Scalable MCMC for Mixed Membership Stochastic Blockmodels

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Abstract

We propose a stochastic gradient Markov chain Monte Carlo (SG-MCMC) algorithm for scalable inference in mixed-membership stochastic blockmodels (MMSB). Our algorithm is based on the stochastic gradient Riemannian Langevin sampler and achieves both faster speed and higher accuracy at every iteration than the current state-of-the-art algorithm based on stochastic variational inference. In addition we develop an approximation that can handle models that entertain a very large number of communities. The experimental results show that SG-MCMC strictly dominates competing algorithms in all cases.

1 Introduction

Probabilistic graphical models represent a convenient paradigm for modeling complex relationships between a potentially very large number of random variables. Bayesian graphical models [13], where we define priors and infer posteriors over parameters also allow us to quantify model uncertainty and facilitate model selection and averaging. But an increasingly urgent question is whether these models and their inference procedures will be up to the challenge of handling very large “big data” problems.

A large subclass of Bayesian graphical models is represented by so called “topic models” such as latent Dirichlet allocation [4]. For these types of models very efficient inference algorithms have recently been developed, either based on stochastic variational Bayesian inference (SVB) [7,12] or on stochastic gradient Markov chain Monte Carlo (SG-MCMC) [2,3,5,6,19]. Both methods have the important property that they only require a small subset of the data-items for every iteration. In other words, they can be applied to (infinite) streaming data.

An important class of “big data” problems are given by networks. Large networks such as social networks easily run into billions of edges and tens of millions of nodes. An interesting problem in this area is the discovery of communities: densely connected groups of nodes that are only sparsely connected to the rest of the network. Large networks may contain millions of such communities. To model overlapping communities the mixed membership stochastic blockmodel (MMSB) was introduced in [8]. Very recently, an efficient stochastic variational inference algorithm was developed for a special case, the assortative MMSB (a-MMSB) [1], greatly extending the reach of Bayesian posterior inference to realistic large scale problem settings. Inspired by this work, and earlier comparisons between SVB and SG-MCMC on LDA [2] we developed a scalable SG-MCMC algorithm for a-MMSB and compared it against SVB on the community detection problem.

Our conclusion is consistent with the findings of [2], namely that SG-MCMC is also both faster and more accurate than SVB algorithms in this domain. While one should expect SG-MCMC to be more accurate than SVB asymptotically (SVB is asymptotically biased while SG-MCMC is not), it is interesting to observe that SG-MCMC dominates SVB across all iterations, despite the fact that SG-MCMC should have a larger variance contribution to the error.

2 Assortative Mixed-Membership Stochastic Blockmodels

Assortative mixed-membership stochastic blockmodel (a-MMSB) [1] is a special case of MMSB [8] that models the group-structure in a network of $N$ nodes. In particular, each node $a$ in the node set $V^*$ has a $K$-dimension probability distribution $\pi_a$ of participating in the $K$ members of the community set $\mathcal{K}$. For every
possible peer b in the network, each node a randomly
draws a community zab. If a pair of nodes (a, b) in the
edge set E∗ are in the same community: zab = zba = k,
then they have a significant probability βk to connect,
i.e., yab = 1. Otherwise this probability is small. Each
community has its connection strength βk ∈ (0, 1)
which explains how likely its members are linked to
each other.

The generative process of a-MMSB is then given by,
1. For each community k, draw community strength
   βk ∼ Beta(η)
2. For each node a, draw community memberships
   πa ∼ Dirichlet(α)
3. For each pair of nodes a and b,
   (a) Draw interaction indicator zab ∼ πa
   (b) Draw interaction indicator zba ∼ πb
   (c) Draw link yab ∼ Bernoulli(r), where r = βk
       if zab = zba = k, and r = δ otherwise.

Unlike the a-MMSB, the original MMSB maintains
pair-wise community strength βk,k′ for all pairs of the
communities. Note that it is trivial to extend the re-
results that we obtain in this paper to the general MMSB
model. The joint probability of the above process can be
written as:

\[
p(y, z, π, β|α, η) = \prod_{a=1}^{N} \prod_{b>a}^{N} p(y_{ab}|z_{ab}, z_{ba}, β) p(z_{ab}|π_a) \prod_{a=1}^{N} p(π_a|α) \prod_{k=1}^{K} p(β_k|η).
\]

Both variational inference [1,4,16] and collapsed Gibbs
sampling algorithms [11] have been used successfully
for small to medium scale problems. However, the
O(N^2) computational complexity per update prevents
it from being applied to large scale networks. A
stochastic variational algorithm was developed in [1]
to address this issue, where each update only depends
on a small mini-batch of the nodes in the network.

