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Discovery of a relation between black hole mass and soft X-ray time lags in active galactic nuclei

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ABSTRACT

We carried out a systematic analysis of time lags between X-ray energy bands in a large sample (32 sources) of unabsorbed, radio quiet active galactic nuclei (AGN), observed by XMM–Newton. The analysis of X-ray lags (up to the highest/shortest frequencies/time-scales), is performed in the Fourier-frequency domain, between energy bands where the soft excess (soft band) and the primary power law (hard band) dominate the emission. We report a total of 15 out of 32 sources displaying a high-frequency soft lag in their light curves. All 15 are at a significance level exceeding 97 per cent and 11 are at a level exceeding 99 per cent. Of these soft lags, seven have not been previously reported in the literature, thus this work significantly increases the number of known sources with a soft/negative lag. The characteristic time-scales of the soft/negative lag are relatively short (with typical frequencies and amplitudes of \( \nu \sim 0.07–4 \times 10^{-3} \) Hz and \( \tau \sim 10–600 \) s, respectively), and show a highly significant (\( \gtrsim 4\sigma \)) correlation with the black hole mass. The measured correlations indicate that soft lags are systematically shifted to lower frequencies and higher absolute amplitudes as the mass of the source increases. To first approximation, all the sources in the sample are consistent with having similar mass-scaled lag properties. These results strongly suggest the existence of a mass-scaling law for the soft/negative lag, that holds for AGN spanning a large range of masses (about 2.5 orders of magnitude), thus supporting the idea that soft lags originate in the innermost regions of AGN and are powerful tools for testing their physics and geometry.

Key words: galaxies: active – galaxies: nuclei – X-rays: galaxies.

1 INTRODUCTION

The observed similarities in the timing properties of different black hole (BH) systems suggest that the same physical mechanism is at work in sources spanning a wide range of masses (e.g. Uttley, McHardy & Vaughan 2005; McHardy et al. 2006). This observational fact represents an important achievement in the context of the theory of unification of BH accretion. A breakthrough in this respect was the discovery of the mass-scaling law that regulates the characteristic time-scales of variability, identified with the high-frequency break in the power spectral density function (PSD). This relation holds for objects of widely different size (i.e. over about eight order of magnitudes in mass, from BH X-ray binaries, BHXB, up to active galactic nuclei, AGN, McHardy et al. 2006; Körding et al. 2007) and is in agreement with expectations from standard accretion disc models, whereby all the characteristic time-scales depend linearly on the BH mass, \( M_{BH} \) (e.g. Shakura & Sunyaev 1973; Treves, Maraschi & Abramowitz 1988).

Another fundamental analogy emerges from the comparison of time lags between X-ray energy bands. Hard/positive lags (i.e. hard X-ray variations lagging soft X-ray variations) are generally observed in both BHXBs and AGN, and can be interpreted in terms of propagation of mass accretion rate fluctuations in the disc (Kotov, Churazov & Gilfanov 2001; Arévalo & Uttley 2006). Those lags are usually detected at relatively low frequencies (i.e. below the PSD high-frequency break).

On the other hand, a relatively new and interesting perspective comes from the study of high-frequency soft/negative lags (i.e. soft
X-ray band variations lagging hard X-ray band variations. The first significant detection of a soft/negative lag in AGN light curves was reported in the narrow line Seyfert 1 galaxy 1H 0707−495 (Fabian et al. 2009; Zoghbi et al. 2010), and interpreted as the signature of relativistic reflection which ‘reverberates’ in response to continuum changes after a time equal to the light-crossing time from the source to the reflecting region. A different interpretation has been proposed in terms of a complex system of scatterers/absorbers located close to the line of sight, but at hundreds of gravitational radii, \( r_g \), from the central source (Miller et al. 2010), thus requiring us to have a special line of sight to the source.

Subsequently, soft lags have been observed in several other sources (e.g. Tripathi et al. 2011; Emmanoulopoulos, McHardy & Papadakis 2011; Zoghbi & Fabian 2011). One of the largest mass sources (\( M_{BH} \sim 10^{-8} M_\odot \)) showing a soft/negative lag is PG 1211+143 (De Marco et al. 2011), whose lag spectrum appears ‘shifted’ by about one order of magnitude (with the lag frequency, \( \nu \), and amplitude, \( \tau \), found at \( \sim \)10−3−10 × 10−4 Hz and \( \sim \)10−2 s, respectively) with respect to those measured in other low mass sources (i.e. \( \nu \sim 10^{3} \) Hz and \( \tau \sim 20–30 \) s, Emmanoulopoulos et al. 2011). In De Marco et al. (2011), we speculated that this difference could be simply explained if the time-scales in PG 1211+143 are scaled-up by the BH mass, estimated to be about 10–100 times the mass of the other AGN for which X-ray lags have been recorded so far. In this paper, we explore this hypothesis, by studying the properties of the lag-frequency spectrum in a large sample of sources, spanning a wide range of masses (about 2.5 decades). The time-scales of detected soft/negative lags are then used to study correlations with relevant parameters, such as luminosity and BH mass.

