An Optical Bow Shock around the Nearby Millisecond Pulsar J2124-3358

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AN OPTICAL BOW SHOCK AROUND THE NEARBY MILLISECOND PULSAR J2124−3358

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ABSTRACT

We report the discovery of an Hα-emitting bow shock nebula powered by the nearby millisecond pulsar J2124−3358. The bow shock is very broad and is highly asymmetric about the pulsar’s velocity vector. This shape is not consistent with that expected for the case of an isotropic wind interacting with a homogeneous ambient medium. Models that invoke an anisotropy in the pulsar wind, a bulk flow of the surrounding gas, or a density gradient in the ambient medium either perpendicular or parallel to the pulsar’s direction of motion also fail to reproduce the observed morphology. However, we find an ensemble of good fits to the nebular morphology when we consider a combination of these effects. In all such cases, we find that the pulsar is propagating through an ambient medium of mean density 0.8−1.3 cm−3 and bulk flow velocity ∼15−25 km s−1 and that the star has recently encountered an increase in density by 1−10 cm−3 over a scale ≲0.02 pc. The wide variety of models that fit the data demonstrate that in general there is no unique set of parameters that can be inferred from the morphology of a bow shock nebula.

Subject headings: ISM: general — pulsars: individual (PSR J2124−3358) — stars: neutron — stars: winds, outflows

On-line material: color figure

1 INTRODUCTION

Many pulsars experience significant ram pressure as they move through the interstellar medium (ISM). This pressure can confine the pulsar’s relativistic wind and generate a bow shock pulsar wind nebula (PWN). The Hα emission generated by such sources provides an important probe of the pulsar’s interaction with its environment (see Chatterjee & Cordes 2002 for a recent review). However, until recently only three Hα PWNe were known, and we consequently have lacked a detailed understanding of this phenomenon.

We are carrying out a survey for new pulsar bow shocks in the southern sky. We have previously reported the discovery of a faint Hα PWN surrounding PSR B0740−28 (Jones, Stappers, & Gaensler 2002). We here present another new Hα pulsar bow shock, associated with the nearby millisecond pulsar J2124−3358 (Bailes et al. 1997). A recent timing ephemeris (M. Bailes 2002, private communication) yields a spin period of 4.93 ms and a position (at MJD 50,288.0) of R.A. (J2000.0) = 21h24m43.86196(6), decl. (J2000.0) = −33°58′44″257(1), where the numbers in parentheses indicate the uncertainty in the last digit. The pulsar’s intrinsic spin-down luminosity is $\dot{E} = 4.3 \times 10^{33}$ ergs s−1 (Toscano et al. 1999), while its dispersion measure of 4.61 pc cm−3 implies a distance of 270 ± 20 pc (Cordes & Lazio 2002). In this Letter, we adopt a distance $D = 270d_0$ pc to the source.

The pulsar timing ephemeris yields a proper motion relative to the solar system barycenter of 52.6(3) mas yr−1 at position angle 195°(3) (north through east). Because of the pulsar’s proximity and low space velocity, the peculiar motion of the Sun with respect to the local standard of rest needs to be accounted for. In the case of PSR J2124−3358, the Sun’s motion is directed almost perpendicular to the line of sight and so contributes a significant component of the observed proper motion. After correction for the solar peculiar velocity (and for the small effects of differential Galactic rotation), we find that the motion of the pulsar relative to its local standard of rest is $47(3)$ mas yr−1 at position angle 209(3)°, corresponding to a projected space velocity of $(61 \pm 4)d_0$ km s−1. The uncertainties in the direction and magnitude of the solar motion dominate those in the pulsar’s distance and measured proper motion.

2 OBSERVATIONS AND RESULTS

The field around PSR J2124−3358 was observed for 4800 s on 2001 July 25 (MJD 52,115) with a narrowband Hα filter on the 3.5 m New Technology Telescope (NTT) at the European Southern Observatory, La Silla, Chile. The mean seeing was $\sim$1.2; all other observational parameters were as described by Jones et al. (2002). Standard techniques for bias and flat-field correction were used to remove instrumental signatures from the data. Individual frames were dithered to permit removal of CCD defects and cosmic rays using median filtering on the frames when combined. An astrometric solution was determined using 10 field stars with positions in the USNO Catalog. The IRAF task CCMAP was used to fit the positions with a third-order polynomial with cross terms. The rms scatter was $(\Delta\alpha, \Delta\delta) = (\pm0.15, \pm0.07)$ and the residuals uniformly scattered. A transformation of the derived USNO star coordinates back onto the image did not reveal any systematic offsets between the observed and derived positions.