3 Stochastic Gradient MCMC

Algorithms

Our algorithm will be based on the stochastic gradient
Langefin dynamics (SGLD) [3]. To sample from a pos-
terior distribution p(θ|X) ∝ p(X|θ)p(θ) given N i.i.d.
data points X = {x_i}^N_{i=1}, SGLD applies the follow-
ing update rule:

\[
θ^* \leftarrow θ + \epsilon \left( \nabla_θ \log p(θ) + N \frac{∂g(θ; D_n)}{∂θ} \right) + ξ,
\]

where ξ ∼ N(0, ε) with ε the step size, D_n a mini-
batch of size n sampled from X, and

\[
g(θ; D_n) = \frac{1}{|D_n|} \sum_{x \in D_n} \nabla_θ \log p(x|θ).
\]

As the step size goes to zero by a schedule satisfying
\[\sum_{i=1}^{∞} \epsilon_i = ∞ \text{ and } \sum_{i=1}^{∞} \epsilon_i^2 < ∞,\]
SGLD samples from the true posterior distribution.

In SGLD, the Metropolis-Hastings (MH) accept-reject
tests are ignored since the rejection probability goes
to zero as the step size collapses to zero. While for
a finite step size this results in some bias, the overall
error is reduced by the reduction of variance due to
the ability to draw many more samples per unit time.

SGLD originated from the Langevin Monte Carlo
(LMC) [15] where, unlike SGLD, the gradient is
computed exactly using all data points and then a
Metropolis-Hastings accept-reject test is applied. Be-
cause at each iteration SGLD requires to process only a
mini-batch D_n and ignores the MH test, the computa-
tion complexity per iteration is only O(n) as opposed
to O(N) of LMC. Any mini-batch sampling algorithm
in the form of Eqn. (2) is called valid SGLD as long as
it guarantees the gradient estimator to be unbiased,
i.e., \[\mathbb{E}_{D_n}[N \frac{∂g(θ; D_n)}{∂θ}] = \nabla_θ \log p(X|θ)\]
and the variance to be finite [5].

The stochastic gradient Riemannian Langevin dynami-
cs (SGRLD) [2] is a subclass of SGLD which is devel-
oped to sample from the probability simplex. By ap-
plying Riemannian geometry [15] and using the mini-
batch estimator in Eqn. 2, it achieved the state-of-the-
art performance for latent Dirichlet allocation (LDA).
In particular, for a K-dimensional probability sim-
plex π, it uses the expanded-mean re-parameteriza-
tion trick, where the probability of a category k is given
by π_k = θ_k / \sum_{j=1}^{K} θ_j with θ_k ∼ Gamma(α, 1) and α
a hyperparameter of the Dirichlet distribution p(π|α).

Then, the update rule becomes

\[
θ_k \leftarrow \theta_k + \epsilon \left( \alpha - θ_k + \frac{N}{|D_n|} \sum_{d \in D_n} g_d(θ_k) \right) + (θ_k)^{2} ξ.
\]

here g_d(θ_k) is the gradient of the log posterior w.r.t.
θ_k on a data point d ∈ D_n.

4 Scalable MCMC for a-MMSB

Our algorithm iterates updating local parameters π
and a global parameter β. Because both parameters lie
on the probability simplex, we start from the SGRoL
and modify it to be more efficient. Also, we introduce
parameters φ and θ to re-parameterize π and β respec-
tively. Then, we alternatively sample in the φ and θ
spaces, and obtain π and β by normalizing φ and θ.