2 THE SAMPLE

The sources analysed are extracted from the CAIXAvar sample – a subsample of the CAIXA sample by Bianchi et al. (2009a) – presented in Ponti et al. (2012), which includes all the well-exposed, X-ray unobscured \( (N_{H} < 2 \times 10^{22} \text{ cm}^{-2}) \), radio quiet AGN observed by XMM–Newton in targeted observations as of 2010 June. We considered all the sources having at least one observation with a longer than 40 ks exposure (41 sources), and selected those with published BH mass, \( M_{BH} \), estimates (39 sources). Finally, we selected all the sources showing significant variability in their light curves. To this aim, we made use of the excess variance estimates provided by Ponti et al. (2012), computed by sampling the 2–10 keV light curve of each source in 40 ks segments (note that also single-interval measurements were considered), and assuming a time resolution of 250 s. All the sources having excess variance different from zero at \( > 2 \sigma \) confidence level were included in our sample, i.e. excluding all the sources consistent with having constant flux on the time-scales of interest for this work (\( \leq 40 \) ks). With the latter selection our final sample was reduced to a total of 32 sources. For each source all the available observations in the XMM–Newton archive have been used in our analysis, apart from those highly corrupted by background flares. In the computation of the lag-frequency spectra, multiple observations have been combined to obtain better statistics.

Only data from the EPIC-pn camera were used,1 because of its high effective area and S/N over the 0.3–10 keV energy band. Data reduction was performed using XMM Science Analysis System (SAS v. 10.0), starting from the observation data files and following standard procedures. Filtered events are characterized by PATTERN \( \leq 4 \), and are free from background flares. Typical source extraction regions are 45 arcsec radius circles. Spectra were extracted and used to select the energy bands for the computation of time lags. They were grouped to a minimum of 20 counts per bin, while response matrices were generated through the RMFGEN and ARFGEN SAS tasks. The analysis of the time series was carried out using routines implemented through IDL v. 6.1. Correction of sporadic count rate drops (usually involving single time bins) in the time series, which occur as a consequence of event losses due to telemetry dropouts, was performed by rescaling the count rate within the bin for the effective fractional time-bin length.

3 LAG VERSUS FREQUENCY SPECTRA

3.1 Analysis

We computed time-lag–frequency spectra between light curves in the soft and hard X-ray energy bands. The soft and hard energy bands were selected so as to single out energies dominated by the soft excess and the primary power law. To this aim, we adopted a phenomenological approach, although we note that several tests have been done by slightly varying the selected energy bounds, and the obtained results are all consistent with each other. Specifically, we first fitted the data in the 1–4 keV energy band with a simple power law absorbed by a cold column of gas (which accounts for any warm absorber-induced extra curvature at high energies), with all the parameters left free to vary. For the soft band, we fixed at 0.3 keV the low energy bound, and selected, as high energy bound, the energy at which the soft excess significantly deviates (at more than 3\( \sigma \)) from the extrapolation of the best-fitting absorbed power law. As the hard energy band, we used the 1–5 keV range, excluding energies where significant deviations from the best-fitting power law were observed, e.g. due to the presence of troughs produced by complex absorption (at \( \sim 1 \) keV) or the presence of a broad Fe K line red tail (at \( \sim 4–5 \) keV). Data above 5 keV were, in general, excluded to avoid contamination from components of the Fe K line complex. A detailed compilation of all the adopted energy bands can be found in Tables 1 and 2.

The time-lag–frequency spectra are computed following the techniques described in detail by Nowak, Wilms & Dove (1999) and applied to XMM–Newton data in De Marco et al. (2011). The time lag is derived from the formula \( \tau(\nu) = \phi(\nu)/2\pi \nu \), where \( \phi(\nu) \) is the frequency-dependent phase of the average cross-power spectrum between the soft and hard time series. The resulting lag–frequency spectra are rebinned multiplicatively, i.e. the bin size is set equal to \( n \) times the frequency value, with step size, \( n \), chosen between \( \sim 1.2 \) and 2 depending on the quality of the data. Sources for which a negative lag was reported in the literature have been re-analysed with our procedures.

3.2 Results

We first present the results of our analysis, deferring to the next section a detailed discussion of their significance and robustness. We set as the detection threshold the 2\( \sigma \) confidence level (\( \sim 95 \) per cent) producing 15 out of 32 sources showing a soft lag with significance well above this limit (11 of them have significance >99 per cent, while the remaining four are above the 97 per cent confidence level). The procedures followed to estimate the significance of negative-lag detections are discussed in detail in Section 3.3.1.

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1 We checked whether the EPIC MOS data yield consistent results, finding a good agreement, although the quality of the lag spectra is significantly affected by the lowest statistics.
Table 1. Sources with a soft-/negative-lag detection at $>2\sigma$ confidence level. (1) Name; (2) XMM–Newton observations; (3) Nominal and effective exposure; (4) Logarithm of the estimated black hole mass, uncertainty, mass estimate technique (R: reverberation mapping, V: stellar velocity dispersion, E: empirical $L_{5100\AA}$ versus $R_{BLR}$ relation) and references (a: Nelson & Whittle 1995; b: Oliva et al. 1999; c: Kaspi et al. 2000; d: Vestergaard 2002; e: Bian & Zhao 2003; f, g: Peterson et al. 2004, 2005; h: Zhang & Wang 2006; i: Wang & Zhang 2007; j: Bentz et al. (2009); k: Zhou et al. 2010; l: Denney et al. 2010); (5) soft and hard X-ray energy bands used for the lag computation; (6) soft-/negative-lag significance as obtained from the combination of the consecutive points forming the soft-lag profile and, within parenthesis, from Monte Carlo simulations.

