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THE MODAL LOGIC OF FORCING

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Abstract. A set theoretical assertion \( \psi \) is forceable or possible, written \( \Diamond \psi \), if \( \psi \) holds in some forcing extension, and necessary, written \( \Box \psi \), if \( \psi \) holds in all forcing extensions. In this forcing interpretation of modal logic, we establish that if ZFC is consistent, then the ZFC-provable principles of forcing are exactly those in the modal theory \( S4.2 \).

1. Introduction

What are the most general principles in set theory relating forceability and truth? We are interested in how the set theoretical method of forcing affects the first order theory of a model of set theory. As with Solovay's celebrated analysis of provability, both this question and its answer are naturally formulated with modal logic. We aim to do for forceability what Solovay did for provability.

Forcing was introduced by Paul Cohen in 1962 in order to prove the independence of the Axiom of Choice AC and the Continuum Hypothesis CH from the other axioms of set theory. In an explosion of applications, set theorists subsequently used it to construct an enormous variety of models of set theory and prove many other independence results. With forcing one builds an extension of any model \( V \) of set theory, in an algebraic manner akin to a field extension, by adjoining a new ideal object \( G \), a \( V \)-generic filter over a partial order \( P \) in the ground model \( V \), while preserving ZFC. The resulting forcing extension \( V[G] \) is closely related to the ground model \( V \), but may exhibit different set theoretical truths in a way that can often be carefully controlled. The method has become a fundamental tool in set theory.

Because the ground model \( V \) has some access via names and the forcing relation to the objects and truths of the forcing extension \( V[G] \), there are clear affinities between forcing and modal logic. (One might even imagine the vast collection of

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\[ \text{[Sol76]} \] for a survey of the result and the subsequent development of the field of provability logic, see also \[ \text{[HJRS]} \].

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all models of set theory, related by forcing, as an enormous Kripke model.) Accordingly, we define that a statement of set theory \( \varphi \) is forceable or possible if \( \varphi \) holds in some forcing extension, and \( \varphi \) is necessary if it holds in all forcing extensions. The modal notations \( \Diamond \varphi \) and \( \Box \varphi \) express, respectively, that \( \varphi \) is possible or necessary. This forcing interpretation of modal logic was introduced by the first author in [Ham03] in connection with the Maximality Principle, a new forcing axiom, with related work in [Lei04] and [HW05]. An alternative but related connection between modal logic and forcing was explored by Fitting and Smullyan in [SF96], and Blass [Bla90] provides an interpretation of modal logic in set theory that is not directly related to forcing. In [Boo93, Chapter 13], Solovay analyzed the set theoretic modalities of “true in all transitive models of ZF” and “true in \( V_\kappa \) for every inaccessible cardinal \( \kappa \),” respectively. This work has been extended in unpublished work of Enayat and Togha.

The forcing modal operators, of course, are eliminable in the language of set theory, because their meaning can be expressed in the usual language of set theory by means of the forcing relation or Boolean values. For example, \( \Diamond \varphi \) simply means that there is some partial order \( P \) and condition \( p \in P \) such that \( p \Vdash_P \varphi \), and \( \Box \varphi \) means that for all partial orders \( P \) and \( p \in P \) we have \( p \Vdash_P \varphi \). In this way, one can interpret \( \Diamond \varphi \) and \( \Box \varphi \) in any model of set theory. In ZFC we may freely use a mixed language of set theory with the modal operators \( \Diamond \) and \( \Box \), understood as abbreviations with the forcing interpretation. Our goal is to discover which modal principles forcing must obey.

For example, the scheme \( \Box \varphi \rightarrow \varphi \) expresses the statement “if \( \varphi \) is true in all forcing extensions, then it is true.” This is valid, because every model of set theory is a (trivial) forcing extension of itself. Similarly, \( \neg \Diamond \varphi \rightarrow \Box \neg \varphi \) is valid for forcing because a statement \( \varphi \) is not forceable if and only if all forcing extensions satisfy \( \neg \varphi \). The principle \( \Box \varphi \rightarrow \Box \Box \varphi \) is valid because if \( \varphi \) holds in all forcing extensions, then so does \( \Box \varphi \), since any forcing extension of a forcing extension is a forcing extension. The reader may easily verify that \( \Box \varphi \rightarrow (\Box \varphi \rightarrow \Box \varphi) \rightarrow (\Box \varphi \rightarrow \Box \psi) \) is valid. The principle \( \Diamond \Box \varphi \rightarrow \Box \Diamond \varphi \) is valid for forcing, because if \( \varphi \) is necessary in \( V_P \) and \( V_Q \) is an arbitrary extension, then \( \varphi \) is true in the product extension \( V_{P \times Q} \), as this extends \( V_P \); consequently, \( \varphi \) is forceable over every such extension \( V_Q \). These modal assertions axiomatize the modal theory known as \( S4.2 \), and a bit of formalization will help us express what we have observed.

A modal assertion is a formula of propositional modal logic, such as \( (\Box q_0 \rightarrow q_0) \), expressed with propositional variables \( q_i \), Boolean connectives \( \land, \lor, \neg, \rightarrow, \leftrightarrow \) and the modal operators \( \Diamond, \Box \). We write \( \varphi(q_0, \ldots, q_n) \) to denote a modal assertion whose propositional variables are among \( q_0, \ldots, q_n \).

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\(^2\)By formalizing forcing in ZFC, rather than the metatheory, one can sensibly force over any model of ZFC, without needing it to be countable or transitive and regardless of the metatheoretical objects, such as generic filters, which may or may not exist in a larger universe. In this syntactic account, one considers what is forced by various conditions without ever building the forcing extension as a structure. A semantic account of forcing over an arbitrary \( M \models ZFC \) is provided by the quotient \( M^\mathbb{P}/U \) of the Boolean valued universe \( M^\mathbb{P} \) by any ultrafilter \( U \), with no need for \( U \) to be \( M \)-generic (even \( U \in M \) works fine!). The original model \( M \) maps elementarily into the ground model of \( M^\mathbb{P}/U \), and so one obtains the forcing extension as an actual structure (although the new ground model may not be isomorphic to \( M \) and may not even be well founded). Vopěnka seems to have been the first to do forcing this way [Vop69].
Main Definition 1. A modal assertion \( \varphi(q_0, \ldots, q_n) \) is a valid principle of forcing if for all sentences \( \psi_i \) in the language of set theory, \( \varphi(\psi_0, \ldots, \psi_n) \) holds under the forcing interpretation of \( \Diamond \) and \( \Box \).

The validity of \( \varphi \), therefore, is expressible as a scheme in set theory. We say that \( \varphi(q_0, \ldots, q_n) \) is a ZFC-provable principle of forcing if ZFC proves all such substitution instances \( \varphi(\psi_0, \ldots, \psi_n) \). This naturally generalizes to larger theories with the notion of a \( T \)-provable principle of forcing. For any model \( W \models ZFC \), the modal assertion \( \varphi(q_0, \ldots, q_n) \) is a valid principle of forcing in \( W \) if all substitution instances \( \varphi(\psi_0, \ldots, \psi_n) \) are true in \( W \). Hamkins posed the question:

Main Question 2. What are the valid principles of forcing?

For the ZFC-provable principles of forcing, our Main Theorem 6 provides the answer. Meanwhile, a few paragraphs ago, we essentially observed the following.

Theorem 3. Every assertion in the modal theory \( S4.2 \) is a ZFC-provable principle of forcing.

Proof. The modal theory \( S4.2 \) is obtained from the axioms

\[
\begin{align*}
K & \quad \Box(\varphi \to \psi) \to (\Box \varphi \to \Box \psi) \\
\text{Dual} & \quad \neg \Diamond \varphi \leftrightarrow \Box \neg \varphi \\
S & \quad \Box \varphi \to \varphi \\
4 & \quad \Box \varphi \to \Box \Box \varphi \\
.2 & \quad \Diamond \Box \varphi \to \Diamond \varphi
\end{align*}
\]

by closing under modus ponens and necessitation (from \( \varphi \), deduce \( \Box \varphi \)). We observed earlier that each axiom is a valid principle of forcing, provably so as a scheme in ZFC. The ZFC-provable principles of forcing are clearly closed under modus ponens, and they are closed under necessitation because if \( \varphi(\psi_0, \ldots, \psi_n) \) holds in all models of set theory, then so does \( \Box \varphi(\psi_0, \ldots, \psi_n) \).

Let us quickly show that none of the modal theories most commonly considered beyond \( S4.2 \) are ZFC-provable principles of forcing. This follows from our main theorem, but we find it informative to have explicit failing instances of the principles; they are what pointed to \( S4.2 \) as the right choice.

5 \( \Diamond \Box \varphi \to \varphi \)

M \( \Box \Diamond \varphi \to \Diamond \Box \varphi \)

W5 \( \Diamond \Box \varphi \to (\varphi \to \Box \varphi) \)

.3 \( \Diamond \varphi \land \Diamond \psi \to (\Diamond (\varphi \land \Diamond \psi) \lor \Diamond (\varphi \land \psi) \lor \Diamond (\psi \land \Diamond \varphi)) \)

Dm \( \Box(\Box(\varphi \to \Box \varphi) \to \varphi) \to (\Diamond \Box \varphi \to \varphi) \)

Grz \( \Box(\Box(\varphi \to \Box \varphi) \to \varphi) \to \varphi \)

Löb \( \Box(\Box(\varphi \to \varphi) \to \varphi) \)

H \( \varphi \to \Box(\Diamond \varphi \to \varphi) \)

Observation 4. If ZFC is consistent, then none of the above assertions is a ZFC-provable principle of forcing.

Proof. (5) Let \( \varphi \) be the assertion “\( V \neq L \)” where \( L \) denotes Gödel’s constructible universe. This is easily forced, and once true it remains true in all further extensions. Thus, \( \Diamond \Box \varphi \) holds in \( L \), but not \( \varphi \) itself. So 5 is not valid for forcing over \( L \).
(M) This is the McKinsey axiom, also known as .1. The Continuum Hypothesis CH is forceable over any model of set theory (see [Jec03 ex. 15.15]), so □♦CH holds. But △CH is also forceable ([Jec03 14.32]), so ♦□CH fails. Thus, M is invalid for forcing in every model of ZFC.

(W5) Let ϕ be the assertion “ω₁ < ω₁ or CH,” which is true in L, but not necessarily there, since one can force △CH without collapsing ω₁. Since one could collapse ω₁, however, ϕ is forceably necessary in any model of set theory. Thus, □♦ϕ holds in L, but not ϕ → □ϕ, and so W5 fails as a principle of forcing in L.