Figure 1 shows a smoothed Hα image of the field surrounding PSR J2124−3358. The position of the pulsar at epoch MJD 52,115 is marked, as is the pulsar’s direction of motion with respect to its local standard of rest. The pulsar is located just inside the apex of an optical nebula with a clear bow shock morphology, while the pulsar’s projected velocity points within...
3. DISCUSSION

The position, speed, and direction of motion of PSR J2124–3358 have all been determined to reasonably high precision (see § 1). This system thus presents an excellent opportunity to model a bow shock PWN and to constrain its parameters.

To quantify the properties of this nebula, we consider a pulsar of space velocity \( V \) moving through an ambient medium of mass density \( \rho \), and number density \( n \). We define the “standoff distance,” \( R_p \), to be the characteristic scale size of the nebula. For an idealized bow shock, \( R_p \) is the distance from the pulsar to the apex of the bow shock along the direction of motion. The corresponding “standoff angle” \( \theta \), to be the angular separation between the pulsar and the outermost edge of the projected H\( \alpha \) emission along the projected direction of the pulsar’s motion. In general, \( \psi_0 \) is the only parameter that can be directly measured from an image; in this case, \( \psi_0 \approx 29^\circ \).

We crudely estimate the parameters of the system by assuming that \( i = 90^\circ \) and that the outer edge of the observed H\( \alpha \) emission demarcates the bow shock structure. In this case, \( \theta_0 \approx \psi_0 \) and so \( R_p \approx 0.003 \, d_0 \, \text{pc} \). At the standoff distance, pressure from the pulsar wind, \( P_{\text{psr}} = E/4\pi R_p^2 c \), balances the ram pressure of the ambient medium, \( P_{\text{ISM}} = \rho_{\text{ISM}} V^2 \), so that \( n_0 = 1.6d_0^{-2} \, \text{cm}^{-3} \). This confirms that the pulsar is embedded in the warm, neutral component of the ISM (e.g., Kulkarni & Heiles 1988), as expected for observable H\( \alpha \) bow shocks. The corresponding ISM sound speed is \( c_s \approx 5 \, \text{km s}^{-1} \), and the Mach number for the pulsar is \( M = V/c_s \approx 12 \).

We now consider the detailed morphology of the head of the nebula. We first rotate the image counterclockwise by \( 61^\circ \), so that the pulsar’s motion is strictly from left to right, and adopt an \((x, y)\) coordinate system with the pulsar at the origin. We then by hand identify a series of points that demarcate the outermost boundary of the head of the optical nebula, over an azimuthal range of \( \pm 120^\circ \) on either side of the pulsar’s direction of motion. The resulting data points can then be fitted with a variety of functional forms. We note that variations in thickness and brightness seen in the nebula potentially provide additional information on the pulsar’s interaction with its environment. However, to use these data, one must take into account the width and surface density of the emitting regions as a function of position and also must consider the effects of charge exchange and collisional excitation (Bucciantini & Bandiera 2001; Bucciantini 2002b). Given these considerable complications, here we consider only the overall shape of the emitting regions, as delineated by the outermost edge of the H\( \alpha \) nebula.

We first consider the idealized case of an isotropic wind propagating through a homogeneous ambient medium. In this case, the shape of the bow shock surface is given by (Wilkin 1996)

\[
R(\phi) = \kappa R_p / \sin \phi \sqrt{3(1 - \phi / \tan \phi)},
\]

where \( R(\phi) \) is the distance from the pulsar to a given point on the bow shock surface, \( \phi \) is the angle between the velocity vector and the vector joining the pulsar to this point, and \( \kappa \) is a constant, with value \( \kappa = 1 \) in this case.

In Figures 2a and 2b, we show solutions to equation (1) for \( i = 90^\circ \) and \( i = 30^\circ \), respectively, scaled to match the data so that for \( \phi = 0^\circ \), the angular separation between the pulsar and the outermost edge of the bow shock surface is \( \psi_0 \approx 29^\circ \).
Fig. 2.—Models of the bow shock nebula powered by PSR J1214−3358. The nine panels correspond to nine of the models listed in Table 1. In each panel, the data points (blue) represent the outer profile of the observed bow shock, the star symbol (red) indicates the position of the pulsar, and the mesh corresponds to the surface of the model bow shock. In each case, the model bow shock solutions are plotted over the range $-140^\circ \leq \phi \leq 140^\circ$. [See the electronic edition of the Journal for a color version of this figure.]

fit parameters for each solution are listed in Table 1. (As an aside, we note that unless $i = 90^\circ$, the usual assumption that $\theta_o = \psi_o$ is incorrect. For example, for the inclined case $i = 30^\circ$ we find that $\theta_v = kR_0 \sin i/l = 0.8 \ll \psi_o$. This indicates that in cases where the inclination angle is not known, the first-order assumption that $\theta_v = \psi_o = kR_0/D$ results in an upper limit on $kR_0$ and a lower limit on $\psi_o$, in contrast to previous calculations [see, e.g., § 5.1 of Chatterjee & Cordes 2002].)