From Eqn. 1, summing over the latent variable z, we
obtain the following joint probability,
\[ p(y, \pi, \beta | \alpha, \eta) = \prod_a p(\pi_a | \alpha) \prod_k p(\beta_k | \eta) \times \prod_{b>a} \sum_{z_{ab}, z_{ba}} p(y_{ab}, z_{ab}, z_{ba} | \beta, \pi_a, \pi_b). \]

(4)

### 4.1 Sampling the global parameter

By the re-parameterization, we have \( \beta_k = \theta_{ki} / (\theta_{ki} + \theta_{k1}) \), where \( \theta_{ki} \sim \text{Gamma}(\eta) \propto \theta_{ki}^{\eta-1} e^{-\theta_{ki}} \). Because \( p(y, \pi, \beta | \alpha, \eta) \) decomposes into \( p(y_{ab}, \beta | \pi, \eta) p(\pi | \alpha) \), replacing \( \beta \) by \( \theta \), we compute the derivative of the logarithm of Eqn. 4 w.r.t. \( \theta_{ki} \) for \( i = \{0, 1\} \) as follows:

\[ \frac{\partial \ln p(y, \pi | \eta, \theta)}{\partial \theta_{ki}} = \frac{\partial}{\partial \theta_{ki}} \ln p(\theta_{ki}) + \sum_a \sum_b g_{ab}(\theta_{ki}), \]

(5)

where \( g_{ab}(\theta_{ki}) = \frac{\partial}{\partial \theta_{ki}} \ln \sum_{z_{ab}, z_{ba}} p(y_{ab}, z_{ab}, z_{ba} | \pi_a, \pi_b) \) which, similar to SGRLD for LDA [2], we can rewrite as

\[ g_{ab}(\theta_{ki}) = \mathbb{E} \left[ (z_{ab} = z_{ba} = k) \left( \frac{1 - i - y_{ab}}{\theta_{ki}} - \frac{1}{\theta_k} \right) \right]. \]

(6)

Because the global parameters \( \{\beta_k\} \) does not change very fast compared to the local parameters \( \{\pi_{ak}\} \), in practice we update only a random subset of the \( \{\beta_k\} \) at each iteration.

### 4.2 Sampling the local parameters

Similar to the global parameter, we re-parameterize the local parameter \( \pi_a \) such that \( \pi_{ak} = \phi_{ak} / \sum_j \phi_{aj} \), with \( \phi_{ak} \sim \text{Gamma}(\alpha) \propto \phi_{ak}^{\alpha-1} e^{-\phi_{ak}} \). Then, taking the derivative of the log of Eqn. 4 w.r.t. \( \phi_{ak} \), we obtain

\[ \frac{\partial \ln p(y, \phi | \beta, \alpha)}{\partial \phi_{ak}} = \frac{\partial}{\partial \phi_{ak}} \ln p(\phi_{ak} | \alpha) + \sum_b g_{ab}(\phi_{ak}). \]

(11)

where \( g_{ab}(\phi_{ak}) = \frac{\partial}{\partial \phi_{ak}} \ln \sum_{z_{ab}, z_{ba}} p(y_{ab}, z_{ab}, z_{ba} | \beta, \phi_a, \phi_b) \) which can be written as

\[ g_{ab}(\phi_{ak}) = \mathbb{E} \left[ (z_{ab} = k) \left( \frac{1}{\phi_{ak}} - \frac{1}{\phi_a} \right) \right]. \]

(12)

Here the expectation is w.r.t. the distribution in Eqn. (8). To compute the expectation analytically, we first integrate over \( z_{ba} \) from Eqn. (8) because the expectation depends only on \( z_{ab} \) and obtain the following probability up to a normalization constant

\[ f_{ab}^{(y)}(k, l) = \sum_{l=1}^{K} f_{ab}^{(y)}(k, l) \]

\[ = \pi_{ak} \left( \frac{\beta_{yk}}{\beta_k} (1 - \beta_k)^{1-y} \pi_{bk} + \delta y (1 - \delta)^{1-y} (1 - \pi_{bk}) \right). \]

(13)

Then we obtain the normalization term by \( Z_{ab}^{(y)} = \sum_{k=1}^{K} f_{ab}^{(y)}(k) \). Integrating out the expectation in Eqn.
(12), we obtain
\[ g_{ab}(\phi_{ak}) = \frac{f_{ab}(k)}{Z^{(y)}_{ab}(k)} - \frac{1}{\phi_a}. \quad (14) \]

Plugging this to Eqn. 3, we obtain the SGRLD update rule for the local parameter \( \phi_{ak} \)
\[ \phi_{ak} \leftarrow \phi_{ak} + \frac{\epsilon}{2} \left( \alpha - \phi_{ak} + \frac{N}{|V_n|} \sum_{b \in V_n} g_{ab}(\phi_{ak}) \right) \]
\[ + (\phi_{ak})^{2} \xi_{ak}. \quad (15) \]

Here, the \( V_n \) is a random mini-batch of \( n \) nodes sampled from \( V^* \). Note that \(|V_n| < |V^*| = N\).