(.3) Let ϕ assert “ω₁ is a cardinal, but ω₁ is not” and ψ assert “ω₁ is a cardinal, but ω₁ is not.” These are each forceable over L, since ω₁ and ω₁ can be collapsed independently. Yet, whenever one of them holds, the other becomes unforceable. So the antecedent of this instance of .3 is true in L, while the conclusion is false, so .3 is not valid in L.

(Dm) This axiom is also known as Dum. Let ϕ assert “ω₁ < ω₁ or ¬CH.” Since one may collapse ω₁, this is possibly necessary, but false, in L. So L |= ¬(□ □ ϕ → ϕ), falsifying the conclusion of this instance of Dm. For the antecedent, suppose a forcing extension satisfies L_p |= ω₁ = ω₁. Since we may force ¬CH over L_p, and then recover CH, both without collapsing ω₁, we conclude L_p |= □(ϕ → □ϕ). It follows vacuously that L_p |= □(ϕ → □ϕ) → ϕ. Alternatively, if L_p |= □ϕ < ω₁, then ϕ is true there, so L_p |= □(ϕ → □ϕ) → ϕ. Thus, every forcing extension satisfies □(ϕ → □ϕ) → ϕ, and so L |= □(□(ϕ → □ϕ) → ϕ), fulfilling the antecedent of Dm in L. So Dm is not valid for forcing over L.

(Grz) This is the Grzegorczyk axiom. Since Grz is stronger than Dm, it is invalid in L by the previous case. We will show, however, that Grz is invalid in every model of set theory. Let ϕ be the CH. Since ¬CH is forceable over any model of set theory, □ϕ is always false, and so ϕ → □ϕ is equivalent to ¬ϕ. So this instance of Grz reduces to □(□¬CH → CH) → CH. Since CH is always forceable, □¬CH is false, making the first implication, and the hypothesis of this instance of Grz, vacuously true. So this axiom instance will fail whenever CH fails. Similar reasoning shows that if ϕ is ¬CH, then the corresponding axiom instance fails if CH holds. So Grz fails as a principle of forcing in every model of set theory.

(Löb) This axiom expresses the content of Löb’s theorem in provability logic, where one interprets □ϕ as “ϕ is provable.” Under the forcing interpretation, however, it is invalid, because in fact it contradicts S4. If ϕ is any contradiction, such as 0 = 1, then □ϕ is false, and consequently □(□ϕ → ϕ) is always true. So in any model of set theory, the hypothesis of this instance of the Löb axiom is true, while the conclusion is false. So Löb is never a valid principle of forcing.

(H) Let ϕ be the CH. As we have mentioned, this is necessarily possible, so □ϕ always holds. In this case, therefore, □(ψ ϕ → ϕ) is equivalent to □ϕ, which is false. So H fails in any model where CH is true. By using ¬CH in the other models, we conclude that H fails as a principle of forcing in every model of set theory.

The corresponding modal theories, listed in Figure 1 with their implication diagram, are obtained by closing the axioms under modus ponens, substitution and necessitation. This list is not exhaustive, as there are continuum many modal theories above S4.2 that are not listed. We refer the reader to [CZ97] and [BRV01] for excellent developments of modal logic, including the analysis of these and many other theories.
Corollary 5. If ZFC is consistent, then none of the modal theories $S5$, $S4W5$, $S4.3$, $S4.2.1$, $S4.1$, $Dm.2$, $Dm$, $K4H$, $GL$ or $Grz$ are ZFC-provable principles of forcing, and all are invalid in $L$. The modal theories $S4.1$, $S4.2.1$, $K4H$, $GL$ and $Grz$ are invalid as principles of forcing in every model of set theory.

So if the ZFC-provable principles of forcing constitute any previously known modal theory, then the best remaining candidate is $S4.2$.

This article is intended primarily for two audiences: set theorists interested in the fundamental principles of forcing and modal logicians interested in the application of their subject to set theory. While we felt it necessary in the arguments to assume a basic familiarity with forcing, we do provide references to specific elementary forcing results in the standard graduate set theory textbooks where this might be helpful. We were able to provide in our arguments a complete account of the necessary concepts from modal logic. Sections 1 and 3 cover the proof of our Main Theorem which answers our Main Question above. Section 2 contains a complete proof of the main theorem written primarily with the set theoretical reader in mind, and Section 3 emphasizes certain aspects of the proof for the modal logicians. After this, we apply our technique fruitfully in Sections 4-6 to various other instances of Main Question 2, by restricting the focus to a given model of set theory, by investigating the role of parameters in the valid principles of forcing, and by restricting attention to a natural class of forcing notions, such as those with the countable chain condition.
2. The main theorem

Our main theorem provides an answer to Question 2.

**Main Theorem 6.** If ZFC is consistent, then the ZFC-provable principles of forcing are exactly those in the modal theory $S4^2$.

The rest of this section is devoted to the proof of this theorem. We begin with the key concepts of buttons and switches, which generalize the important features of the substitution statements arising in the proof of Observation 4. Specifically, a *switch* is a statement $\varphi$ of set theory such that both $\varphi$ and $\neg \varphi$ are necessarily possible, so that by forcing $\varphi$ can be switched on or off at will. For example, the CH is a switch, because you can ensure either CH or $\neg$CH by forcing over any model of set theory. In contrast, a *button* is a statement that is (necessarily) possibly necessary. The button is *pushed* when it is necessary, and otherwise *unpushed*. The idea is that you can always push a button by making it necessary, but having done so, you cannot unpush it again. The assertion “$\omega_1^L$ is countable” is a button because it can be forced over any model of set theory and once it becomes true it remains true in all further extensions. This button is unpushed in L. The reader is invited to check that a statement is possibly necessary if and only if it is necessarily possibly necessary; at bottom, this amounts to the $S4^2$ validity of $\Diamond \Box \varphi \leftrightarrow \Box \Diamond \Box \varphi$. Thus, a button remains a button in every forcing extension. Although it may seem at first that buttons and switches are very special sorts of statements, we invite the reader to check that in fact every statement in set theory is either a button, the negation of a button, or a switch (and these types are disjoint).

A collection of buttons $b_n$ and switches $s_m$ is *independent* in a model if first, all the buttons are unpushed in the model and second, necessarily (that is, in any forcing extension), any of the buttons can be pushed and any of the switches can be switched without affecting the value of any of the other buttons or switches. In other words, the collection of buttons and switches is independent in $W$ if the buttons are unpushed in $W$, but in any forcing extension $W^P$, whatever the pattern of buttons and switches is in $W^P$, any button can be turned on by forcing to some $W^{P+Q}$ without affecting the value of any of the other buttons or switches, and any switch can be turned either on or off by forcing to some $W^{P+R}$ without affecting the value of any of the other buttons or switches. It follows, of course, that any finite pattern of buttons and switches being on or off is possible by forcing over $W$. For an account of buttons, switches and independence in an arbitrary Kripke model, see Definition 8 and the accompanying text.

We note that the counterexample substitution instances showing the forcing invalidity of the modal assertions in Observation 4 were each Boolean combinations of independent buttons and switches.

**Lemma 6.1.** If $V = L$, then there is an independent collection of infinitely many buttons and infinitely many switches.

**Proof.** For positive natural numbers $n$ and $m$, let the button $b_n$ be the assertion “$\omega_n^L$ is not a cardinal,” and let the switch $s_m$ be the assertion “the GCH holds at $\aleph_{\omega_1+m}$.” If $V = L$, then it is clear that none of the buttons is true, but in any model of set theory, the button $b_n$ can be made true by collapsing $\omega_n^L$, without affecting the truth of any other button or the properties of the GCH above $\aleph_\omega$ (see [Jec03, 15.21]). Once the button $b_n$ becomes true, it is clearly necessary,
because the cardinal $\omega_1^n$ will remain collapsed in any further forcing extension. The switches $s_m$ are clearly switches, because with forcing one can arrange the values of the continuum function at $\aleph_{\omega+m}$ at will by forcing that adds no new bounded sequences below $\aleph_\omega$ (see [Jec03] 15.18 and related)). Thus, the switches can be set to any desired pattern without affecting any of the buttons. \qed

A lattice is a partial order such that any two nodes $a$ and $b$ have a greatest lower bound or meet, denoted $a \land b$ and a least upper bound or join, denoted $a \lor b$. It follows that every nonempty finite set $A$ has a meet $\bigwedge A$ and join $\bigvee A$, and that a finite lattice has a least and a greatest element.

**Lemma 6.2.** If $F$ is a finite lattice and $W$ is a model of set theory with a sufficiently large independent family of buttons $b_i$, then to each node $w \in F$ we may assign an assertion $p_w$, a Boolean combination of the buttons, such that $W$ satisfies:

1. In any forcing extension, exactly one of the $p_w$ is true, and $W \models p_{w_0}$, where $w_0$ is the minimal node of $F$.
2. In any forcing extension satisfying $p_w$, the statement $p_v$ is forceable if and only if $w \leq v$ in $F$.

**Proof.** Let us associate a button $b_u$ with each node $u \in F$. For any $A \subseteq F$, let $b_A = (\bigwedge_{u \in A} \Box b_u) \land (\bigwedge_{u \notin A} \neg \Box b_u)$ be the sentence asserting that exactly the buttons in $A$ are pushed and no others. Let $p_w = \bigvee \{ b_A \mid w = \bigvee A \}$ be the sentence asserting that the pattern of buttons that have been pushed corresponds to a set $A$ with least upper bound $w$ in $F$. Since every forcing extension must have some pattern $A$ of buttons $b_u$ pressed and every such $A$ has a least upper bound in $F$, it is clear that $p_w$ will be true in the model if and only if $w$ is the least upper bound of $A$. Thus, in any forcing extension exactly one of the $p_w$ is true, and $W \models p_{w_0}$, as all buttons are unpushed in $W$.