These plots make clear that for any inclination, the observed nebula is too broad and too asymmetric to be described by equation (1). However, in comparing a pulsar bow shock to the shape described by equation (1), a number of caveats must be made. First, equation (1) describes a system in which radiative cooling is efficient and in which there is significant mixing between the stellar wind and ambient material (Wilkin 1996), neither of which is likely to be the case for pulsar bow shocks (Bucciantini & Bandiera 2001). However, these effects do not change the shape of the bow shock but simply require $k \sim 1.7–2.4$ in equation (1) (Bucciantini 2002a; van der Swaluw et al. 2002). Van der Swaluw et al. (2002) also demonstrate that for low Mach numbers $M \lesssim 5$, the tail of the resulting bow shock is slightly broader than that described by equation (1). However, in this case we have demonstrated above that $M > 12$, sufficiently high that a morphology close to the analytic shape should result.

We are thus forced to conclude that the idealized bow shock morphology is unable to describe this nebula. To account for the observed appearance, we must relax some of the assumptions from which equation (1) was derived. Specifically, we need to consider the possibilities of a density gradient in the ISM, of a significant flow velocity for the ambient medium, or of anisotropies in the pulsar wind. We briefly summarize how each of these effects manifest themselves in the observed nebular morphology.

1. A local density gradient perpendicular to the pulsar’s direction of motion will distort the bow shock shape of equation (1) so that the head of the nebula is narrower on the side where the density is higher and broader on the side where the density is lower. We here consider a nebula in an exponential density gradient of e-folding scale $kR_0$, using the analytic solution provided by Wilkin (2000).

2. A density gradient parallel to the pulsar velocity vector results in a time-variable ambient gas pressure. The standoff distance will thus continually change to adjust for this pressure imbalance, decoupling the position of the pulsar from that of its bow shock. A detailed treatment of this process is beyond the scope of this Letter; here we approximate the effects of such a gradient by using equation (1), but with the nebula shifted along the $x$-axis by an amount $-R_v$. This crudely corresponds to an increase in ambient density by a factor $\sim (kR_0)^5/(kR_0 - R_v)^5$ over a length scale $\sim kR_0$. If we assume an exponential density gradient with e-folding scale $nR_0$, we then find that $m \sim -1/[2 \ln (1 - R_v/kR_0)]$. Note that this approximate treatment only describes the behavior in the narrow region between the pulsar and the apex of the bow shock; we assume here that the pulsar has only recently encountered the density gradient, so that the overall nebular morphology has the form of equation (1) with constant $R_0$.

3. Bulk motion of the ambient gas (in the reference frame of Galactic rotation at that position) will result in a nebula as described by equation (1), but with the nebula rotated by some angle $\omega$ about the pulsar position. The angle $\omega$ is determined by

<table>
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<tr>
<th>Model</th>
<th>$kR/D$ (arcsec)</th>
<th>$nR^2/k^2$ (cm$^{-1}$)</th>
<th>$i$ (deg)</th>
<th>$l$ (deg)</th>
<th>$R'/D$ (arcsec)</th>
<th>$\omega$ (deg)</th>
<th>$c_s$ (deg)</th>
<th>$\lambda$ (deg)</th>
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<th>Comments</th>
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<tr>
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<td>0.31</td>
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<td>2.4</td>
<td>4.0</td>
<td>$-12$</td>
<td>$-13$</td>
<td>90</td>
<td>Yes</td>
<td>Models C, D, E, and F with $\lambda = 90^\circ$</td>
</tr>
</tbody>
</table>

Note.—Entries in the “Fit?” column correspond to models that are unable to fit and that can successfully fit the observed nebular morphology.
subtraction of the ISM flow velocity vector from the pulsar velocity vector.