<table>
<thead>
<tr>
<th>Name</th>
<th>Obs ID</th>
<th>Exposure [effective] (ks)</th>
<th>Log ($M_{BH}$)</th>
<th>$\Delta E_{\text{soft/hard}}$ (keV)</th>
<th>Significance</th>
</tr>
</thead>
<tbody>
<tr>
<td>NGC 4395</td>
<td>0142830101</td>
<td>113 [90]</td>
<td>5.56 ± 0.14 R, g</td>
<td>0.3–1/1–5</td>
<td>99.3 per cent (98.0 per cent)</td>
</tr>
<tr>
<td>NGC 4051</td>
<td>0109141401, 015756101</td>
<td>122 [100], 52 [42]</td>
<td>6.24 ± 0.14 R, l</td>
<td>0.3–1/1–5</td>
<td>99.9 per cent (99.5 per cent)</td>
</tr>
<tr>
<td></td>
<td>0606320101, 0606320201, 0606320301, 0606320401, 0606321301, 0606321401, 0606321501, 0606321601, 0606321701, 0606321801, 0606321901, 0606322001, 0606322101, 0606322201, 0606322301</td>
<td>46 [45], 46 [42], 46 [21], 45 [18], 42 [39], 42 [40], 42 [34], 42 [41], 45 [38], 44 [40], 45 [36], 40 [37], 44 [24], 44 [41], 43 [42]</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Mrk 766</td>
<td>0109141301, 0304030301</td>
<td>130 [105], 99 [98]</td>
<td>6.25 ± 0.35 R, j</td>
<td>0.3–0.7/1.5–4</td>
<td>99.6 per cent (97.6 per cent)</td>
</tr>
<tr>
<td>Ark 564</td>
<td>0006810101, 0006810301, 0206400101</td>
<td>34 [11], 16 [12], 102 [99]</td>
<td>6.27 ± 0.50 E, h</td>
<td>0.3–1/2–5</td>
<td>97.0 per cent (98.4 per cent)</td>
</tr>
<tr>
<td>MCG-6-30-15</td>
<td>0111570101, 0111570201, 0209740101, 0209740701, 0209740801</td>
<td>47 [10], 66 [51], 89 [80], 129 [122], 130 [124]</td>
<td>6.30 ± 0.40 V/E, b, k</td>
<td>0.3–0.9/1.5–3</td>
<td>99.9 per cent (99.5 per cent)</td>
</tr>
<tr>
<td>1H 0707-495</td>
<td>0511580101, 0511580201, 0511580301, 0511580401</td>
<td>124 [122], 124 [97], 123 [100], 122 [86]</td>
<td>6.31 ± 0.50 E, c</td>
<td>0.3–1/1–4</td>
<td>&gt;99.9 per cent (&gt;99.9 per cent)</td>
</tr>
<tr>
<td>RE J1034+396</td>
<td>0506410101, 0506580201, 0653510101, 0653510201</td>
<td>93 [84], 70 [51], 52 [20], 54 [32]</td>
<td>6.57 ± 0.27 E, k</td>
<td>0.3–1/1.5–4.1</td>
<td>98.4 per cent (96.0 per cent)</td>
</tr>
<tr>
<td>NGC 7469</td>
<td>0112170101, 0112170201, 0207090101, 0207090201</td>
<td>25 [18], 19 [23], 79 [84], 85 [78]</td>
<td>7.09 ± 0.05 R, f</td>
<td>0.3–1.5/1.5–5</td>
<td>97.0 per cent (97.0 per cent)</td>
</tr>
<tr>
<td>Mrk 335</td>
<td>0306870101, 0600540501, 0600540601</td>
<td>133 [118], 83 [110], 132 [81]</td>
<td>7.15 ± 0.12 R, f</td>
<td>0.3–0.6/3–5</td>
<td>99.7 per cent (98.6 per cent)</td>
</tr>
<tr>
<td>PG 1211+143</td>
<td>0112610101, 0208020101, 0502050101, 0502050201</td>
<td>56 [53], 60 [34], 65 [46], 51 [20]</td>
<td>7.37 ± 0.12 R, c</td>
<td>0.3–0.7/1.5–5</td>
<td>99.9 per cent (99.8 per cent)</td>
</tr>
<tr>
<td>NGC 3516</td>
<td>0107460601, 0107460701</td>
<td>124 [75], 130 [116]</td>
<td>7.50 ± 0.05 R, l</td>
<td>0.3–1/1–5</td>
<td>99.3 per cent (97.2 per cent)</td>
</tr>
<tr>
<td>NGC 6860</td>
<td>0552170301</td>
<td>123 [117]</td>
<td>7.59 ± 0.50 E, i</td>
<td>0.3–1.1–5</td>
<td>98.8 per cent (97.8 per cent)</td>
</tr>
</tbody>
</table>
The lag–frequency spectra of the 15 sources with a significant soft-lag detection are shown in Fig. 1, while Fig. 2 displays some examples of spectra with only a marginal (significance <2σ) soft/negative lag. Most of the sources do show smooth lag profiles, several of which are characterized by a hard/positive lag at the lowest frequencies, dropping to negative values at higher frequencies, others showing only the soft-/negative-lag component, but shifted to low frequencies.

Our results are summarized in Tables 1 and 2, respectively for sources with a significant or marginal/non-significant detection. The detection significances reported in the Table 1 are derived following different approaches (in particular, those enclosed in parentheses are obtained from extensive Monte Carlo simulations), as detailed in Section 3.3.1.