For the second claim, suppose that $W[G]$ is a forcing extension where $p_w$ holds. Let $A = \{ u \in F \mid W[G] \models b_u \}$ be the set of buttons that are pushed in $W[G]$. Since $p_w$ is true, it must be that $w$ is the join of $A$ in $F$. If $w \leq v$ in $F$, then by pushing the button $b_v$ and no others, we arrive at a forcing extension $W[G][H]$ with buttons pushed in $A \cup \{v\}$. Since this has join $v$, this means that $p_v$ is true in $W[G][H]$, and hence $p_v$ is forceable in $W[G]$, as desired. Conversely, suppose that $p_v$ is forceable in $W[G]$. Thus, there is some further extension $W[G][H]$ satisfying $p_v$. This extension exhibits some pattern of buttons $\{ b_u \mid u \in B \}$, where the join of $B$ is $v$. Since $W[G][H]$ is a forcing extension of $W[G]$, the buttons in $A$ remain pushed in $W[G][H]$, and so $A \subseteq B$. Thus, $v$ must be at least as large as the join of $A$, which is $w$, so $w \leq v$ in $F$. \qed

A pre-lattice is obtained from a lattice by replacing each node with a cluster of one or more equivalent nodes, all related by $\leq$. Equivalently, it is a partial pre-order $\leq$ (a reflexive and transitive relation) on a set $F$, such that the quotient of $F$ by the equivalence relation $u \equiv v \iff u \leq v \leq u$ is a lattice under the induced quotient relation $\leq$.

**Lemma 6.3.** Suppose that $F$ is a finite pre-lattice and $\{ b_i, s_j \}_{i,j}$ is a sufficiently large finite independent family of buttons and switches in a model of set theory $W$. Let $w_0$ be any node in the minimal cluster of $F$. Then to each $w \in F$ we may
assign an assertion $p_w$, a Boolean combination of the buttons and switches, such that $W \models p_w$, and:

1. In any forcing extension, exactly one of the $p_w$ is true.
2. In any forcing extension satisfying $p_w$, the statement $p_v$ is forceable if and only if $w \leq v$ in $F$.

Proof. The idea is to use the buttons as in Lemma 6.2 to determine which cluster is intended in the quotient lattice, and then use the switches to determine which node is intended within this cluster. Let $[u]$ denote the equivalence class of $u$ in the quotient lattice $F/\equiv$, and let $p[u]$ be the label assigned to $[u]$ in Lemma 6.2. Thus, $p[u]$ is the disjunction of various complete patterns of buttons having supremum $[u]$. Suppose that the largest cluster of $F$ has $k$ nodes, and $k \leq 2^n$. For each subset $A \subseteq \{0, \ldots, n-1\} = n$, let $s_A = (\wedge_{i \in A} s_i) \land (\bigvee_{i \notin A} \neg s_i)$ assert that the pattern of switches is specified by $A$. Since every pattern of switches is possible by forcing over $W$, every $s_A$ is necessarily possible, and in any forcing extension of $W$, exactly one $s_A$ holds. For each cluster $[u]$, assign to every $w \in [u]$ a nonempty set $\hat{A}_w = \{A_{w0}, \ldots, A_{wn}\}$ of subsets of $n$ in such a way that the various $\hat{A}_w$ for $w \in [u]$ partition the subsets $A \subseteq n$. We may assign the pattern $A$ of switches that happen to hold in $W$ to any desired node $w_0$ in the minimal cluster of $F$. Let $s_w = \bigvee_{A \in \hat{A}_w} s_A$ assert that the switches occur in a pattern appearing in $\hat{A}_w$. Finally, define $p_w = p[u] \land s_w$.

We now prove that this works. In any forcing extension of $W$, we know by Lemma 6.2 that exactly one $p[u]$ is true. Furthermore, any forcing extension exhibits some pattern $A$ of switches being true, and this $A$ is assigned to exactly one $w \in [u]$, so exactly one $s_w$ is true for $w \in [u]$. Thus, in any forcing extension, exactly one $p_w = p[u] \land s_w$ is true. We arranged that $p[w_0]$ is true in $W$ by the assignment of the pattern of switches holding in $W$ to the world $w_0$.

If $W^p$ is a forcing extension satisfying $p_w$, then both $p[u]$ and $s_w$ hold in $W^p$. If $w \leq v$ in $F$, then we already know that $p[v]$ is forceable in $W^p$, and $s_v$ is forceable from any extension of $W$ without affecting the buttons, so $p_v = p[v] \land s_v$ is forceable over $W^p$, as desired. Conversely, if $p_v$ is forceable over $W^p$, this implies that $p[u]$ is forceable over $W^p$, and so $[u] \leq [v]$ in the quotient lattice. It follows that $w \leq v$ in $F$. 

We now state some definitions from modal logic. A propositional world, also called a state, is a map of the propositional variables to the set $\{\text{true}, \text{false}\}$. This is simply a row in a truth table. A Kripke model $M$ is a set $U$ of propositional worlds, together with a relation $R$ on $U$ called the accessibility relation. The Kripke semantics define when a modal assertion $\varphi$ is true at a world $w$ in a Kripke model $M$, written $(M, w) \models \varphi$. Namely, for atomic assertions, $(M, w) \models q$ if $q$ is true in $w$; for Boolean connectives, one uses the usual inductive treatment; for necessity, $(M, w) \models \square \varphi$ if whenever $w R v$, then $(M, v) \models \varphi$; and for possibility, $(M, w) \models \Diamond \varphi$ if there is $v$ with $w R v$ and $(M, v) \models \varphi$. The underlying frame of the model $M$ is the structure $(U, R)$, ignoring the internal structure of the elements of $U$. The reader may easily check that every Kripke model whose frame is a partial pre-order satisfies $S4$, and every Kripke model on a directed partial pre-order satisfies $S4.2$. A deeper fact is Lemma 6.5 that the finite pre-lattice frames are complete for $S4.2$. If $\Lambda$ is a modal theory and every Kripke model with frame $F$ satisfies $\Lambda$ at every world, then $F$ is a $\Lambda$-frame. A modal theory $\Lambda$ has the finite frame property if
whenever $\Lambda \not\vdash \varphi$, then there is a finite $\Lambda$-frame $F$ and a Kripke model having frame $F$ in which $\varphi$ fails. A class $\mathcal{F}$ of frames is complete for a modal theory $\Lambda$ if every $F \in \mathcal{F}$ is a $\Lambda$-frame and any $\varphi$ true in all Kripke models having frames in $\mathcal{F}$ is in $\Lambda$. In this case, we also say that $\Lambda$ is defined by $\mathcal{F}$. Two Kripke models $M$ and $M'$ are bisimilar if there is a correspondence of their worlds $a \sim a'$ for $a \in M$, $a' \in M'$, not necessarily functional or one-to-one, such that corresponding worlds have the same truth assignments to the propositional variables, and whenever $a$ accesses $b$ in $M$ and $a \sim a'$, then there is some $b'$ in $M'$ such that $b \sim b'$ and $a'$ accesses $b'$ in $M'$, and conversely, whenever $a \sim a'$ and $a'$ accesses $b'$ in $M'$, then there is some $b \sim b'$ such that $a$ accesses $b$. It follows by induction that corresponding worlds in $M$ and $M'$ have exactly the same modal truths.

The next lemma is the heart of our argument, where we prove that the behavior of any Kripke model on a finite pre-lattice can be exactly simulated by forcing.

**Lemma 6.4.** If $M$ is a Kripke model whose frame is a finite pre-lattice with a world $w_0$ and $W$ is a model of set theory with a sufficiently large independent family of buttons and switches, then there is an assignment of the propositional variables $q_i$ to set theoretical assertions $\psi_i$, such that for any modal assertion $\varphi$ we have

$$ (M, w_0) \models \varphi(q_0, \ldots, q_n) \quad \text{if and only if} \quad W \models \varphi(\psi_0, \ldots, \psi_n). $$

**Proof.** Each $\psi_i$ will be a certain Boolean combination of the buttons and switches. We have assumed that the frame $F$ of $M$ is a finite pre-lattice. We may assume without loss of generality that $w_0$ is an initial world of $M$, by ignoring the worlds not accessible from $w_0$. Let $p_w$ be the assertions assigned according to Lemma 6.4. Since $w_0$ is an initial world of $F$, we may ensure that $W \models p_{w_0}$. Let $\psi_i = \bigvee \{ p_w \mid (M, w) \models q_i \}$. We will prove the lemma by establishing the following stronger claim:

$$ (M, w) \models \varphi(q_0, \ldots, q_n) \quad \text{if and only if} \quad W \models \Box (p_w \rightarrow \varphi(\psi_0, \ldots, \psi_n)). $$

This is true for atomic $\varphi$, since $q_i$ is true at $w$ if and only if $p_w$ is one of the disjuncts of $\psi_i$, in which case $p_w \rightarrow \psi_i$ in any forcing extension of $W$, and conversely if $p_w \rightarrow \psi_i$ is true in a forcing extension where $p_w$ is true, then $\psi_i$ must be true there, in which case $q_i$ is true at $w$ in $M$. If the statement is true for $\varphi_0$ and $\varphi_1$, then it is also true for $\varphi_0 \land \varphi_1$. For negation, suppose that $(M, w) \models \neg \varphi(q_0, \ldots, q_n)$. By induction, $W \not\models \Box (p_w \rightarrow \varphi(\psi_0, \ldots, \psi_n))$, so there is a forcing extension $W'$ satisfying $p_w$ and $\neg \varphi(\psi_0, \ldots, \psi_n)$. Since the truth values of $\psi_i$ necessarily depend only on the values of the various $p_w$, it follows that all forcing extensions with $p_w$ will satisfy $\neg \varphi(\psi_0, \ldots, \psi_n)$. So we have proved $W \models \Box (p_w \rightarrow \neg \varphi(\psi_0, \ldots, \psi_n))$, as desired, and reversing the steps establishes the converse. Finally, $(M, w) \models \Diamond \varphi(q_0, \ldots, q_n)$ if and only if $\exists u \geq w (M, u) \models \varphi(q_0, \ldots, q_n)$, which occurs if and only if $W \models \Box (p_u \rightarrow \varphi(\psi_0, \ldots, \psi_n))$. Since $W \models \Box (p_u \rightarrow \Diamond p_u)$, this implies $W \models \Box (p_w \rightarrow \Diamond \varphi(\psi_0, \ldots, \psi_n))$, as desired. Conversely, if $W \models \Box (p_w \rightarrow \Diamond \varphi(\psi_0, \ldots, \psi_n))$, then $\varphi(\psi_0, \ldots, \psi_n)$ is forceable over any extension of $W$ with $p_w$. Since all such extensions have $p_u$ for some $u \geq w$ and the $\psi_i$ depend only on the values of $p_u$, it must be that $W \models \Box (p_u \rightarrow \varphi(\psi_0, \ldots, \psi_n))$ for some $u \geq w$. By induction, this is equivalent to $(M, u) \models \varphi(q_0, \ldots, q_n)$ and consequently to $(M, w) \models \Diamond \varphi(q_0, \ldots, q_n)$, as desired.

