rim scale height (not unusual in A11) means an order of magnitude increase in its temperature. Due to the sudden change of the radial optical depth from $\sim 0$ to unity in a narrow transition region directly illuminated by the star, some puffing up may be present, but probably not that significant. In addition, Isella & Natta (2005) pointed out that a realistic puffed up rim has a curved edge (away from the star) instead of a straight vertical edge due to the dependence of $T_{\text{sub}}$ on pressure, which further limits the ability of the rim to shadow the outer disk. Based on these reasons, we choose not to have the rim puffed up in our models, though we note that a relatively weak puffing up, as in the uniformly heavily depleted model here, does not make a major difference in the results. A similar idea applies to the puffed up wall as well.

The typical $\beta$ value assumed in A11 in this sample ($\beta \sim 1.15$) is small compared with the canonical values for irradiated disk models ($\beta \sim 1.25$–1.3; Chiang & Goldreich 1997; Hartmann et al. 1998). Because of this, the temperature determined by the input scale height ($T_{\text{input}}$, Equations (15) and (16)) may increase inwardly too steeply compared with the output mid-plane temperature calculated in the code ($T_{\text{output}}$). $T_{\text{input}}$ at 100 AU in the three models are close to each other due to their similar scale height there, and all agree with $T_{\text{output}}$ ($\sim 30$ K) within 20%. However, at 1 AU, while $T_{\text{input}}$ in our smooth small dust disk models is close to $T_{\text{output}}$ ($\sim 220$ K, within 30%), the input temperature in the uniformly heavily depleted model appears to be too high by a factor of $\sim 3$.

### Table 1

<table>
<thead>
<tr>
<th>Model Comparison</th>
<th>Our Model</th>
<th>Uniformly heavily Depleted Cavity</th>
<th>Full Small Dust</th>
</tr>
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<tr>
<td>$\Sigma_{d, s}$</td>
<td>Equations (3) and (4)</td>
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<td>Equation (2)</td>
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<td>$\delta_i$ at $R_{\text{sub}}$ ($\delta_{\text{sub}, s}$)</td>
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<td>$\sim 10^{-5}$</td>
<td>1</td>
</tr>
<tr>
<td>$\Sigma_{d, b}$ (or $\delta_b$)</td>
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<td>$\sim 10^{-5}$</td>
<td>1</td>
</tr>
<tr>
<td>$h_{\text{sub}}$ at $R_{\text{sub}}$</td>
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<td>Thicker</td>
<td>...</td>
</tr>
<tr>
<td>Puffed up inner rim</td>
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<td>Little to heavy</td>
<td>...</td>
</tr>
<tr>
<td>Observation: SED</td>
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<td>Y</td>
<td>N</td>
</tr>
<tr>
<td>Observation: sub-mm</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
</tr>
<tr>
<td>Observation: NIR</td>
<td>Y</td>
<td>N</td>
<td>Y</td>
</tr>
</tbody>
</table>

Note. * Whether or not these models can reproduce the signatures in various observations: the infrared deficit around 10 $\mu$m in SED, the central cavity in sub-mm images, and the smooth radial profile of NIR images.

6. DISCUSSION

6.1. Direct Constraints from Observations and Our Generic Model

First, we review the direct, model-independent constraints on the disk structure that the three observations—the infrared SED, SMA sub-mm observations, and SEEDS NIR polarized scattered light imaging—put on many transitional disks in this cross sample.

1. IRS reveals a distinctive dip in the spectra around 10 $\mu$m, which indicates that the small dust ($\sim$mm-sized or so) in the inner part of the disk (from $R_{\text{sub}}$ to several AU) must be moderately depleted. However, due to degeneracy in parameter space, the detailed inner disk structure is model dependent. Models with different cavity depletion factors, $\Sigma_i$, and scale heights at the innermost disk could all reproduce the transitional disk signature. The IRS spectra are not very sensitive to the distribution of big dust.