Overplotted on the measured lag–frequency spectra (Fig. 1) are the 1σ confidence levels of the observed time lags. The contours have been computed through Monte Carlo simulations (see Section 3.3.1), using as a template-lag profile an interpolated function that describes the measured lag, and applying a frequency-dependent phase-shift to each pair of simulated light curves.
Figure 1. Lag–frequency spectra of sources with a detected soft/negative lag at >2σ confidence level, in order of increasing mass (from top left to bottom right). The error bars are calculated using the standard formula from Bendat & Piersol (1986), as used in Nowak et al. (1999). The simulated 1σ contour plots (dashed curves) are overplotted on the data. The red-continuous curves limit the range \( \tau = \left[ -1/2\nu, +1/2\nu \right] \) of allowed time-lag values at each frequency, while the red-dotted curves mark the standard deviation of a uniform distribution defined on the same interval of time-lag-permitted values (see Section 3.3.2 for details).

According to this function, the spread in lag values is consistent with the errors associated with the data, which have been computed through the formula from Bendat & Piersol (1986), as used in Nowak et al. (1999). Moreover, it is worth noting that, to recover the observed lag amplitude, we had to correct the input lag function by a frequency-dependent factor. If this correction is omitted, the lag amplitudes at the lowest frequencies tend to be underestimated. This bias had already been pointed out in Zoghbi et al. (2010) and De Marco et al. (2011). It is related to a red noise leak effect, whereby phase-lag components associated with frequencies below the lowest sampled frequency contribute to those within the monitored frequency window. If the lag associated with these components is either positive, null or smaller (in absolute value) than the intrinsic negative lag at the observable frequencies, the overall effect is of diluting the amplitude of the latter, thus underestimating a measurement. The amount of dilution depends on the amount of power below the lowest sampled frequency, thus being stronger for sources with steeper power spectra (e.g. the highest mass sources, for which the sampled frequency range in this analysis is far below the PSD high-frequency break).
The soft/negative lags detected in our analysis are perfectly consistent (in both amplitude and frequency) with those already reported in the literature for eight of the sources of our sample (Ark 564; Arévalo et al. 2006; 1H 0707—495, Zoghbi et al. 2010; Mrk 766, MCG-6-30-15, Emmanoulopoulos et al. 2011; PG 1211+143, De Marco et al. 2011; Mrk 1040, Tripathi et al. 2011; RE J1034+396, Zoghbi & Fabian 2011; NGC 3516, Turner et al. 2011), even when slightly different energy bands are adopted. Moreover, we report a total of seven newly detected soft lags (i.e. NGC 4395, NGC 4051, NGC 7469, Mrk 335, NGC 6860, NGC 5548, Mrk 841). The observed values of lag amplitudes and frequencies span about two decades (i.e. $\tau \sim 10^{2}–10^{3}$ s and $\nu \sim 0.07–4 \times 10^{-3}$ Hz), similar to the sampled BH mass range of values ($\sim 10^{7}–10^{9} M_{\odot}$). These new detections significantly increase the number of soft/negative lags observed in nearby AGN.

Despite the wide range of BH masses and hence variability timescales (and correspondingly, amplitudes) in our sample, it is interesting to note that we are still able to detect significant lags over a wide range of masses. One might expect that for the more slowly variable sources there would not be sufficient variable signal to detect the lags. We address this question by showing the PSD of the 15 sources with a detected soft lag (see Fig. 3). The PSDs have been computed in the range of energies used to compute the lag–frequency spectra (i.e. in the soft and hard band selected for each source) so as to estimate the relative importance of variability power due to Poisson noise fluctuations with respect to the intrinsic power of the source at the lag frequencies. The lags are always detected at the frequencies where the Poisson noise contribution is negligible. Thus, it is not surprising that we are able to detect significant negative lags in all these sources. We refer to Section 3.3.2 for further discussion about this issue.

### 3.3 Robustness of lag detections

#### 3.3.1 Negative-lag significance

To determine the detection significance of the observed soft lags, we used different methods. We first combined the significance of all the consecutive points that form the soft-lag profile (using the error propagation rule for statistically uncorrelated data points) and derived the number of standard deviations from zero lag. In the computation, we did not take into account the low-frequency hard/positive lag points (where present), and excluded frequencies where the effects of Poisson noise are significant (see details in Section 3.3.2). Indeed, the effect of counting noise is to produce a drop of coherence (the measure of the degree of linear correlation between the two light curves, e.g. Vaughan & Nowak 1997) to zero values. The corresponding cross-spectrum phase at these frequencies is randomly distributed between $[-\pi, +\pi]$, thus precluding the detection of any intrinsic time lag. The soft/negative lags reported in this paper occur at frequencies well below the limit-frequency set by Poisson noise (Section 3.3.2), and are characterized by a medium-to-high level of intrinsic coherence ($0.4 \lesssim \gamma_{l}^{2} \lesssim 1$, estimated using prescriptions given by Vaughan & Nowak 1997 for correction of counting noise effects), this value representing the fraction of the signal that is responsible for the lag. The derived soft-lag significances have been cross-checked with those obtained by carrying out a $\chi^{2}$ test against a constant zero-lag model.

Noteworthy is the fact that, under a more rigorous approach, the single points in the lag–frequency profile cannot be treated as independent variables in standard statistical tests. For this reason, the reliability of the soft lags in the 15 sources has been further tested through extensive Monte Carlo simulations. This approach allows us to check the robustness of the detections against spurious fluctuations produced by Poisson noise and red noise, over the entire sampled range of frequencies.