The next step of our proof relies on a fact about $S4$. A tree is a partial order $\leq$ on a set $F$ such that the predecessors of any node are linearly ordered. A pre-tree
Figure 2. A partial order (left) and its partial unravelling, a baled tree (right)

is a partial pre-order \( \leq \) on a set \( F \) such that the quotient \( F/\equiv \) is a tree; each node of this tree is effectively replaced in \( F \) with a cluster of equivalent nodes. A \textit{baled tree} is a partial order \( \leq \) on a set \( F \) having a largest node \( b \in F \), such that \( F \setminus \{b\} \) is a tree (imagine baling or tying the top branches of a tree together, as in Figure 2). A \textit{baled pre-tree} is the result of replacing each node in a baled tree with a cluster of equivalent nodes; equivalently, it is a partial pre-order whose quotient by \( \equiv \) is a baled tree. Note that every baled tree is a lattice, and every baled pre-tree is a pre-lattice. A partial pre-order is \textit{directed} if any two nodes have a common upper bound.

\textbf{Lemma 6.5.} If a modal assertion \( \varphi \) is not in \( S4.2 \), then it fails in some Kripke model \( M \) whose frame is a finite baled pre-tree, and hence a finite pre-lattice.

\textit{Proof.} It is easy to see that every Kripke model whose frame is a directed partial pre-order satisfies \( S4.2 \), and conversely that any frame that is not a directed partial pre-order has a Kripke model violating \( S4.2 \) (see [CZ97, Theorem 3.38]). Thus, \( S4.2 \) is defined by the class of directed partial pre-orders. By [CZ97, Theorem 5.33], it is known that \( S4.2 \) has the finite frame property, and so if \( S4.2 \not\vDash \varphi \), then \( \varphi \) fails in a Kripke model \( M_0 \) whose frame \( F_0 \) is a finite \( S4.2 \) frame, which is to say, a finite directed partial pre-order. We will construct a Kripke model \( M \) that is bisimilar with \( M_0 \), and which consequently has the same modal theory, but whose frame is a finite baled pre-tree, and consequently a finite pre-lattice. Our construction is a minor modification of the standard technique of tree unravelling as described in the proof of [CZ97, Theorem 2.19]. We know that \( \varphi \) fails at some world \( w_0 \) in \( M_0 \), and we may assume that \( w_0 \) is in the smallest cluster of \( F_0 \). By directedness, \( F_0 \) has a largest cluster \([b]\). The quotient \( F_0/\equiv \) is a finite directed partial order. For each \([u] \in F_0/\equiv \), let us say that \( t \) is a path from \([w_0]\) to \([u]\) in \( F_0/\equiv \) if it is a maximal linearly ordered subset of the interval \([w_0,u]\) in \( F_0/\equiv \). Such paths form a tree when ordered by end-extension. Let \( F \) be the \textit{partial unravelling} of \( F_0 \), except for the largest cluster. That is, \( F \) consists of the maximal cluster \([b]\) of \( F_0 \), together with the set of all pairs \((u,t)\), where \( t \) is a path from \([w_0]\) to \([u]\) in \( F_0/\equiv \) and \([u] \neq [b]\). The order on \( F \) is by end-extension of the paths \( t \) and the \( F_0 \) order on \( u \), with \([b]\) still maximal. The worlds within any copy of a cluster are still equivalent and consequently still form a cluster, and so \( F \) is a baled pre-tree. Let \( M \) be the
resulting Kripke model on $F$, obtained by also copying the propositional values from every world $u \in F_0$ in $M_0$ to the copies $\langle u, t \rangle$ of it in $F$. It is easy to see that $M$ is bisimilar with $M_0$, according to the correspondence that we have defined, because every world accesses in $M$ copies of the worlds its corresponding world accesses in $M_0$ and only such copies. It follows that every world in $M_0$ satisfies exactly the same modal truths in $M$ that its copies satisfy in $M$. Consequently, $\varphi$ fails at the copy of $w_0$ in $M$. Thus, $\varphi$ fails in a Kripke model whose frame is a finite baled pre-tree, and all such frames are pre-lattices.

\[ \square \]

Proof of Theorem 6. Finally, we prove the theorem. By Theorem 5 the set of ZFC-provable principles of forcing includes S4.2. If $\varphi$ is not in S4.2, then by Lemma 6.5 there is a Kripke model $M$ on a finite pre-lattice in which $\varphi$ fails at an initial world. It is well known that if ZFC is consistent, then so is ZFC+$V=L$, and so by Lemma 6.1 there is a model of set theory $L$ having an infinite independent family of buttons and switches. By Lemma 6.4 there is an assignment of the propositional variables of $\varphi$ to sentences $\psi_i$ such that $L \models \neg \varphi(\psi_0, \ldots, \psi_n)$. Therefore, $\varphi$ is not a valid principle of forcing in $L$, and hence not a ZFC-provable principle of forcing.

3. The Jankov-Fine formula

While the previous section was written with a set theoretical reader in mind, let us now emphasize certain points for the modal logicians. The main theorem can be restated in a way (as follows) that aligns it with many other completeness theorems in modal logic.

**Theorem 7.** If ZFC is consistent, then

\[ \text{S4.2} \vdash \varphi(q_0, \ldots, q_n) \quad \text{if and only if} \quad \forall \psi_0, \ldots, \psi_n \text{ ZFC} \vdash \varphi(\psi_0, \ldots, \psi_n), \]

where the $\psi_i$ range over the sentences in the language of set theory and $\square$ and $\Diamond$ are understood in ZFC with the forcing interpretation.

Modal logicians will recognize that Lemmas 6.2 and 6.3 assert exactly that the assertions $p_w$ fulfill the relevant Jankov-Fine formula, which we now define. For any graph $F = (U, E)$, assign a propositional variable $p_w$ to each vertex $w \in U$ of the graph and let $\delta(F)$ be the following formula, the Jankov-Fine formula. It asserts that, necessarily, exactly one $p_w$ is true, and if $p_w$ is true, then $\Diamond p_v$ if and only if $w E v$.

\[ \delta(F) = \square \bigvee_{w \in U} p_w \wedge \square \bigwedge_{w \neq v} (p_w \rightarrow \neg p_v) \wedge \square \bigwedge_{w \in E v} (p_w \rightarrow \Diamond p_v) \wedge \square \bigwedge_{w \not\in E v} (p_w \rightarrow \neg \Diamond p_v) \]

Lemma 6.4 has nothing essentially to do with set theory, but rather only with Kripke models and the Jankov-Fine formula:

**Lemma 7.1.** Suppose that $M$ is a Kripke model whose frame $F$ is a finite partial pre-order and $w_0$ is a world of $M$. If $N$ is any other Kripke model satisfying S4 (at some world $u_0$) and the Jankov-Fine formula $\delta(F) \wedge p_{w_0}$, then there is an assignment of the propositional variables $q_i$ of $M$ to assertions $\psi_i$ in $N$ such that for any modal assertion $\varphi$,

\[ (M, w_0) \models \varphi(q_0, \ldots, q_n) \quad \text{if and only if} \quad (N, u_0) \models \varphi(\psi_0, \ldots, \psi_n). \]
Proof. We argue just as inLemma 6.3. Let $p_w$ be the assertions in $N$ satisfying the Jankov-Fine formula. Let $\psi_i = \bigvee \{ p_w \mid (N, w) \models q_i \}$. We establish the following stronger claim by induction on $\varphi$:

$$(M, w) \models \varphi(q_0, \ldots, q_n) \iff (N, u_0) \models \Box (p_w \rightarrow \varphi(q_0, \ldots, q_n)).$$

The atomic case holds by the definition of $\psi_i$. Conjunction follows because $\Box$ distributes over $\land$. Negation follows via the properties of the Jankov-Fine formula, because every world in $N$ (accessible from $u_0$) satisfies exactly one $p_w$, and any two such worlds agree on every $\psi_i$. Possibility follows using the Jankov-Fine formula again, since $p_w$ is possible from a world with $p_w$ if and only if $w \leq u$ in $F$. Finally, the stronger claim implies the lemma, because $p_{u_0}$ is true at $u_0$ in $N$. \hfill $\square$

A modal theory $\Lambda$ is closed under substitution if $\varphi(q_0, \ldots, q_n)$ is in $\Lambda$ whenever $\varphi(q_0, \ldots, q_n)$ is, for any modal assertions $\psi_i$.

**Lemma 7.2.** Suppose that $F$ is a finite partial pre-order. If a modal theory $\Lambda \supseteq S4$ is closed under substitution and is consistent, for any $w_0 \in F$, with the Jankov-Fine formula $\delta(F) \land p_{w_0}$, then $F$ is a $\Lambda$-frame.

**Proof.** If $F$ is not a $\Lambda$-frame, then there is a Kripke model $M$ with frame $F$ and some $\varphi \in \Lambda$ such that $(M, w_0) \models \neg \varphi(q_0, \ldots, q_n)$ for some $w_0 \in F$. If $\Lambda$ is consistent with $\delta(F) \land p_{w_0}$, then there is a Kripke model satisfying $(N, u_0) \models \Lambda \land \delta(F) \land p_{w_0}$. By Lemma 7.1 there is an assignment $q_i \mapsto \psi_i$, where $\psi_i$ is a Boolean combination of the $p_w$ in $N$, such that $(N, u_0) \models \neg \varphi(q_0, \ldots, q_n)$. This contradicts a substitution instance of $(N, u_0) \models \Lambda$, since $\varphi \in \Lambda$. \hfill $\square$

Similarly, the concepts of button and switch are not set theoretic; they make sense in any Kripke model. Specifically:

**Definition 8.** A button is a statement that is necessarily possibly necessary, and a switch is a statement such that it and its negation are necessarily possible. A family of buttons $\{b_i\}_{i \in I}$ and switches $\{s_j\}_{j \in J}$ is independent in $M$ at world $u$ if none of the buttons is necessary at $u$ and necessarily, any button can be turned on and any switch can be turned either on or off without affecting the other buttons and switches.

This can be expressed precisely in modal logic as follows. For any $A \subseteq I$ and $B \subseteq J$, let $\Theta_{A,B} = (\wedge_{i \in A} \Box b_i) \land (\wedge_{j \notin A} \neg \Box b_i) \land (\wedge_{j \in B} s_j) \land (\wedge_{j \notin B} \neg s_j)$ assert that the pattern of the buttons and switches is specified by $A$ and $B$. The family $\{b_i\}_{i \in I} \cup \{s_j\}_{j \in J}$ of buttons and switches is independent if

$$\left( \bigwedge_{i \in I} \neg \Box b_i \right) \land \bigwedge_{A \subseteq I} \bigwedge_{B \subseteq J} \Box (\Theta_{A,B} \rightarrow \bigwedge_{A' \subseteq A} \bigwedge_{B' \subseteq J} \Diamond \Theta_{A',B'}).$$

Thus, the buttons are off initially, and necessarily, from any possible pattern of buttons and switches, any larger pattern of buttons and any pattern of switches is possible. The main technique in our proofs of Lemmas 6.2 and 6.3 appears to be very reminiscent of Smoryński's [Smo70] proof of de Jongh's theorem [dJ70] on Heyting's Arithmetic.