2. The SMA images show a sub-mm central cavity, which indicates that the big dust (mm-sized or so, responsible for the sub-mm emission) is heavily depleted inside the cavity. However, while the observations can effectively constrain the spatial distribution of the big dust outside the cavity, they can place only upper limits on its total amount inside the cavity. SMA observations do not place strong constraints on the distribution of the small dust, though a weak upper limit for the amount of small dust inside the cavity may be determined based on the SMA noise level.

3. SEEDS NIR polarized scattered light images are smooth on large scales, and have no clear signs of a central cavity. The radial profiles of many images increase inwardly all the way from the outer disk to the inner working angle without sudden jumps or changes of slope, indicating that the scattering surfaces and their shapes are smooth and continuous (outside $\psi_{\text{in}}$). On the other hand, scattered light images are not very sensitive to the detailed surface density profiles and the total amount of small dust inside the cavity. The NIR images normally do not provide significant constraints on the distribution of the big dust.

In this work, we propose a generic disk model that grossly explains all three observations simultaneously. Previous models in the literature that assume a full outer disk and a uniformly heavily depleted inner cavity can reproduce (1) and (2), but fail at (3), because they also produce a cavity in the scattered light images, which contradicts the new SEEDS results. Through radiative transfer modeling, we find that
qualitatively (3) is consistent with a smooth disk of small dust with little discontinuity in both surface density and scale height profile. Table 1 summarizes the key points in various models and compares their performances in these three observations.

Since we focus on only generic disk models that reproduce the gross features in observations, and we do not try to match the details of specific objects, we more or less freeze many nonessential parameters in Sections 3–5 that do not qualitatively change the big picture for simplicity. The important ingredients include the dust properties (mostly for the small dust, both the size distribution and the composition), , the big-to-small dust ratio, and (both the absolute scale and ) . NIR scattered light images are able to provide constraints on some of these parameters (particularly and ), due to the dependence of the position and the shape of the disk surface on them. These parameters were not well constrained previously using sub-mm observations and SED due to strong degeneracies .

We note that alternative models for explaining the scattered light images exist, but generally they require additional complications. As one example, if the small dust is not depleted in the outer part of the sub-mm cavity, but is heavily depleted inside a radius smaller than , then it is possible to fit all the three observations, in which case the dust cavity does not reveal itself in the scattered light images due to its small size. However, in this case one needs to explain why different dust populations have different cavity sizes. Future scattered light imaging with even smaller may test this hypothesis.

As another example, while we achieve a smooth scattering surface by having continuous surface density and scale height profiles for the small dust, it is possible to have the same result with discontinuities in both, but with just the right amount such that the combination of the two yields a scattering surface inside the cavity smoothly joining the outer disk. This may work if the cavity is optically thick (i.e., not heavily depleted), so that a well-defined scattering surface inside the cavity exists. Experiments show that for the models in Section 3.2, uniformly depleting the small dust by a factor of and tripling the scale height inside the cavity would roughly make a smooth scattering surface. However, fine tuning is needed to eliminate the visible edge from a small mismatch in the two profiles. Also, the thicker cavity shadows the outer disk, and makes it much dimmer in scattered light (by about one order of magnitude). Lastly, without tuning on the scale height and/or surface density in the innermost part, this model produces too much NIR–MIR flux and too small flux at longer wavelengths in its SED, due to its big scale height at small .

6.2. The Structure of the Cavity in Transitional Disks

There are several important conclusions that can be drawn based on our modeling of the transitional disks at different wavelengths.