4. An anisotropic wind can generate a wide variety of complicated bow shock morphologies, depending on the geometry and orientation of the outflow (Bandiera 1993; Wilkin 2000). Wilkin (2000) derives analytic solutions for the bow shocks generated by axisymmetric winds, parameterizing the resulting morphologies via the variable $c_2$ and $\lambda$. The parameter $c_2$ indicates the nature of the wind (see eq. [109] of Wilkin 2000): $c_2 = 3$ corresponds to a completely polar wind, $c_2 = 0$ to an isotropic wind, and $c_2 = -1.5$ to a completely equatorial wind. The parameter $\lambda$ is the angle between the pulsar spin axis and the pulsar velocity vector.

We have generated an exhaustive set of bow shock morphologies corresponding to each of the above four models, for all reasonable free parameters and for all inclination angles. For each of these models alone, we are unable to find a set of parameters that can match the observed bow shock morphology: a perpendicular density gradient or ISM bulk flow can generate a nebula that is asymmetric about the x-axis (as seen in Figs. 2c and 2d) but that is too narrow to match the data, while a parallel gradient or anisotropic wind can generate a broader bow shock (as seen in Figs. 2e and 2f) but cannot account for the high level of asymmetry between the top and bottom halves of the nebula.

However, when we combine two or more of these effects, we find that we can match the morphology of the head of the nebula with a wide variety of parameters. A representative selection of such fits are listed in the lower half of Table 1: in all cases, the predicted bow shock morphology corresponds well to that of the Hα-emitting nebula. We plot three of these models in Figure 2: in model H, there is a density gradient at an angle to the pulsar’s motion (in this case at an approximate position angle of 225° in Fig. 2) and a bulk flow in the ISM; in model I, a pulsar with an equatorial wind (with $\lambda = 0°$) moves through a perpendicular density gradient and a bulk flow; in model J, there is both a parallel density gradient and a bulk flow. This latter case is particularly noteworthy, as the resultant model is completely equivalent to that described by equation (1) but with an apparent pulsar position and direction of motion that differ from their true values. This makes clear that fitting to the morphology of the bow shock without knowing these parameters can give misleading results.

The models that we have invoked to describe the nebular morphology all correspond to physically reasonable scenarios. Most notably, each of the successful fits to the data requires both a peculiar flow velocity for the ambient ISM of magnitude $15-25$ km s$^{-1}$ and an increase in ambient density of magnitude $\Delta n_p \sim 1-10$ cm$^{-3}$ over a scale of $\sim 0.02$ pc. The implied flow velocities are all within the range of random motions seen in H I clouds (Anantharamaiah, Radhakrishnan, & Shaver 1984; Kulkarni & Fich 1985), while the required density variations are all within the range of random motions seen in H I.

Finally, the mean density implied by all these models is $n_0 = 0.8-1.3$ cm$^{-3}$ (assuming $k = 2$ and $d_0 = 1$), quite typical of the warm, neutral component of the ISM in which observable Hα/pulsar bow shocks will be generated.

Given the density gradients inferred for the ambient medium, it is perhaps surprising that large variations in the Hα surface brightness are not seen as a function of position around the PWN. A considerably more detailed investigation, incorporating the effects discussed by Bucciantini & Bandiera (2001), is needed to establish whether the ambient density can be quantitatively probed using the variations in nebular brightness.

4. CONCLUSIONS

We have identified a striking Hα bow shock powered by the millisecond pulsar PSR J2124-3358. The morphology of the nebula does not match the standard bow shock shape but can be described by models that include a significant density gradient in the ISM and a bulk flow of ambient gas; an anisotropy in the pulsar wind may also contribute to the nebular morphology. We conclude that, in general, it is not possible to uniquely extract the physical conditions of the system by fitting to the morphology of the nebula with respect to the central source, nor can the position and direction of motion of the pulsar be determined from the shape of the bow shock alone. Rather, we find that additional information is needed to break the degeneracy between different possibilities. In the case of PSR J2124-3358, a significant flow velocity for ambient gas can be identified through a nonzero systemic velocity in optical spectroscopy, a density gradient along the pulsar’s direction of motion can be demonstrated through relative motion of the pulsar and its bow shock in multiepoch imaging, and anisotropies in the pulsar’s relativistic wind may be revealed through high-resolution imaging of the X-ray emission from J2124-3358 (e.g., Sakurai et al. 2001) using the Chandra X-Ray Observatory. When combined with detailed modeling of the brightness and width of the nebula as a function of position, these data can be used to fully characterize the interaction of this pulsar with its environment.

We thank Matthew Bailes for providing updated timing parameters for PSR J2124-3358 and Shami Chatterjee for helpful discussions. We are particularly grateful to the referee, Rino Bandiera, for pointing out a crucial error in our original calculations. We acknowledge the NTT team for their assistance. These results are based on observations made with ESO telescopes at the La Silla Observatory (program 67.D-0064).

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