### 4.3 Scalable local updates for a large number of communities

In some applications, the number of communities can be very large \cite{18} so that the local update becomes very inefficient due to its \( O(K|V_n|) \) computation per node in \( E_n \), and also \( O(KN) \) space complexity. In this section, we extend the above algorithm further with a novel approximation in order to make the algorithm scalable in terms of both speed and memory usage even for a very large number of communities which the SVI \cite{1} approach cannot achieve.

**Community split:** For each node \( a \in V^* \), we first split the community set \( K \) into three mutually exclusive subsets: the *active set* \( A(a) \), the candidate set \( C(a) \), and the *bulk* set \( B(a) \) such that \( A(a) \cup C(a) \cup B(a) = K \). Then, sorting the \( \pi_a \) w.r.t. \( k \) in descending order, we obtain a new order of communities \( k_1, \ldots, k_K \). The active set \( A(a) \) contains communities whose cumulative distribution function \( F(k_i) \) is less than a threshold \( \tau \in (0, 1) \), i.e., \( A(a) = \{k_i \in K | F(k_i) < \tau \} \). The candidate set \( C(a) \) includes communities which are in the active set of at least one of the neighbors of node \( a \), i.e., \( C(a) = \{k \in K \setminus A(a) \exists b \in N(a) \text{ s.t. } k \in A(b)\} \). The bulk set \( B(a) \) contains all the remainder, i.e., \( B(a) = K \setminus (A(a) \cup C(a)) \). Here, we use \( N(a) \) to denote the neighbors of node \( a \).

The rationale behind this split scheme is twofold. First, due to *sparsity*, at each node only a small number of communities will have meaningful probability while a large number of communities will have very low probability \( \pi_{ak} \). We want the communities of low probability to belong to the bulk set, to share a single probability \( \pi_{ak} \), and thus to be updated by one-shot for all \( k \in B(a) \). We use \( K \) to represent the representative community of a bulk set. Second, due to the *locality*, neighboring nodes are likely to have a similar distribution over communities (after all, the model only assigns high probability to links when the associated nodes have high probability of sampling the same community). That is, when a neighbor of node \( a \) has a community \( k \) in its active set, this community may be a good candidate to become active for node \( a \) as well. By maintaining a candidate set we allow communities to spread efficiently to neighboring nodes and thus through the network.

**One-shot update:** For communities \( k \in B(a) \), we apply the following approximation of the unnormalized probability in Eqn. (13)
\[ f_{ab}(k \in B(a)) \approx \tilde{f}_{ab}(\kappa) \]
\[ = \pi_{ak} \left\{ \beta_{a}^{(1-y)}(1-\beta_{a}(1-y)\bar{\pi}_{b} + \delta_{a}^{(1-y)}(1-\delta)(1-y)(1-\bar{\pi}_{b}) \right\}. \quad (16) \]

That is, we replace \( \pi_{bk} \) and \( \beta_{k} \) in Eqn. (13) by \( \bar{\pi}_{b} = \frac{1}{m} \sum_{k \in B_{b}(a)} \pi_{bk} \) and \( \beta_{a} = \frac{1}{m} \sum_{k \in B_{a}(a)} \beta_{k} \) respectively using a random mini-batch \( B_{b}(a) \) of size \( m \) sampled from \( B(a) \). As a result, all \( k \in B(a) \) share a single value \( \tilde{f}_{ab}(\kappa) \). Therefore, we can efficiently approximate the normalization constant by
\[ Z_{ab}^{(y)} = \sum_{k \in K} f_{ab}(k) \approx \tilde{Z}_{ab}^{(y)} \]
\[ = |B(a)| \tilde{f}_{ab}(\kappa) + \sum_{k \in B(a)} f_{ab}(k). \quad (17) \]