Thus, for each source we simulated 1000 pairs of correlated stochastic light curves, representing the hard and soft bands. We generated the light curves using the method of Timmer & König (1995), with different PSDs for each band but choosing the same random number seed for each light curve in the pair so that the initial light curves are 100 per cent coherent. In the simulations, we assume the same source and background count rates and same Poisson noise level as the real data in the selected soft and hard energy bands. The intrinsic variability power of the source within each energy band have been estimated by fitting the corresponding PSDs (Fig. 3) with a simple power law plus constant (accounting for the Poisson noise contribution) model, and integrating over the sampled frequency range. The slope of the power law in the two bands has been fixed to the mean values obtained by González-Martín & Vaughan (2012) using the same fitting model, i.e. $\alpha = -2$ for the soft band and $\alpha = -1.7$ for the hard band. The derived best-fitting parameters have been used to define the underlying PSDs of the simulated light curves. The latter are assumed to break to a slope of $\alpha = -1$ (e.g. Edelson & Nandra 1999; Uttley, McHardy & Papadakis 2002; Markowitz 2010) below a characteristic frequency.

The break frequency of each source has been estimated by rescaling the break frequency of 1H 0707--495 (Zoghbi et al. 2010) for the mass of the source, according to the scaling relationship provided by McHardy et al. (2006), using the BH masses listed in Table 1, and discarding the dependence on the mass accretion rate. For the sources in common, the estimated values are in agreement with

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2 Assuming a linear scaling of the break frequency with the mass accretion rate (McHardy et al. 2006), and using values tabulated in Ponti et al. (2012) for the bolometric luminosity, this approximation introduces a negligible uncertainty, of a factor of $\sim 2–3$, on the estimated break frequency. The latter uncertainty is even more negligible if the dependence of the break frequency on the mass accretion rate is weaker, as argued by González-Martín & Vaughan (2012).
Figure 3. Estimated power spectra (black squares: soft energy band; red triangles: hard energy band) of sources with a soft lag detected at $>2\sigma$ confidence level, in order of increasing mass (from top left to bottom right). The PSD are logarithmically rebinned (Papadakis & Lawrence 1993). The normalization defined by Miyamoto et al. (1991) have been adopted. The vertical dotted lines mark the range of frequencies spanned by the soft lag, while the dashed horizontal lines mark the Poisson noise level for each band (computed following Vaughan et al. 2003).

results by González-Martín & Vaughan (2012), and in most of the cases the PSD high-frequency break lies below the analysed frequency range. It is worth noting that considering slightly different values for the PSD parameters (e.g. a steeper high-frequency PSD slope, e.g. Vaughan et al. 2011) does not change the results here.

Poisson noise contribution has been accounted for by adding Gaussians to each simulated light curves, with variance equal to the standard deviation of the mean count rate (the latter being estimated from the best-fitting constant level of Poisson noise in the PSDs). A zero-phase lag was imposed on each pair of simulated light curves, meaning that every fluctuation in the resulting lag–frequency spectrum above and below the zero-lag level is due to statistical noise.

As previously mentioned, the effect of counting noise is to produce a deviation of the coherence function from one, resulting in
a drop to zero-value at high frequencies, where the Poisson noise variability power dominates. This effect is reproduced in the simulated data by adding the proper level of Poisson noise. However, the low-frequency modes can still be affected by an extra intrinsic fraction of incoherent signal (e.g. in HH 0707–495, Zoghbi et al. 2010, and in REJ 1034+396, Zoghbi & Fabian 2011, this drop in coherence has been attributed to the transition between two different variability processes). We accounted for it by adding a fraction $1 - \gamma^2(\nu)$ of uncorrelated signal to every pair of simulated light curves, where $\gamma^2(\nu)$ represents the frequency-dependent fraction of intrinsic coherence as measured from the data.

The resulting simulated light curves were used to compute lag–frequency spectra, adopting the same sampling (e.g. duration of each light-curve segment, time resolution) and rebinning (e.g. logarithmic rebinning factor of the lag spectrum, minimum number of counts per bin) as in the real data. We then defined a sliding-frequency window, containing the same number, $N_w$, of consecutive frequency bins as those forming the observed negative-lag profile in the data (i.e. typically $N_w = 3$). The figure of merit $\chi = \sqrt{\sum (\tau/\sigma_{\text{lag}})^2}$ within the sliding window is computed at each step and the maximum value recorded for all the simulated lag–frequency spectra. In this procedure, the full range of sampled frequencies is swept, with the exception of those where the measured coherence drops to zero as a consequence of Poisson noise (this cutoff being around $10^{-3}$–$10^{-2}$ Hz, see following section). Since our aim is to estimate the probability of recovering the observed lag profile only by chance, we registered the number of times $N_w$ consecutive negative-lag points are observed in the simulated data with a figure of merit $\chi$ exceeding the real one. The estimated significances for the 15 detected soft lags are reported (in parentheses) in Table 1. In most of the sources, we registered a mild decrease of the inferred significances with respect to those obtained with the standard statistical tests. Specifically, probabilities should be multiplied by a factor of $\sim 0.97$–0.99, depending on the quality of the data. However, the corrected values are still consistent with lying above the adopted 2σ detection threshold.