**Lemma 7.3.** If $F$ is a finite pre-lattice, $w_0 \in F$ and $\Lambda \supseteq S4$ is a modal theory consistent with a sufficiently large independent family of buttons and switches, then $\Lambda$ is consistent with the Jankov-Fine formula $\delta(F) \land p_{w_0}$.
Lemma 9. A class $\mathcal{F}$ of frames is complete for $\mathbf{S}4.2$ if and only if every $F \in \mathcal{F}$ is an $\mathbf{S}4.2$ frame and there are Kripke models with frames in $\mathcal{F}$, for arbitrarily large finite independent families of buttons and switches.

Proof. The forward implication is immediate, because $\mathbf{S}4.2$ is consistent by Lemma 9 with the existence of large independent families of buttons and switches. Conversely, suppose the latter property. If $\varphi_0$ is not in $\mathbf{S}4.2$, then by Lemma 6.5 there is some Kripke model $M$ whose frame $F$ is a finite pre-lattice such that
(M, w₀) |= ¬ϕ₀(q₀, ..., qₙ). Let (N, u₀) be a Kripke model with frame in F having an independent family of n buttons and m switches, where n is the number of clusters in F and the size of any cluster is at most 2ᵐ. By the proof of Lemma 7.3, there are assertions pᵦ for w ∈ F such that (N, u₀) |= δ(F) ∧ pᵦ. By Lemma 7.1, there is an assignment of the propositional variables qᵢ of M to assertions ψᵢ in N such that (M, w₀) |= ϕ(q₀, ..., qₙ) if and only if (N, u₀) |= ϕ(ψ₀, ..., ψₙ). By the assumption on ϕ₀, this means that (N, u₀) |= ¬ϕ₀(ψ₀, ..., ψₙ). Thus, a substitution instance of ϕ₀ fails at a world in N, a Kripke model whose frame is in F. So this class of frames is complete for S₄.2.

Theorem 11. The following sets of frames are complete for S₄.2.

1. Finite directed partial pre-orders.
2. Finite pre-lattices.
3. Finite baled pre-trees.
4. Finite pre-Boolean algebras.

Proof. All of these frames are directed partial pre-orders, and so they are all S₄.2 frames. Lemma 6.3 shows that any statement not in S₄.2 fails in a Kripke model whose frame is a finite baled pre-tree, and hence a finite pre-lattice and a finite directed pre-order, so these classes are complete for S₄.2. The new part of this theorem is (4). By Lemma 9 the class of finite pre-Boolean algebras has Kripke models for arbitrarily large finite independent families of buttons and switches. So by Lemma 10 this class is also complete for S₄.2.

Let us summarize what we have proved about S₄.2:

Theorem 12. Suppose that the modal theory Λ contains S₄ and is closed under substitution. For any class F of finite frames complete for S₄.2, the following are equivalent:

1. Λ is consistent with arbitrarily large finite independent families of buttons and switches.
2. Λ is consistent with the Jankov-Fine formula δ(F) ∧ pᵦ for any frame F ∈ F and world w ∈ F.
3. Every frame in F is a Λ-frame.
4. Λ ⊆ S₄.2.

Proof. Lemma 7.2 shows that (2) implies (3), as the elements of F must be finite directed partial pre-orders. For (3) implies (4), observe that if ϕ ∈ S₄.2, then it must fail in a Kripke model whose frame is in F, contrary to (3). For (4) implies (2), note that S₄.2 and δ(F) ∧ pᵦ are true together in the Kripke model having frame F, with pᵦ true exactly in the world w. For (4) implies (1), if Λ ⊆ S₄.2, then Λ is true in the Kripke models constructed in Lemma 9 which have large independent families of buttons and switches. Finally, Lemma 7.3 shows that (1) implies (2) in the special case where F is the class of all finite pre-lattices, and hence (1) implies (4) for any F, since they do not depend on F, completing the proof.

Our later analysis will benefit from similar characterizations of S₄ and S₅. For S₅, we use the fact that the class of finite complete reflexive graphs is complete for S₅. This result will be applied in Theorem 17.
Theorem 13. Suppose that a modal theory \( \Lambda \) contains \( S4 \) and is closed under substitution. Then the following are equivalent:

1. \( \Lambda \) is consistent with arbitrarily large finite independent families of switches.
2. \( \Lambda \) is consistent with the Jankov-Fine formula \( \delta(F) \land p_w \) for any finite complete graph \( F \) and world \( w \in F \).
3. Every finite complete reflexive graph is a \( \Lambda \)-frame.
4. \( \Lambda \subseteq S5 \).

Proof. For (1) implies (2), the point is that when \( F \) has only one cluster, the argument of Lemma 6.3 does not require any buttons. Suppose that \( N \) is a Kripke model having an independent family of switches \( \{ s_j \}_{j \in J} \). For any \( A \subseteq J \), define \( s_A \) as in Lemma 6.3 to assert that the pattern of switches is \( A \). Partition the collection of \( A \subseteq J \) among the worlds \( u \in F \) by assigning a nonempty set \( A_u \) of sets to each world \( u \) in \( F \). Let \( s_u = \bigwedge_{A \in A_u} s_A \) as in Lemma 6.3. By assigning whatever pattern of switches holds at \( u_0 \) to the world \( u \), we can arrange that \( (N,u_0) \models s_w \). Since every world must have some unique pattern of switches, it follows that \( (M,u_0) \) satisfies that necessarily, exactly one \( s_u \) is true. Furthermore, since the switches are independent, we also know that \( (M,u_0) \models \square s_u \) for any \( u \in F \). Since all worlds in \( F \) are accessible from each other, this implies \( (N,u_0) \models \delta(F) \land p_u \), as desired.

Lemma 7.2 shows that (2) implies (3). Also, (3) implies (4) because any statement not in \( S5 \) is known to fail in a Kripke model whose frame is a finite complete reflexive graph (see [CZ97, Proposition 3.32, Corollary 5.29]). Finally, if \( \Lambda \subseteq S5 \), then \( \Lambda \) holds in any Kripke model whose frame is a complete graph. It is easy to arrange independent families of switches in such Kripke models, just by ensuring that every possible pattern of switches is exhibited in some world. \( \square \)

In the \( S4 \) context, one can generalize Theorems 12 and 13 to the following, which we expect will be relevant for Question 36. Recall that a modal logic \( \Theta \) has the finite frame property if whenever \( \Theta \not\vDash \varphi \), then there is a finite \( \Theta \)-frame \( F \) and a Kripke model \( M \) with frame \( F \) in which \( \varphi \) fails. Such theories as \( S4, S4.2, S4.3 \) and \( S5 \) are known by [CZ97, 5.29, 5.32, 5.33] to have the finite frame property.

Theorem 14. Suppose that \( \Theta \) is a modal logic containing \( S4 \) and having the finite frame property, such as \( S4, S4.2, S4.3 \) or \( S5 \). If \( \Lambda \) contains \( S4 \) and is closed under substitution, then for any class \( \mathbb{F} \) of frames complete for \( \Theta \), the following are equivalent:

1. \( \Lambda \) is consistent with the Jankov-Fine formula \( \delta(F) \land p_{w_0} \) for any frame \( F \in \mathbb{F} \) and world \( w_0 \in F \).
2. Every frame in \( \mathbb{F} \) is a \( \Lambda \)-frame.
3. \( \Lambda \subseteq \Theta \).

Proof. If the Jankov-Fine formula \( \delta(F) \land p_{w_0} \) holds in a Kripke model \( (N,u_0) \models \Lambda \), then by Lemma 7.1 any Kripke model \( M \) with frame \( F \) has an assignment \( q_i \mapsto \psi_i \) such that \( (M,w_0) \models \varphi(q_0,\ldots,q_n) \) if and only if \( (N,u_0) \models \varphi(\psi_0,\ldots,\psi_n) \). In particular, if \( \varphi \) fails in such an \( M \), then the corresponding substitution instance of it will fail in \( N \models \Lambda \). So every such \( F \) is a \( \Lambda \)-frame, and we have proved (1) implies (2). For (2) implies (3), observe that if \( \varphi \) is not in \( \Theta \), then it fails in a Kripke model \( M \) having a finite frame \( F \in \mathbb{F} \). Since \( F \) is a \( \Lambda \)-frame, we know that \( M \models \Lambda \) and consequently \( \varphi \) is not in \( \Lambda \). So \( \Lambda \subseteq \Theta \). For (3) implies (1), observe that the Jankov-Fine formula \( \delta(F) \land p_{w_0} \) is easily satisfied at a Kripke model \( M \) having
frame $F$, where $p_w$ is true exactly at $w$. Since $F$ is a $\Theta$-frame, we know that $M \models \Theta$ and consequently $M \models \Lambda$ by (3), so (1) holds, and the proof is complete. 

We do not have a button-and-switch characterization of $S4$ in Theorem [13] because the frame of an $S4$ model need not be directed, and it is not true that every possibly necessary statement is necessarily possibly necessary. Under $S4$, one can have assertions $\varphi$ such that, simultaneously, $\varphi$ is possibly necessary, $\neg \varphi$ is possibly necessary, and $\varphi$ is possibly a switch. Thus, for the $S4$ context, we emphasize the official definition of button as a statement that is necessarily possibly necessary. Such examples show that unlike $S4.2$, under $S4$ it is no longer true that every statement is a button, the negation of a button or a switch.

4. Forcing over a fixed model of set theory

While our main theorem establishes that the ZFC-provable principles of forcing are exactly those in $S4.2$, it is not true that every model of set theory observes only these validities. For any $W \models ZFC$, recall that a modal assertion $\varphi$ is a valid principle of forcing in $W$ if for all sentences $\psi_i$ in the language of set theory we have $W \models \varphi(\psi_0, \ldots, \psi_n)$. For meta-mathematical reasons connected with Tarski’s theorem on the non-definability of truth, there is initially little reason to expect that the collection of such $\varphi$ should be definable in $W$; rather, the assertion that $\varphi$ is valid in $W$ is expressed as a scheme, asserting all substitution instances $\varphi(\psi_0, \ldots, \psi_n)$ in $W$. So this is formally a second-order notion. Because a statement is provable in ZFC exactly when it holds in all models of ZFC, our main theorem establishes that the modal assertions $\varphi$ that are valid in all models of set theory are exactly those in $S4.2$. Our proof, however, established the following stronger result.