Note that we only sum over \( |A(a) \cup C(a)|+1 \) terms which will be a much smaller size than \( |B(a)| \). Now, to compute the gradient efficiently, we apply the stratified sampling\(^1\) for \( V_n \) by sampling \( n_{1} \) nodes \( V_{1} \) from the neighbors \( N(a) \) and \( n_{0} \) nodes \( V_{0} \) from non-neighbors \( V^* \setminus N(a) \) such that \( V_n = V_{1} \cup V_{0} \). Then, the sum of gradients for \( V_n \) in Eqn. (15) is obtained by
\[ \sum_{b \in V_n} g_{ab}(\phi_{ab}) \approx c_1 \left( \sum_{b \in V_1} \left( \frac{\tilde{f}_{ab}(k)}{Z_{ab}^{(y)}} - \frac{1}{\phi_{a}} \right) + c_0 \sum_{b \in V_0} \left( \frac{\tilde{f}_{ab}(k)}{Z_{ab}^{(y)}} - \frac{1}{\phi_{a}} \right) \right). \quad (18) \]

Here, we set \( c_1 = |N(a)|/n_1 \) and \( c_0 = (N - |N(a)|)/n_0 \) to ensure the unbiasedness of the gradient under stratified sampling. Again, it is important to note that all states in \( B(a) \) share a single current value \( \phi_{ak} \) and also the same update equation of Eqn. (18). Thus for \( B(a) \) we compute Eqn. (18) only once and update all of them in one-shot. The computation cost becomes \( O(|A(a) \cup C(a)| |V_n|) \) per node in \( E_n \), which we expect to be efficient because \( |A(a) \cup C(a)| \ll K \) due to sparsity. For \( k \notin B(a) \), we simply replace \( \tilde{f}_{ab}(k) \) in Eqn. (18) by \( f_{ab}(k) \) in Eqn. (13), and update individually.

\(^1\)Note that, to be more efficient under the approximation, we use a sampling method which is different to the method used in the global update.
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Algorithm 1 Pseudo-code for each sampling iteration $t$

1: Sample a mini-batch $E$ of $n_t$ node pairs from $\mathcal{E}^*$
2: for each node $a$ in $\mathcal{E}$ do
3: Sample a mini-batch of nodes $\mathcal{V}_n(a) = \mathcal{V}_1(a) \cup \mathcal{V}_0(a)$ from $\mathcal{V}^*$
4: Update $\phi_{ak}$ for all $k \in \mathcal{A}(a) \cup \mathcal{C}(a)$ using Eqn. (18) and Eqn. (15)
5: Update $\phi_{a\kappa}$ only for the representative bulk state $\kappa$ using Eqn. (18) and Eqn. (15)
6: Sort and normalize to obtain $\{ \pi_{ak} \}$ and the cdf $F(k_i)$ for all $|\mathcal{A}(a) \cup \mathcal{C}(a)|+1$ states
7: Promote or demote some states using the updated cdf, threshold $\tau$, and neighbor information
8: end for
9: for $k$ in a random subset of $\mathcal{K}$ do
10: Update $\theta_{k(0,1)}$ by Eqn. (10) using $\mathcal{E}$ and obtain $\beta_{k}$ from $\theta_{k(0,1)}$
11: end for

Promotion and demotion: after updating all $|\mathcal{A}(a) \cup \mathcal{C}(a)|+1$ states (communities), we need to update the community split by promoting (e.g. to active or candidate set) or demoting (e.g. to candidate or bulk set) some of the states. To do this, we sort and normalize $\{ \phi_{ak} \}$, and obtain the updated cdf $F(k_i)$. Then, we update $\mathcal{A}(a), \mathcal{C}(a)$, and $\mathcal{B}(a)$ based on the threshold $\tau$ and based on the communities that are active in the neighboring nodes. In particular, if the cdf of the bulk state $F(\kappa)$ is less than the threshold, we promote some states in the bulk set by a random sampling. In this case, the number of states to promote is equal to int((\tau - F(\kappa_{-1}))/\pi_{a\kappa}). Here $\kappa_{-1}$ denotes a state just left to the $\kappa$ in the sorted community sequence. We sample a state from the pool of states that are yet not represented anywhere in the graph. The reason is that we wish to avoid creating disconnected communities of nodes, which we believe represent suboptimal local nodes in the posterior distribution. Finally, we check which states in $\mathcal{B}(a)$ can be promoted to $\mathcal{C}(a)$ by checking the neighboring nodes. We provide the pseudo code of the above algorithm in the Algorithm 1.