### 3.3.2 Poisson noise

Counting noise gives an important contribution at high frequencies, where the intrinsic variability power of the source decreases to values comparable to the Poisson noise component. Poisson noise adds to the signal as an incoherent component, whose phase (i.e. the argument of the cross-spectrum vector) is uniformly and randomly distributed in the range $[-\pi, +\pi]$. When combined with the intrinsic cross-spectrum vector, this component increases the spread in the phase. Fourier phase lags are limited to the range of values $[-\pi, +\pi]$, corresponding to the condition $|\tau| \leq 1/2\nu$ on the time-lag amplitude. The latter limits on $\tau$ have been marked in Fig. 1 as continuous red curves. This implies that, if the lag values within each frequency bin are highly spread (e.g. as a consequence of low variability power and/or low intrinsic coherence, and so higher Poisson noise fraction) they tend to distribute uniformly within these limits, since the tails of the distribution are cut at $\tau = \pm 1/2\nu$ and reflected within the permitted range of values. In this regime, the uncertainty on the lag is of the order of the range of permitted values, thus precluding the detection of any intrinsic lag. However, rebinning the cross spectrum over contiguous frequencies and/or over different light-curve segments, reduces this effect, since the Poisson noise components to the cross-spectrum vectors tend to cancel out in the averaging process. In other words, this allows the detection of time lags up to frequencies higher than the frequency at which the variability power of the source is of the order of the Poisson noise component. Hence, the frequency $\nu_{\text{Poiss}}$ at which Poisson noise starts dominating the lag–frequency spectra is given by the frequency at which the spread in the measured time lag (defined by the 1σ contour plots in Fig. 1) is of the order of the standard deviation (dotted red curves in Fig. 1) of a uniform distribution defined on the interval $\tau = [-1/2\nu, +1/2\nu]$. As is clear from Fig. 1, the data are well sampled enough that Poisson noise and intrinsic coherence do not lead to errors approaching the $\pm \pi$ limits of the phase lag.

To determine $\nu_{\text{Poiss}}$, following a more rigorous approach, we relied on Monte Carlo simulations. With respect to previous simulations, we adopted the different approach of studying the effects of Poisson noise on the cross-spectrum terms at each frequency. To this aim, we generated 1000 realizations of the Poisson noise cross-spectrum vector. The randomization of the corresponding phase and amplitude is obtained by drawing two Gaussian-distributed random numbers and using them as the real and imaginary part. The standard deviation of the two Gaussian distributions is a function of the measured coherence, $\gamma^2$, and the number of samples into each frequency bin ($N = k^m$, where $k$ is the number of frequencies and $m$ is the number of light-curve segments averaged over) and is given by $\delta = \sqrt{(1 - \gamma^2)(2N\nu^2)^{-1}}$. Each simulated vector is then added to the intrinsic cross-spectrum vector. We applied this procedure to all the detected soft lags, assuming a constant soft/negative time lag over all the sampled frequency range, whose amplitude is fixed to the minimum value in the observed lag profile, and checked at which frequency, $\nu_{\text{Poiss}}$, the distribution of phases starts to tend to a uniform distribution and the average phase goes to zero. In most of the sources the estimated $\nu_{\text{Poiss}}$ is $\gtrsim 0.01$ Hz, falling well above the highest frequency sampled. Only in four cases (i.e. Mrk 335, NGC 3516, NGC 5548 and Mrk 841) $\nu_{\text{Poiss}}$ is lower ($>10^{-3}$ Hz).

In the lag minimum is always detected significantly (a factor of $\sim 3$–20) below $\nu_{\text{Poiss}}$, in agreement with results of zero-lag Monte Carlo simulations, whereby the observed negative lags are not due to spurious noise features.

### 4 LAG CORRELATIONS

The measured lag–frequency spectra have similar profiles, with the negative lag shifting to lower frequencies as the BH mass of the source increases (see Fig. 1, where the plots are in order of increasing mass of the source). It is thus interesting to test the hypothesis of a $M_{\text{BH}}$ dependence of the soft lag characteristic timescales (i.e. amplitude and frequency).

The sources showing a soft/negative lag have widely different mass values, spanning about 2.5 orders of magnitude in estimated $M_{\text{BH}}$. The $M_{\text{BH}}$ values adopted in this paper are taken from the literature (see Table 1 for references) and are preferably those obtained from reverberation mapping and stellar velocity dispersion techniques. In all the other cases (5 out of 15), we considered estimates obtained from the empirical relation between the optical luminosity at 5100 Å and the broad line region size ($R_{\text{BLR}}$. e.g. Bentz et al. 2009). The unknown mass uncertainties have been replaced with the estimated dispersion of the adopted relation for mass determination (i.e. 0.5 dex in the case of single epoch methods, and 0.4 dex for the others).

Fig. 4 shows the lag frequency and amplitude versus mass ($v_{\text{corr}}$ and $M_{\text{BH}}$) on a logarithmic scale. In the plots, the $v_{\text{corr}}$ and $\tau$ values (and their uncertainties) correspond to the frequency and amplitude of the minimum, single point in the negative-lag profile (the effects of statistical fluctuations in the position of

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the lag minimum are further discussed in Section 4.1), once corrected for the redshift of the source. The fit of these data sets with a constant is unsatisfactory, yielding $\chi^2 = 213$ and $\chi^2 = 41$ (14 degrees of freedom), respectively for the lag frequency and amplitude. To statistically assess whether the pairs of parameters are correlated, we computed Spearman’s rank correlation coefficient, $\rho$. The test yielded $\rho \sim -0.79$ and 0.90, respectively for the $\nu_{\text{lag}}$ and $\tau$ parameters, both corresponding to a correlation with significance $\gtrsim 4\sigma$ (null-hypothesis probabilities of $\sim 4 \times 10^{-4}$ and $\sim 5 \times 10^{-6}$, respectively), with the correlation between $\tau$ and BH mass being the most significant.

It is worth noting that the lag profile in the large mass sources is not well sampled, since the data are limited (at the lowest frequencies) by the duration of the observations. Hence, we checked whether the correlation still holds when considering these points as upper/lower limits for the lag frequency/absolute amplitude, by computing generalized Kendall’s rank correlation statistics for censored data sets (e.g. Isobe, Feigelson & Nelson 1986). Although slightly lower, the significance of the correlation is still relatively high ($\gtrsim 3\sigma$).