**Theorem 15.** If $W$ is a model of set theory with arbitrarily large finite independent families of buttons and switches, then the valid principles of forcing in $W$ are exactly $S4.2$.

This result is stronger because it shows that the minimal set of forcing validities is realized in a single model of set theory (such as any model of $V = L$), rather than arising as the intersection of the validities of several models. Nevertheless, there are models of set theory whose valid principles of forcing go beyond $S4.2$. For example, the Maximality Principle MP of [Ham03] asserts all instances of the scheme $\Diamond \Box \psi \rightarrow \psi$, so that any set theoretic statement $\psi$ that holds in some forcing extension and all further extensions is already true. In other words, MP asserts that $S5$ is valid for forcing. Because it is established in [Ham03] that if ZFC is consistent, then so is ZFC + MP, we conclude:

**Theorem 16.** If ZFC is consistent, then it is consistent with ZFC that all $S5$ assertions are valid principles of forcing.

The forcing validities of a model, however, never go beyond $S5$.

**Theorem 17.** The valid principles of forcing in any model of set theory are included within $S5$.

**Proof.** Let $\Lambda$ be the set of forcing validities in a model $W$ of set theory. By Theorem 3 this includes all of $S4.2$. Also, $\Lambda$ is easily seen to be closed under substitution. Observe next that any model of set theory has an infinite independent family of switches, such as $s_n = \text{“the GCH holds at } \aleph_n \text{.”}$ These and their negations are
forceable in any finite pattern over any model of set theory by well known forcing arguments. It follows that \( \Lambda \) is consistent with the modal assertions that there are large independent families of switches. By Theorem 13, consequently, \( \Lambda \subseteq \mathbf{S5} \).

**Corollary 18.** If ZFC is consistent, then there is a model of set theory whose valid principles of forcing are exactly \( \mathbf{S5} \).

Our results establish that both \( \mathbf{S4.2} \) and \( \mathbf{S5} \) are realized as the exact set of forcing validities of a model of set theory (realized, respectively, in models of \( V = L \) or of MP).

**Question 19.** Which modal theories arise as the valid principles of forcing in a model of ZFC?

For example, can there be a model of set theory whose valid principles of forcing are exactly \( \mathbf{Dm.2} \) or exactly \( \mathbf{S4.3} \)? We have seen that if a model of set theory has sufficiently many independent buttons and switches, then the valid principles of forcing will be only \( \mathbf{S4.2} \). At the other extreme, if there are no buttons, then MP holds and so the valid principles of forcing in the model will be \( \mathbf{S5} \). Is it possible to have a model with a finite bound on the size of an independent family of buttons?

**Question 20.** Is there a model of ZFC with one unpushed button but not two independent buttons?

What are the valid principles of forcing in such models? It is clear that if there are only finitely many buttons in a model (meaning that the independent families of buttons have some bounded finite size), then we could use Lemmas 6.3 and 6.4 to simulate any Kripke model on a pre-lattice frame with a correspondingly bounded number of clusters. The various classes of such frames generate modal theories strictly between \( \mathbf{S4.2} \) and \( \mathbf{S5} \). Are these realizable as the forcing validities of models of set theory? Are these the only modal theories that arise? The next theorem is a start on these questions. Denote the collection of modal assertions \( \varphi \) that are valid in \( W \) by \( \text{Force}^W \). Two buttons \( b_0 \) and \( b_1 \) are *semi-independent* if both are unpushed and one can push \( b_0 \) without pushing \( b_1 \).

**Theorem 21.** Suppose that \( W \) is a model of ZFC set theory.

1. \( \mathbf{S4.2} \subseteq \text{Force}^W \subseteq \mathbf{S5} \).
2. If \( W \) has no unpushed buttons, then \( \text{Force}^W = \mathbf{S5} \).
3. If \( W \) has at least one unpushed button, then \( \text{Force}^W \subseteq \mathbf{S5} \).
4. If \( W \) has two semi-independent buttons, then \( \mathbf{W5} \) is not valid in \( W \), and so \( \mathbf{S4W5} \nsubseteq \text{Force}^W \).
5. If \( W \) has two independent buttons, then \( \mathbf{3} \) is not valid in \( W \), and so \( \mathbf{S4.3} \nsubseteq \text{Force}^W \).
6. If \( W \) has an independent family of one button and one switch, then \( \mathbf{Dm} \) is not valid in \( W \), and so \( \mathbf{Dm} \nsubseteq \text{Force}^W \).

**Proof.** Statement (1) is the content of Theorems 8 and 17. Over \( \mathbf{S4} \), the additional \( \mathbf{S5} \) axiom is equivalent to \( \diamond \Box \varphi \rightarrow \Box \varphi \), which exactly asserts that every button is pushed. So (2) and (3) hold. For (4), suppose that \( b_0, b_1 \) are semi-independent buttons in \( W \), and let \( \varphi = (\neg \Box b_0 \land \neg \Box b_1) \lor \Box (b_0 \land b_1) \), which asserts that either neither or both buttons are pushed. Thus, \( \varphi \) is both true and possibly necessary in \( W \), since the buttons are initially unpushed and we could push both, but \( \varphi \) is
not necessary, since we could push just \( b_0 \); this violates W5. For (5), suppose that \( W \) has two independent buttons \( b_1 \) and \( b_2 \). We argue as in Observation \([\text{I}]\). Let \( \varphi = \square b_1 \land \neg \square b_2 \) and \( \psi = \square b_2 \land \neg \square b_1 \). Since both buttons are unpushed in \( W \) and either may be pushed, we conclude that \( W \vDash \Diamond \varphi \land \Diamond \psi \). But in any forcing extension of \( W \), if \( \varphi \) is true, then \( \psi \) is impossible and vice versa. So this instance of the conclusion of .3 fails in \( W \). Thus, .3 is not valid in \( W \), and so \( \text{Force}^W \) does not include S4.3. For (6), suppose that \( W \) has an independent family of one button \( b \) and one switch \( s \). We follow the argument of Observation \([\text{I}]\) case Dm. We may assume that both \( \square b \) and \( s \) are false in \( W \). Let \( \varphi = \square b \lor s \). This is possibly necessary in \( W \), since one could push the button \( b \), but not true in \( W \), so \( \Diamond \square \varphi \rightarrow \varphi \) is false in \( W \). In any forcing extension of \( W \), if \( \Diamond (\varphi \rightarrow \square \varphi) \), then it must be that the button \( b \) has been pushed there, since otherwise one could make \( \varphi \) true and then false again by flipping the switch \( s \). So we have argued that \( (\square (\varphi \rightarrow \square \varphi)) \rightarrow \varphi \) holds in every forcing extension of \( W \). Thus, the hypothesis of this instance of Dm holds in \( W \), while the conclusion fails, so Dm is not valid in \( W \). This establishes (6). \( \square \)

Semi-independent buttons are part of the following more general arrangement. A list of assertions \( \varphi_1, \ldots, \varphi_n \) is a volume control if each is a button, pushing any of them necessarily also pushes all the previous, and any of them can be pushed without pushing the next. More precisely:

\[
\square \bigwedge_{i<n} (\square \varphi_{i+1} \rightarrow \square \varphi_i) \land (\Diamond \square \varphi_{i+1}) \land (\neg \square \varphi_{i+1} \rightarrow \Diamond (\neg \varphi_{i+1} \land \square \varphi_i)).
\]

The idea is that one can turn up the volume to level \( j \) by forcing \( \square \varphi_j \), but there is no turning it down again. The volume control has volume zero if \( \neg \square \varphi_1 \) (and so a volume control of length \( n \) has \( n+1 \) many volume settings). These volume controls exhibit the linear dependence of buttons, rather than independence. If buttons \( b_0 \) and \( b_1 \) are semi-independent, then \( \square b_0 \land \square (b_0 \land b_1) \) is a volume control of length 2; conversely, every volume control of length 2 at volume zero consists of two semi-independent buttons. Similar ideas with more buttons produce arbitrarily long volume controls. A Kripke model with a linear frame of \( n+1 \) clusters admits volume controls of length \( n \) but no independent buttons. A family of volume controls, buttons and switches is independent in a model if all the volume controls have zero volume in that model, all the buttons are unpushed in that model, and in any forcing extension, one can operate any of the volume controls, buttons and switches without affecting any of the others.

**Theorem 22.** If \( W \) is a model of set theory exhibiting arbitrarily long volume controls independent from arbitrarily large families of independent switches, then \( \text{Force}^W \subseteq S4.3 \).

**Proof.** We know by \([\text{CZ97}]\) 3.31, 3.32, 3.40, 5.33] that the finite linear pre-orders are a complete class of S4.3 frames. Suppose that \( F \) is such a finite linear pre-order and \( w_0 \) is a node in the minimal cluster of \( F \). Let \( v_1, \ldots, v_n \) be a volume control in \( W \), where \( n \) is the number of clusters of \( F \), and suppose that this volume control forms an independent family with the switches \( s_0, \ldots, s_m \), where the size of any cluster is at most \( 2^n \). As in Lemmas \([6.2] \) and \([6.3] \) we will assign to each node \( w \in F \) an assertion \( p_w \), so that \( W \) satisfies the Jankov-Fine formula \( \delta(F) \land p_{w_0} \). Specifically, within each cluster \( [u] \), assign to each node \( w \in [u] \) a nonempty set \( A_w \).
of subsets $A \subseteq n$ in such a way that these partition all subsets $A \subseteq n$, and define $\text{sw} = \bigvee_{A \in \vec{A}} s_A$, as in Lemma 6.3. In the least cluster, we assign the pattern $A$ of switches holding in $W$ to the node $w_0$. Now, for any node $w \in F$, if $w$ is in the $i$th cluster, then we define $p_w = v_i \wedge s_w$. That is, the volume control indicates the intended cluster and the switch indicates the intended node within that cluster. Since every forcing extension of $W$ exhibits some volume setting and some pattern of switches, it is clear that it will satisfy exactly one of the $p_w$, and in any extension of $W$ where $p_w$ holds, then $\Diamond p_w$ holds if and only if $w \leq v$. Thus, the Jankov-Fine formula $\delta(F) \wedge p_{w_0}$ is satisfied. It now follows by Theorem 14 that $F$ is a $\text{Force}^W$-frame. So every $\text{S}4.3$-frame is a $\text{Force}^W$-frame, and so $\text{Force}^W \subseteq \text{S}4.3$.