First, as we discussed in Section 3.2.2, for some objects the lower limit for the depletion of the small dust at the cavity edge (as constrained by the scattered light images) is likely to be above the upper limit for the big dust constrained by the SMA, based on the modeling results and the noise level in the two instruments. This essentially means that the small dust has to spatially decouple from the big dust at the cavity edge. This is the first time that this phenomenon has been associated with a uniform sample in a systematic manner. Detailed modeling of both images for individual objects is needed, particularly in order to determine how sharp the big dust cavity edge is from the sub-mm observations, to pin down the two limits and check whether they are really not overlapping. While we defer this to future work, we note that having the big dust the same surface density as the small dust inside the cavity probably cannot reproduce the sub-mm images. Experiments show that even with our declining (Equation (4)), a fixed big/small dust ratio and a continuous surface density for both throughout the disk (i.e., ), produce a sub-mm cavity with a substantially extended edge, and the central flux deficit disappears in the smeared out image. If this is confirmed, it further leads to two possibilities: (1) whatever mechanism responsible for clearing the cavity have different efficiency for the small and big dust or (2) there are other additional mechanisms that differentiate the small and big dust after the cavity clearing process. At the moment it is not clear which one of the two possibilities is more likely, and both need more thorough investigations.

Second, as we argued in Section 5, in order to reproduce the distinctive NIR deficit in the transitional disk SED, an effective “upper limit” of at the innermost region is required, which in experiments with our disk parameters is on the order of .

This is far from the lower limit of at the cavity edge (close to 1), constrained by the scattered light images. Together, the two limits indicate that the spatial distribution of the small grains is very different inside and outside the cavity—specifically, tends to be flat or even decrease inwardly inside the cavity.

In addition, this implies that the gas-to-dust ratio needs to increase inwardly, given that most of these objects have non-trivial accretion rates ( ). For a steady Shakura & Sunyaev disk, the accretion rate is related to the gas surface density as

\[
\frac{\alpha c_s^2 \Sigma_{\text{gas}}}{\Omega} \approx \frac{M}{3\pi},
\]

where is the Shakura–Sunyaev viscosity parameter, is the angular velocity of the disk rotation, and is given by Equation (16). At , Equation (17) predicts , assuming a temperature , , and as typical T Tauri values. This is very different from our upper limit of , in the innermost disk, obtained assuming a fixed gas-to-dust ratio of 100 (the flat models in Figure 1). To simultaneously have large but small in the innermost disk, the gas-to-dust ratio needs to increase substantially from the nominal value of 100 (by a factor of ~ in our models, echoes with Zhu et al. 2011). This could put constraints on the cavity depletion mechanism or dust growth and settling theory.

At the moment, the mechanisms that are responsible for clearing these giant cavities inside transitional disks are not clear (see summary of the current situation in A11). Regarding the applications of our model on this subject, we note two points here. The flat/declining surface density of the small grains inside the cavity in our models is consistent with the grain growth and settling argument that the small grains in the inner disk are consumed at a faster rate due to higher growth rate there (Dullemond & Dominik 2005; Garaud 2007; Brauer et al. 2008; Birnstiel et al. 2010). Also, the so-called dust filtration mechanism seems promising for explaining why small dust but not big dust is present inside the cavity (Paardekoper & Mellema 2006; Rice et al. 2006), since it could effectively trap the big dust at a pressure maximum in the disk but filter through the small dust. Particularly, combining the two (dust growth and dust filtration), Zhu et al. (2012) proposed a transitional disk formation model from a theoretical point of view to explain the
observations, and their predicted spatial distribution of both dust populations in the entire disk is well consistent with the ones here.

6.3. Future Observations

Imaging is a very powerful tool for constraining the structure of protoplanetary disks and the spatial distribution of both the small and big dust, and there are many ongoing efforts aiming at improving our ability to resolve the disks. In the direction of optical–NIR imaging, updating existing coronagraph and Adaptive Optics (AO) systems, such as the new Coronagraphic Extreme Adaptive Optics (SCExAO) system on Subaru (Murakami et al. 2010; Guyon et al. 2011, which could raise the contrast level of the cavity becomes higher and higher, and closer and closer to the raw image (which essentially has an infinite spatial resolution). With these next generation instruments, the transition of the spatial distribution of the small dust at the cavity edge will be better revealed.