Following Bianchi et al. (2009b), we applied a least squares linear regression approach to derive constraints on the functional dependence of $\nu_{\text{lag}}$ and $\tau$ from $M_{\text{BH}}$. To minimize the uncertainty in the best-fitting model, we carried out 1000 Monte Carlo simulations, whereby the $x$- and $y$-axis coordinates of each experimental point were substituted by two random values drawn from two Gaussian distributions with means equal to the coordinates of the data point on each axis and the associated statistical uncertainty as standard deviation (see Bianchi et al. 2009b). Each simulated data set was fitted in log–log space with a linear model. The mean of the slopes and intercepts were used to define our best-fitting model, while the mean standard deviation represents the uncertainty of the best-fitting parameters. The results of the fits are Log$\nu_{\text{lag}} = -3.50[\pm 0.07] - 0.47[\pm 0.09]$ Log($M_\odot$) and Log$[\tau] = 1.98[\pm 0.08] + 0.59[\pm 0.11]$ Log($M_\odot$), where $M_\odot = M_{\text{BH}}/10^7 M_\odot$. The estimated scatter around the best-fitting model is $\sigma = 0.19$ and 0.23, respectively for the $\tau - M_{\text{BH}}$ and $\nu_{\text{lag}} - M_{\text{BH}}$ relations. The fit significantly improves with respect to the fit with a constant model, yielding a $\chi^2 \sim 66$ and $\chi^2 \sim 17$ (respectively for the lag frequency and amplitude data sets) with the addition of one parameter (corresponding to a $\gtrsim 99.9$ per cent F-test probability). It is worth noting that the small scatter in the relation is consistent with being mostly due to the uncertainty in BH mass determination, being of the same order of the intrinsic scatter in reverberation mass estimates.

The best-fitting and the 1$\sigma$ combined uncertainty on the model parameters have been overplotted on the data in Fig. 4. We note that, although statistically not consistent with a linear relation, the best-fitting slopes increase and become consistent with linear scaling, if the data from the larger mass objects are treated as upper/lower limits for the lag frequency/absolute amplitude. Moreover, as pointed out in Section 3.2, the simulations of the observed lag profile revealed that red noise leakage plays a role in decreasing the intrinsic amplitude of the lag at low frequencies, thus affecting mostly the soft lag in high mass sources. A rough estimate yields a decreasing factor of $\sim 2$, with fluctuations depending on the shape of the PSD. Indeed, this effect is less important in low mass sources, where the amount of power below the lowest sampled frequency is smaller. Overall, correcting the observed $\tau - M_{\text{BH}}$ correlation for this bias would result in a steeper (i.e. with best-fitting value of 0.72 $\pm 0.11$) function of BH mass.

Finally, we checked whether the lag time-scales exhibit some dependence on the source X-ray luminosity between $E = 2$–$10$ keV (see Fig. 5), but a less significant correlation was found ($< 3\sigma$ and $< 2\sigma$, respectively, for $\tau$ and $\nu_{\text{lag}}$), which further decreases ($< 2\sigma$) when looking at the correlation with the bolometric luminosity (as computed using the correction factor by Marconi et al. 2004). These results support the hypothesis that the main parameter driving the correlation is the BH mass.

**Non-detections:** we checked whether the absence of a soft/negative lag in the remaining 17 sources may be real or due to poor statistics. Hence, for each lag–frequency spectrum we recorded the most negative-lag amplitude and its frequency in the interval where the coherence is not consistent with zero. We collected a total of 10 marginal soft lags with significance between 1–2$\sigma$ and 7 with significance $< 1\sigma$ (examples are shown in Fig. 2, while details on the 17 sources are listed in Table 2). Results are shown in left-hand panel of Fig. 6 (where, for brevity, only the $\tau - M_{\text{BH}}$ data points are displayed, overplotted on the 15 soft-lag detections...
at $>2\sigma$ confidence level), where the $>1\sigma$ detections are plotted with error bars, while the $<1\sigma$ are marked as 90 per cent upper limits. The agreement with the overall correlation is clear, with the significance increasing to $>5\sigma$ confidence level ($\rho \sim 0.73$ and 0.86, respectively for the frequency and amplitude versus BH mass correlations). We conclude that none of the remaining 17 sources is, with the available data, significantly outside the observed correlation and that all the sources are consistent with showing the same lag properties. The low detection significance of the soft lag in these sources is mainly due to poor statistics issues (e.g. limited exposure, small number of observations, low variability power, etc.), which are most relevant in large mass sources, where the expected lag frequency is of the order of the minimum sampled frequency.

4.1 Tests of the correlation

The correlations between the soft lag and BH mass presented in this paper have been derived assuming the minimum, single point in the negative-lag profile as representative of the intrinsic soft-lag time-scale. This choice is arbitrary, thus, to be more conservative, we estimated the effects of statistical fluctuations in the position of the soft lag minimum on the observed $v_{\text{lag}}$–$M_{\text{BH}}$ relation. To this aim, we made use of the Monte Carlo simulations generated to determine the confidence contours of the lag profile (see Section 3.2). These simulations assume as a template an interpolated lag function that describes the measured lag, whereby any deviation of the minimum from the observed one is due to statistical fluctuations. Hence, for each simulated lag profile we recorded the frequency of the minimum time lag, and used them to infer a mean frequency and standard deviation. These values were correlated with BH mass, to check if the observed correlation still holds. We found that statistical fluctuations in the position of the lag minimum have almost negligible effects, only slightly reducing Spearman’s rank correlation coefficient to $\rho \sim 0.78$ (i.e. bringing the null-hypothesis probability from $\sim 4 \times 10^{-4}$ to $\sim 7 \times 10^{-4}$), and increasing the scatter around the best-fitting model from $\sim 0.23$ to $\sim 0.26$. The fact that the difference with respect to results obtained using $v_{\text{lag}}$ measured values is small is due to the fact that, in general, the soft-lag profiles are not very broad in frequency. Thus the effects of statistical fluctuations on the position of the minimum within the soft-lag range of frequencies are negligible as compared to the scatter in the relation introduced by the uncertainties in the BH mass, and does not affect the stronger correlation between $\tau$ and BH mass.