George Leibman has observed that a volume control of length $\omega^2$, with sufficiently uniform assertions, can be used to construct an independent family of one volume control of length $\omega$ and infinitely many switches, as follows. One divides the $\omega$ blocks into increasingly large finite blocks, with the position within these sub-blocks indicating the configuration of the switches, and the current $\omega$ block indicating the overall new volume of length $\omega$. Thus, it is sufficient in Theorem 22 to have merely a (sufficiently uniform) volume control of length $\omega^2$, or actually volume controls of length $\omega \cdot n$ for arbitrarily large $n$, without worrying about independent switches.

We close this section with a curious question. A modal theory is normal if it is closed under modus ponens, substitution and necessitation. All the named modal theories that we have considered, such as $\text{S}4$, $\text{S}4.2$, $\text{S}4.3$, $\text{Dm}.2$, $\text{S}5$ and so on, are normal. Meanwhile, the set of valid principles of forcing in any model of ZFC is easily seen to be closed under modus ponens and substitution. But is it closed under necessitation?

**Question 23.** If $\varphi$ is a valid principle of forcing, does it remain valid in all forcing extensions?

In other words, is $\Box \varphi$ also valid? Equivalently, if $W \models \text{ZFC}$, then is $\text{Force}^W$ normal? Of course, if $\text{Force}^W$ is necessarily $\text{S}4.2$ or $\text{S}5$, then the answer is yes, so this question is related to Questions 19 and 26.

5. **The modal logic of forcing with parameters**

We know from [Ham03] that parameters play a subtle role in the strength of the Maximality Principles. While MP is equiconsistent with ZFC, allowing real parameters in the scheme results in the principle MP($\mathbb{R}$), which has some large cardinal strength; allowing uncountable parameters leads to inconsistency. Allowing real parameters from all forcing extensions leads to a principle $\Box \text{MP}(\mathbb{R})$ with a large cardinal strength of at least infinitely many Woodin cardinals (but less than AD$_\mathbb{R}$ + $\Theta$ is regular). So let us analyze the role played by parameters in the valid principles of forcing. Specifically, define that $\varphi(q_0, \ldots, q_n)$ is a valid principle of forcing in a model $W$ with parameters in $X$ if for any set theoretical formulas $\psi_i(\vec{x})$ we have

$$W \models \forall \vec{x} \in X \varphi(\psi_0(\vec{x}), \ldots, \psi_n(\vec{x})).$$

We denote the collection of such $\varphi$ by $\text{Force}^W(X)$. The next theorem provides another answer to Question 2.
Theorem 24. In any model of set theory, the modal assertions $\varphi$ that are valid principles of forcing with all parameters are exactly those in $S_{4.2}$. Succinctly, $\text{Force}^W(W) = S_{4.2}$.

Proof. Certainly any $S_{4.2}$ assertion is a valid principle of forcing with any parameters, by the argument of Theorem 3, which did not depend on whether there were parameters or not. For the converse direction, we argue as in the Main Theorem, using the following fact, that with sufficient parameters one can always construct independent families of buttons and switches.

Lemma 24.1. If $W$ is any model of ZFC, then with parameters $\omega^W_n$ for $n \in \omega$, there is an infinite independent family of buttons and switches.

Proof. Let $b_n$ be the assertion “$\omega^W_{n+1}$ is not a cardinal” and for positive $m$, let $s_m$ be “the GCH holds at $\aleph_{n+m}$,” referring to $\aleph_{n+m}$ de dicto, rather than with a parameter. In any forcing extension of $W$, any of the buttons can be forced without affecting the truth of the other buttons, by collapsing $\omega^W_{n+1}$ to its predecessor (see [Jec03, 15.21]). After this, the switches $s_n$ and their negations can be forced in any desired pattern without adding bounded sets below $\aleph_{n}$ and, consequently, without affecting the buttons $b_n$ (see [Jec03, 15.18 and related]).

The result now follows from Theorem 15 and the observation that the existence of parameters can simply be carried through that argument. Specifically, if $\varphi$ is not in $S_{4.2}$, then it fails at some world $w_0$ in a Kripke model whose frame is a finite pre-lattice. As in the Main Theorem, we use the buttons and switches to define $p_w$ for each world $w$ in $M$ verifying the Jankov-Fine formula as in Lemma 6.3. If we define $\psi_i$ as in Lemma 6.4, then we observe as before that $(M,w_0) \models \varphi(q_0,\ldots,q_n)$ if and only if $W \models \varphi(\psi_0,\ldots,\psi_n)$. Since $\varphi$ fails at $w_0$ in $M$ and the $\psi_i$ are Boolean combinations of the buttons and switches, this produces a failing substitution instance of $\varphi$ in $W$ using the same parameters.

Theorem 25. For any $W \models \text{ZFC}$ and any sets $X \subseteq Y$ of parameters in $W$, then $S_{4.2} \subseteq \text{Force}^W(Y) \subseteq \text{Force}^W(X) \subseteq \text{Force}^W \subseteq S_5$.

Proof. Certainly any $S_{4.2}$ assertion is valid, even with parameters, so $S_{4.2} \subseteq \text{Force}^W(Y)$. If $X \subseteq Y$, then it is at least as hard for a modal assertion $\varphi$ to be valid for all substitution instances using parameters in $Y$ as for parameters in $X$, so $\text{Force}^W(Y) \subseteq \text{Force}^W(X)$. Finally, $\text{Force}^W = \text{Force}^W(\emptyset)$, which is contained in $S_5$ by Theorem 17.

Question 26. Can the set of forcing validities $\text{Force}^W(X)$ be strictly between $S_{4.2}$ and $S_5$? When is it equal to $S_{4.2}$ or to $S_5$?

For example, in the proof of Theorem 24, we only used parameters $\omega^W_n$, so we may conclude:

Corollary 27. For any model $W$ of set theory, $\text{Force}^W(\aleph_1^W) = S_{4.2}$. More specifically, $\text{Force}^W(\{\omega^W_n \mid n \in \omega \}) = S_{4.2}$.

Corollary 28. If a model $W$ of set theory is absolutely definable in all forcing extensions (by the same formula, without parameters), then $\text{Force}^W = S_{4.2}$. 
Proof. If \( W \) is absolutely definable, then the \( \omega_n^W \) are also absolutely definable, thereby avoiding in Theorem 24 the need for them to appear explicitly as parameters. \( \Box \)

An essentially identical argument shows, more generally, that if \( W \) is absolutely definable from parameters in \( X \), then \( \text{Force}^W(X) = \text{S4.2} \). In particular, no such \( W \) is a model of the Maximality Principle with parameters in \( X \). We now push the parameters a bit lower. Let \( H_{\omega_2} \) denote the collection of sets having hereditary size less than \( \omega_2 \).

**Theorem 29.** For any model \( W \) of set theory, \( \text{Force}^W(H_{\omega_2}) = \text{S4.2} \).

Proof. We will build an independent family of buttons and switches. In \( W \), let \( \omega_1 = \bigsqcup_n S_n \) be a partition of \( \omega_1 \) into infinitely many disjoint stationary subsets \( S_n \). Let \( b_n \) assert “\( S_n \) is not stationary”. Each assertion \( b_n \) is false in \( W \), since the \( S_n \) are stationary there, but in any forcing extension, by shooting a club through the complement of any \( S_n \), we can force \( b_n \) to be necessary, while preserving all stationary subsets of the complement of \( S_n \) (see [Jec03, 23.8, ex. 23.6]). Thus, in any forcing extension of \( W \), we can push button \( b_n \) without affecting any of the other buttons. (Note that this forcing collapses \( \omega_1 \) when \( S_n \) is the sole remaining stationary set on the list.) So the buttons \( b_n \) are independent in \( W \). For switches, let \( s_k \) assert that the GCH holds at \( \aleph_{k+2} \). By forcing over \( W \) or any extension we can arrange the switches in any finite pattern, without adding subsets to \( \omega_1^W \) and consequently without affecting the buttons. So \( W \) has an infinite independent family of buttons and switches using parameters in \( H_{\omega_2} \), and so by Theorem 15 we conclude \( \text{Force}^W(H_{\omega_2}^W) = \text{S4.2} \). \( \Box \)

This stationary set idea provides an alternative source of independent buttons for Lemma 6.1, because if \( V = L \), then one can use the \( L \)-least partition of \( \omega \) many stationary sets; one advantage here is that this provides arbitrarily large finite independent families of buttons that can be pushed without collapsing cardinals. Indeed, the button to collapse \( \omega_1^X \) is equivalent to the infinite conjunction of these independent buttons.

Returning to Question 26, we observe that if \( W \) is a model of \( V = L \) or if \( \text{Force}^W = \text{S4.2} \), then clearly all the classes line up on the left side with \( \text{Force}^W(X) = \text{S4.2} \). If \( W \models \text{MP} \), then \( \text{Force}^W = \text{S5} \) is on the right. If \( W \models \text{MP}(\mathbb{R}) \), then \( \text{Force}^W(\mathbb{R}) = \text{S5} \). If \( X \) has any uncountable parameter \( x \), then the assertion \( \psi = \text{“} x \text{ is countable} \text{“} \) is possibly necessary but not true in \( W \); consequently, \( \diamond \square \psi \rightarrow \psi \) fails in \( W \), and so \( \text{Force}^W(X) \neq \text{S5} \). More generally, if \( X \) has an element from which \( \omega_1^W \) is absolutely definable, then \( \text{Force}^W(X) \neq \text{S5} \). In fact, since CH is always a switch and independent from “\( \omega_1^W \) is countable,” we can conclude in this case that \( \text{Dm} \) is not valid, so \( \text{Dm} \not\subseteq \text{Force}^W(X) \). If the set of parameters supports long volume controls with independent switches, then \( \text{Force}^W(X) \subseteq \text{S4.3} \). If it supports many independent buttons and switches, then \( \text{Force}^W(X) = \text{S4.2} \). The situation \( \text{S4.2} \subseteq \text{Force}^W(X) \subseteq \text{S5} \) would occur if one could construct at least one button in \( W \) using parameters in \( X \), but not arbitrarily large finite independent families of buttons and switches.