5 Experiments

We evaluate the efficiency and accuracy of our algorithm on five datasets [18]: Synthetic [1], US-AIR, NETSCIENCE, RELATIVITY, and HEP-PH, summarized in Table 1. (The last column is the percentage of link edges among all possible edges.) We compare four algorithms. As exact batch-mode MCMC methods, we use collapsed Gibbs sampling (CGS) and Langevin Monte Carlo (LMC). We also compare to SVI [1] as a state-of-the-art method in variational Bayes. Finally, two of our algorithms are tested, one with and the other without the approximation for large communities. We call these SGMC and SGMC-M, respectively.

We used $\alpha = 1/K$ and $\eta = 1$ for all of the models and for all experiments unless otherwise stated. For the stepsize annealing schedule we used $\varepsilon_t = (\tau_0 + t)^{-\kappa}$ with $\kappa = 0.5$ and $\tau_0 = 1024$ [2]. For the stratified sampling of the global update in SVI and SGMCs, we used $m$ such that the size of non-link edges $N/m$ to be 30 $< N/m < 100$. And for the mini-batch size of the stratified sampling of the local update in SGMCs, we used 20 samples with 10 from neighbors and 10 from non-neighboring nodes. For SGMC-M, we used the threshold $\tau = 0.9$ by default unless otherwise stated. Also, for the held-out test set, we used 1% of the total links and non-links.

As the performance metric, we use perplexity which is defined as exponential of the negative average log-likelihood of the data. Given a collection of $T$ samples of the model parameters $\{ \beta_t \}$ and $\{ \pi_t \}$, the averaged perplexity on the held-out test set $\mathcal{E}_h$ is

$$
\text{perp}_{avg}(\mathcal{E}_h|\{\beta_t\},\{\pi_t\}) = \exp\left(-\frac{1}{|\mathcal{E}_h|} \sum_{(a,b) \in \mathcal{E}_h} \log\left(\sum_{t=1}^{T} p(y_{ab}|\beta_t, \pi_t)\right)\right)
$$

(19)

5.1 Results

Comparison to exact batch MCMC: We first show the accuracy of our algorithm in comparison to exact batch-mode MCMC algorithms (CGS and LMC). For this, we use two relatively small datasets, Synthetic and US-AIR, due to the slow speed of the batch algorithms. The results are shown in Fig. 1a and Fig. 1b.

As expected, for the smaller dataset (Synthetic) in Fig. 1a, we see that CGS converges very fast. However, it is interesting to observe that our stochastic gradient sampler (SGMC) using fixed step-size converges to the same level of accuracy in comparable time, whereas LMC converges much slower than both the collapsed
Gibbs sampler and our algorithm due to its full gradient computation and the Metropolis-Hastings accept-reject step. As we move to a larger network (US-AIR) in Fig. 1b, we begin to see that our stochastic gradient sampler outperforms in speed the collapsed Gibbs sampler as well as the Langevin Monte Carlo. It is interesting to see that the approximation error of our algorithm due to the finite step size and the absence of accept-reject tests is negligible compared to the perplexity of the exact MCMC.

Effect of our approximation for large communities: In Fig. 2a and Fig. 2b, Fig. 2c on three large datasets, HEP-PH, NETSCIENCE and RELATIVITY, we show the speed-up effect of our approximate method (SGMC-M) compared to the SGMC without the approximation. Here we measure the time per iteration for various community size $K = \{30, 50, 100, 200, 300, 500, 1000\}$ and set the threshold to $\tau = 0.9$. As shown, we can see that the approximate method SGMC-M only slightly increases the wall-clock time per iteration even if the community size increases. However, without the approximation (SGMC), the time per iteration increases linearly w.r.t. the community size. In fact, we can obtain more time savings as the community size increases further because the level of sparsity, i.e. the number of communities for which each node has non-negligible probability of participation, does not change much when we increase $K$.

Furthermore, it is interesting to see in Fig. 3a, Fig. 3b and Fig. 3c that we do not lose much accuracy despite the approximation. In particular, for Fig. 3b, the SGMC-M performs as good as the SGMC. Although for Fig. 3c the SGMC-M performs worse than the SGMC, it still outperforms the SVI. Note that the results are based on converged perplexity which SGMC-M will reach much faster. The figures also reveal some interesting facts. First, the predictive accuracy is dominated by SGMC for all choices of $K$. Second, the curve of SVI has a V-shape indicating that the optimal value for $K$ is in between the minimum and maximum value of $K$ we tested. However, for SGMC the accuracy remains relatively stable as we increase $K$, making it less sensitive to the choice of this hyperparameter.