It is worth noting that a good correlation is still present even when only the highest significance lags are taken into account. Indeed, carrying out a separate Spearman test on the $\tau$ versus $M_{\text{BH}}$ values for the $\gtrsim 3\sigma$ detections, and for those between 2 and $3\sigma$, we obtain a $\rho \sim 0.9$ in each case, which corresponds to a correlation significance of $\sim 99.8$ per cent. This is clearly visible in Fig. 6 (right-hand panel), where sources belonging to the two different groups are displayed using different colours/symbols. Moreover, if only the $\gtrsim 3\sigma$ detections lag points are taken into account in the fits with a linear model (in log–log space), the best-fitting slope parameter (i.e. $0.75 \pm 0.18$) is steeper than the value obtained from the whole data set (Section 4). Correction for red noise leakage leads to a further steepening of the correlation (with best-fitting value of $0.95 \pm 0.19$).
5 DISCUSSION

The systematic analysis of X-ray lags presented in this paper significantly increases the number of soft lags so far detected in AGN (15 out of 32 sources). The main result is the discovery of a highly significant ($>3\sigma$) correlation between the time-scales (frequency and amplitude) of the detected soft/negative lag and the BH mass. Moreover, data from the remaining 17 sources are consistent with the observed correlation, the significant detection of a soft lag being precluded only by poor statistics in these observations. Hence, we conclude that a soft lag, scaling with the mass of the BH, cannot be excluded in any of the 32 sources of our sample. This result confirms our previous inference (De Marco et al. 2011), whereby the negative lag detected in PG 1211+143 was suggested to represent the large mass counterpart of negative lags detected in lower mass sources (such as 1H 0707−495). Most importantly it highlights a fundamental property of soft lags, namely the fact that they depend on the BH mass. For example, in a reverberation scenario, this is naturally expected, given that the gravitational radius light-crossing time ($t_c = r_g/c$, where $r_g = GM/c^2$ is the gravitational radius) scales linearly with the mass of the central object. Although the inferred best-fitting slopes for the observed lag–$M_{BH}$ trends are statistically different from a linear relation, we notice that the data are biased against an intrinsically steeper dependence. Indeed, a steeper correlation is observed if the bias due to red noise leakage is taken into account (Section 3.2). The same correction leads to a one-to-one BH mass versus lag correlation if only the highest significance ($>3\sigma$) detections are considered in the fit (Section 4.1). Moreover, the large mass sources are sensitive to the length of the observation, which does not allow us to measure the lag profile over frequencies lower than the inverse of the observation length. Albeit not introducing any spurious correlation, the effect of these biases is to induce a flattening of the intrinsic one. Indeed, when the large BH mass data points are treated as upper/lower limits the slope of the correlations becomes even steeper (Section 4). A sample including longer and more sensitive observations would be necessary to accurately determine the real slope of the relation.

A thorough study of the implications of the lag–$M_{BH}$ correlation, as inferred from our analysis, on the proposed soft-lags models is beyond the aim of this paper. However, it is worth noting that a BH mass dependence of the characteristic time-scales is naturally expected in standard accretion disc models. In Fig. 4, we overplotted as a reference the light-crossing time at $1r_g$, $2r_g$ and $6r_g$ as a function of BH mass. The observed soft lags roughly lie in this range of time-scales, meaning that the involved distances are quite small and, again, mass dependent. Moreover, the evidence for a soft lag being present in such a large number of sources is at odds with expectations from models that need the single objects to be on a special line of sight for the measured lag to be observable (e.g. Miller et al. 2010). It is worth noting that, although the observed amplitudes of the soft lags roughly agree with the light-crossing time at small radii, associating a measured lag with a particular radius is not trivial (Wilkins & Fabian 2013). For instance, the observed lag is likely to be smaller than the intrinsic one due to the cross-contamination of primary and delayed spectral components in the two bands of interest (e.g. Miller et al. 2010), which introduces a dilution factor for the lag (see e.g. Kara et al. 2013a,b). Moreover, relativistic effects (e.g. Shapiro delay) are likely to play a major role which prevents us from trivially matching an observed time delay with a given distance. Another important aspect has been recently pointed out by Kara et al. (2013b) who show that the frequency and amplitude of the soft lag in IRAS 13224−3809 are in fact flux dependent. If this behaviour is ubiquitous, it will affect the measured lags at least in cases where the X-ray observation is not long enough to sample appropriately all different X-ray flux levels of a given source. This is likely to mostly affect the measured lags for the slowest varying highest BH mass sources in which a particular X-ray observation may be biased towards a particular flux state.

Overall these results are consistent with a scenario whereby the delayed soft excess emission originates in the innermost regions of the accretion disc, and is triggered by a compact central source of hard X-rays. Hence, a thorough understanding of soft lags properties will allow us to probe the physics and geometry of the innermost regions of AGN.

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