The hypothesis \( \text{Force}^W(\mathbb{R}) = \text{S5} \) is equivalent to \( W \models \text{MP}(\mathbb{R}) \), which has large cardinal consistency strength. Specifically, [Ham03] shows it to be equiconsistent over ZFC with the existence of a stationary proper class of inaccessible cardinals. It
is natural to inquire about the strength of weaker hypotheses concerning Force\(^W\)(\(\mathbb{R}\)). For example, we prove next that \(Dm \subseteq \text{Force}^W(\mathbb{R})\) already has large cardinal strength. Define that \(\omega_1\) is \textit{inaccessible to reals} if \(\omega_1\) is an inaccessible cardinal in \(L[x]\) for every real \(x\) (equivalently, if \(\omega_1^{L[x]} < \omega_1\) for all \(x \in \mathbb{R}\)). The assertion that there is a stationary proper class of inaccessible cardinals is expressed as a scheme in ZFC, asserting that every class of ordinals (definable from parameters) that is closed and unbounded in the class of all ordinals contains an inaccessible cardinal.

**Theorem 30.** If \(Dm\) is valid for forcing with real parameters, then \(\omega_1\) is inaccessible to reals and every \(L[x]\) for \(x \in \mathbb{R}\) has a stationary proper class of inaccessible cardinals. Indeed, \(L_{\omega_1} \prec L\) and even \(L_{\omega_1}[x] \prec L[x]\).

**Proof.** We show \(L_{\omega_1} \prec L\) by verifying the Tarski-Vaught criterion. This claim should be understood metatheoretically and proved as a scheme. Suppose that \(L \models \exists u \exists v \varphi(u, v)\), where \(u \in L_{\omega_1}\). If there is no such \(v\) inside \(L_{\omega_1}\), then the assertion \(\varphi(u) = \text{there is } v \in L_{\omega_1}\) such that \(L \models \varphi(u, v)\)” is false in \(W\). But it is certainly forceably necessary, because we could make \(\varphi(u)\) true by collapsing cardinals until the least witness \(v\) in \(L\) is hereditarily countable. In other words, \(\varphi(u)\) is a button in \(W\). The parameter \(u\), being in \(L_{\omega_1}\), is hereditarily countable and can therefore be coded with a real. Meanwhile, the assertion CH is a switch, and this switch is independent of \(\varphi(u)\), because the CH and its negation can be forced over any model without collapsing \(\omega_1\) and therefore without affecting the truth of \(\varphi(u)\). Since we have an independent button and switch in \(W\) using a real parameter, it follows by Theorem 21 case (6), that \(Dm\) is not valid in \(W\) with real parameters, contrary to our assumption that \(Dm\) is valid for forcing over \(W\) with real parameters.

By relativizing to any real \(x\), we similarly conclude that \(L_{\omega_1}[x] \prec L[x]\), again proved as a scheme. It follows by elementary set theory that \(\omega_1\) is (strongly) inaccessible in \(L[x]\). Also, if \(C \subseteq \text{ORD}\) is a definable proper class club in \(L[x]\), defined from parameters in \(L_{\omega_1}[x]\), it follows that \(C \cap \omega_1\) is unbounded in \(\omega_1\), and consequently \(\omega_1 \in C\). Since \(L_{\omega_1}[x] \prec L[x]\), we conclude that every proper class club definable from parameters in \(L_{\omega_1}[x]\) contains an inaccessible cardinal. Thus, the inaccessible cardinals form a stationary proper class in \(L_{\omega_1}[x]\). By elementarity again, we conclude that the inaccessible cardinals form a stationary proper class in \(L[x]\), as desired. \(\square\)

**Corollary 31.** The following are equiconsistent over ZFC:

1. \(\text{ZFC + MP}(\mathbb{R})\).
2. \(\text{ZFC + S5 with real parameters is valid for forcing}\).
3. \(\text{ZFC + S4W5 with real parameters is valid for forcing}\).
4. \(\text{ZFC + Dm.2 with real parameters is valid for forcing}\).
5. \(\text{ZFC + Dm with real parameters is valid for forcing}\).
6. \(\text{ZFC + the inaccessible cardinals form a stationary proper class}\).

**Proof.** The Maximality Principle \(\text{MP}(\mathbb{R})\) asserts exactly that Axiom 5 is valid for forcing with real parameters, so (1) \(\iff\) (2). Clearly (2) \(\implies\) (3) \(\implies\) (4) \(\implies\) (5), since \(\text{S5} \supseteq \text{S4W5} \supseteq \text{Dm.2} \supseteq \text{Dm}\). In fact, (4) \(\iff\) (5), since the axiom .2 is always valid. Statement (5) implies, by Theorem 30 that (6) is true in \(L\). Finally, if there is a model where (6) holds, then results in [Ham03] produce a model satisfying \(\text{ZFC + MP}(\mathbb{R})\). \(\square\)
The assertions in Corollary 31 should be understood as schemes asserting the relevant substitution instances \( \forall \vec{x} \in \mathbb{R} \varphi(\psi_0(\vec{x}), \ldots, \psi_n(\vec{x})) \).

**Question 32.** Which modal theories arise as the valid principles of forcing with real parameters?

We know that \( S4.2 \subseteq \text{Force}^W(\mathbb{R}) \subseteq S5 \), and both of these endpoints can occur. But is there any model of set theory \( W \) giving rise to any intermediate modal theory?

6. Restricting to a class of forcing notions

One can naturally restrict the scope of forcing extensions to those obtained by the members of a particular class \( \Gamma \), so that \( \square_\Gamma \varphi \) means that \( \varphi \) holds in all forcing extensions by forcing in \( \Gamma \) and \( \diamond_\Gamma \varphi \) means that \( \varphi \) is forceable by some forcing in \( \Gamma \). Natural classes \( \Gamma \) would include ccc forcing, proper forcing, and so on. The analogue of the Main Question becomes:

**Question 33.** For a given class of forcing \( \Gamma \), what are the valid principles of \( \Gamma \)-forcing?

There are many open questions here, which we leave for future projects. Let us close the paper by observing that even with ccc forcing, the situation changes dramatically.

**Theorem 34.** If ZFC is consistent, then the ZFC-provable principles of ccc forcing do not include \( S4.2 \).

**Proof.** It is easy to deduce in \( S4.2 \) the following Directedness axiom:

\[
(\diamond \square \varphi \land \diamond \square \psi) \rightarrow \diamond \square (\varphi \land \psi).
\]

We will show that the ccc interpretation of this Directedness axiom is not valid in \( L \). This proof relies on the fact, a part of mathematical folklore, that there are two fundamentally different ways to destroy a Suslin tree by ccc forcing. If \( T \) is a Suslin tree, then of course forcing with \( T \) itself adds a branch through \( T \), making it non-Aronszajn. Alternatively, if \( T \) is Suslin, then there is ccc forcing making \( T \) into a special Aronszajn tree, a union of countably many antichains (see [Jec03, 16.19 and related]). No further forcing can add a branch through this tree without collapsing \( \omega_1 \), since the branch would have to contain at most one node from each antichain. Thus, these two alternatives cannot be amalgamated by ccc forcing. If \( \varphi \) is the assertion “the L-least Suslin tree is not Aronszajn” and \( \psi \) is the assertion “the L-least Suslin tree is special,” then each of these statements is possibly necessary by ccc forcing over \( L \), but their conjunction is false in all ccc extensions of \( L \). Thus, \( (\diamond_{\text{ccc}} \square_{\text{ccc}} \varphi) \land (\diamond_{\text{ccc}} \square_{\text{ccc}} \psi) \) holds in \( L \), but not \( \diamond_{\text{ccc}} \square_{\text{ccc}} (\varphi \land \psi) \), violating Directedness.

**Corollary 35.** The same conclusion holds for any class \( \Gamma \) of forcing notions containing all ccc forcing, whose members in any ccc extension preserve \( \omega_1 \). This includes the classes of proper forcing, semi-proper forcing, cardinal-preserving forcing, and so on.

**Proof.** In the proof of Theorem 34 the assertions \( \varphi \) and \( \psi \) are each ccc-forceable over \( L \) and once true, they are necessary by all forcing. Consequently, they are each \( \Gamma \)-forceably necessary in \( L \). The conjunction \( \varphi \land \psi \), however, is not forceable
by \( \omega_1 \)-preserving forcing over \( L \), and hence not \( \Gamma \)-forceable over \( L \). So the \( \Gamma \)-forcing validities in \( L \) do not include \( S4.2 \).

Nevertheless, one can easily verify that \( S4 \) remains valid for ccc forcing (and also for the other classes).

**Question 36.** What is the modal logic of ccc forcing? Does it go beyond \( S4 \)?

A complete set of \( S4 \) frames consists of finite pre-trees (partial pre-orders whose quotients are trees), and with them one might try to carry out a similar analysis as in our Main Theorem, by finding set theoretical assertions to fulfill the Jankov-Fine assertions. The point is that branching in these trees gives rise to behavior totally unlike either buttons or switches. Branching corresponds in set theory to the possibility of ccc forcing extensions that cannot be amalgamated by further ccc forcing, as in the folklore fact above, where one chooses either to specialize a Suslin tree of \( L \) or to make it not Aronszajn. What is needed, therefore, is an elaborate generalization of this folklore idea, in which one can successively make choices with ccc forcing that cannot later be amalgamated by ccc forcing, in such a way that every ccc forcing extension is included.

While Theorem 34 shows that the ZFC-provable ccc modal validities do not include all of \( S4.2 \), it is not currently clear conversely whether they are included within \( S4.2 \). To prove that they are, it would suffice to find a model of ZFC with arbitrarily large independent families of ccc buttons and switches.

Under Martin’s Axiom MA, of course, the product of ccc posets is again ccc, and this implies that the Directedness Axiom is valid for ccc forcing. But we seem unable to prove that this axiom is necessary under MA, since MA itself is easily destroyed by ccc forcing: adding even a single Cohen real creates Souslin trees. In the ccc analogue of Question 23 it is not clear whether the collection of the modal validities of ccc forcing is closed under necessitation. Thus, we seem unable to conclude that \( S4.2 \) is valid for ccc forcing over any model of MA.

**Question 37.** What are the ZFC + MA-provably valid principles of ccc forcing?

Lastly, we mention that for ccc forcing, unlike the general situation with Corollary 31, there is no large cardinal strength to the hypothesis that \( S5 \) is valid for ccc forcing with real parameters. Specifically, [Lei04] proves that if ZFC is consistent, then there is a model of ZFC in which every \( S5 \) assertion is valid for ccc forcing with real parameters. If one wants \( S5 \) to be valid for ccc forcing with parameters in \( H_{2^\omega} \), however, then [Ham03] shows that it is equiconsistent, as in Corollary 31 with a stationary proper class of inaccessible cardinals.

**References**