On the other hand, in radio astronomy, the ALMA30 is expected to revolutionize the field, with its much better sensitivity level and exceptional spatial resolution (~0.1 or better). As examples, the right panels in Figure 8 show images convolved by a Gaussian profile with resolution ~0.1, which mimic the ability of ALMA and show two prominent improvements over the images under the current SMA resolution (~0.3, middle panels). First, the edge of the cavity is much sharper in the mock ALMA images. This will make the constraint on the transition of the big dust distribution at the cavity edge much better. Second, while the weak emission signal in the bottom model is overwhelmed by the halo of the outer disk in the mock SMA image, resulting in that the bottom model is nearly indistinguishable from the top model (which essentially produces zero cavity sub-mm emission), the mock ALMA image successfully resolves the signal as an independent component from the outer disk, and separates the two models. This weak emission signal traces the spatial distribution of the dust (both populations) inside the cavity, which is the key in understanding the transitional disk structure.

At this stage, the total number of objects that have been observed by all three survey-scale projects (using IRS/SMA/Subaru) is still small. Increasing the number in this multi-instrument cross sample will help clear the picture. In addition, future observations which produce high spatial resolution images at other wavelengths, such as UV, optical, or other NIR bands (for example using the Hubble Space Telescope; Grady et al. 2009, or the future James Webb Space Telescope), or using an interferometer (such as the Astrometric and Phase-Referencing Astronomy project on Keck; Adelman et al. 2007; Pott et al. 2009, or the AMBER system on Very Large Telescope Interferometer; Petrov et al. 2007; Tatulli et al. 2007) should also be able to provide useful constraints on the disk properties.

7. SUMMARY

We summarize this paper by coming back to the question that we raised at the beginning: What kind of disk structure is consistent with and is able to reproduce the characteristic signatures in all three observations of transitional protoplanetary disks: a high contrast cavity in sub-mm images by SMA, an NIR deficit in SED by Spitzer IRS, and a smooth radial profile in NIR polarized scattered light images by Subaru HiCIAO. We propose one generic solution for this problem, which is feasible but by no means unique. The key points are as follows.

1. A cavity with a sharp edge in the density distribution of big grains (up to ~mm-sized) and with a depletion factor of at least 0.1–0.01 inside is needed to reproduce the SMA sub-mm images, as pointed out by A11.
2. Right inside the cavity edge (~15–70 AU), the surface density for the small dust (~μm-sized and smaller) does not have a big sudden (downward) jump (a small discontinuity

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may exist). The SEEDS NIR scattered light images, which typically detect the disk at $R \gtrsim 15$ AU (the inner working angle in SEEDS), generally require continuous/smeared profiles for the surface density and scale height of the small dust.

3. The small dust in the innermost region (i.e., within a few AU, on a scale smaller than measured by SEEDS) has to be moderately depleted in order to produce the transitional-disk-like SED, assuming that the disk is not too flared, but the exact depletion factor is uncertain and model dependent.

As we discussed in Section 6.2, combining all the above points, our model suggests that the spatial distributions of the big and small dust are decoupled inside the cavity (particularly at the cavity edge). Also, our model argues that the surface density of the small dust inside the cavity is flat or decreases with radius, consistent with the predictions in dust growth models. Combined with the accretion rate measurement of these objects, it further implies that the gas-to-dust ratio increases inwardly inside the cavity of transitional disks.

R.D. thanks Sean Andrews, Nuria Calvet, Eugene Chiang, Bruce Draine, Catherine Espaillat, Elise Furlan, and Jim Stone for useful conversations and help. This work is partially supported by NSF grants AST 0908269 (R.D., Z.Z., and R.R.), AST 1008440 (C.G.), AST 1009314 (J.W.), AST 1009203 (J.C.), NASA grant NNX22SK53G (L.H.), and the Sloan Fellowship (R.R.). We thank Pascale Garaud and Doug Lin for organizing the International Summer Institute for Modeling in Astrophysics (ISIMA) at Kavli Institute for Astronomy and Astrophysics, Beijing, which facilitated the discussion of radiative transfer modeling among R.D., L.H., T.M., and Z.Z. We also thank the anonymous referee for suggestions that improved the quality of the draft.

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