In Fig. 4, we show the convergence of perplexity over wall-clock time on several datasets using SGMC, SGMC-M and SVI. Note that we do not include the SVI method in Fig. c and Fig. 4d where we use a large community size, since the perplexity tends to
become very large and thus makes it incomparable to our methods. In general, we have two main observations. First, the approximate method SGMC-M dominates other methods during early stages, but eventually SGMC reaches lower perplexity than SGMC-M. Second, in Fig. 4b and Fig. 4b, both SGMC and SGMC-M reach much lower perplexity than SVI. In general, we have two main observations. First, the approximate method SGMC-M dominates other methods during early stages, but eventually SGMC reaches lower perplexity than SGMC-M. Second, in Fig. 4b and Fig. 4b, both SGMC and SGMC-M reach much lower perplexity than SVI.

In Fig. 5a, we show the efficiency of SGMC-M in terms of memory usage. In this experiment, we set the threshold $\tau = 0.9$ for all datasets. As shown, the memory usage (i.e. $|\mathcal{A}(a) \cup \mathcal{C}(a)|/K$) of SGMC-M decreases as the number of communities increases. This is because the sparsity does not change even if we increase the community size $K$. Note that the memory usages of SVI and SGMC are always 100%. This is a significant feature for large scale networks because without the approximation the space complexity is $O(KN)$ where both $K$ and $N$ can be very large [18]. It is also interesting to see that at every node 90% of the total density is allocated to only about 10% $\sim 20\%$ of the communities (e.g., for $K=500,1000$).

Lastly, we investigate the effect of the threshold $\tau$ and the results are shown in Fig. 5b and Fig. 5c using Synthetic and US-AIR datasets. As shown, with $\tau = 0.9$ and $\tau = 1$, we obtain the best result. It is interesting because the memory usage of SGMC-M is only a half of SGMC without the approximation ($\tau = 1$). As expected, as we decrease the threshold, smaller communities are represented in the active and candidate set and thus we lose some accuracy while gaining some speed-up.

Effect of step sizes: SG-MCMC converges in theory as the step size goes to zero. Although we have used decreasing step sizes in the above experiments, it will be interesting to see how fixed step sizes affect the algorithm, because in practice we cannot decrease the step size to zero. One of the result is shown in Fig. 6a. The figure clearly reveals the trade-off between a large step size (leading to a large bias) and a small step size (leading to slow mixing). For the US-AIR dataset a step size 0.01 seems to work best.

Mini-batch size and computational efficiency: Depending on the number of edges/nodes sampled in a mini-batch, there is a clear trade-off between the computational cost per update and the variance of an update (i.e. for stochastic gradients). Our SG-MCMC includes two sampling steps for each iteration, one for edges and the other for nodes (line 1 and 3 in Algorithm 1). Since we are using a “stratified random
node sampling\(^2\) strategy, it is important to choose a proper \(m\) in order to obtain both fast convergence and low variance. We tested the effects of the parameter \(m\). The results are shown in Fig. 6b and Fig. 6c. As we can see, setting \(m\) to 5 achieves the best performance for the synthetic dataset while \(m = 20\) performs best for the US-AIR data set.\(^5\) In practice, setting \(m\) in such a way that the corresponding mini-batch size becomes between 30 and 100 results in good performance, i.e. if we have 10K nodes in total, we could set \(m\) to a value between 100-350.\(^3\) Overall, SG-MCMC takes \(O(n^2K)\) computational time\(^4\) for each iteration, where \(n = N/m\) and \(N\) is the total number of the nodes.

6 Conclusion and Future Work

In this paper we have developed a new scalable MCMC algorithm based on stochastic gradient computations for assortive mixed membership stochastic blockmodels (a-MMSB). The algorithm represents a natural extension of stochastic gradient Riemannian Langevin dynamics (SGRLD) \(^2\) to a-MMSBs. In line with the results reported in [2] for LDA, SGRLD also significantly outperforms its stochastic variational Bayesian counterpart. As was shown in [18], SGRLD algorithms are particularly suited for distributed implementation. We are currently working towards a distributed implementation of our algorithm on a HPC infrastructure allowing us to perform full Bayesian inference on the very large “Friendster” network with almost two billion edges. Initial results show that we achieve good perplexity and sample to convergence on the full network.

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References


